

THE PRESSURE METRIC FOR CONVEX REPRESENTATIONS

MARTIN BRIDGEMAN, RICHARD CANARY, FRANÇOIS LABOURIE,
AND ANDRES SAMBARINO

ABSTRACT. Using the thermodynamics formalism, we introduce a notion of intersection for convex Anosov representations, show analyticity results for the intersection and the entropy, and rigidity results for the intersection. We use the renormalized intersection to produce a $\text{Out}(\Gamma)$ -invariant Riemannian metric on the smooth points of the deformation space of convex, irreducible representations of a word hyperbolic group Γ into $\text{SL}_m(\mathbb{R})$ whose Zariski closure contains a generic element. In particular, we produce mapping class group invariant Riemannian metrics on Hitchin components which restrict to the Weil–Petersson metric on the Fuchsian loci. Moreover, we produce $\text{Out}(\Gamma)$ -invariant metrics on deformation spaces of convex cocompact representations into $\text{PSL}_2(\mathbb{C})$ and show that the Hausdorff dimension of the limit set varies analytically over analytic families of convex cocompact representations into any rank 1 semi-simple Lie group.

1. INTRODUCTION

In this paper we produce a mapping class group invariant Riemannian metric on a Hitchin component of the character variety of reductive representations of a closed surface group into $\text{SL}_m(\mathbb{R})$ whose restriction to the Fuchsian locus is a multiple of the Weil–Petersson metric. More generally, we produce a $\text{Out}(\Gamma)$ -invariant Riemannian metric on the smooth points of the deformation space of convex, irreducible representations of a word hyperbolic group Γ into $\text{SL}_m(\mathbb{R})$ whose Zariski closure contains a generic element. We use Plücker representations to produce metrics on deformation spaces of convex cocompact representations into $\text{PSL}_2(\mathbb{C})$ and on the smooth points of deformation spaces

Canary was partially supported by NSF grant DMS - 1006298. Labourie and Sambarino were partially supported by the European Research Council under the *European Community's* seventh Framework Programme (FP7/2007-2013)/ERC grant agreement n° FP7-246918, as well as by the ANR program ETTT (ANR-09-BLAN-0116-01).

of Anosov, Zariski dense representations into an arbitrary semi-simple Lie groups.

Our metric is produced using the thermodynamic formalism developed by Bowen [12, 13], Parry–Pollicott [44], Ruelle [49] and others. It generalizes earlier work done in the Fuchsian and quasifuchsian cases by McMullen [42] and Bridgeman [9]. In order to utilize the thermodynamic formalism, we associate a natural flow $U_\rho\Gamma$ to any convex, Anosov representation ρ and show that it is topologically transitive metric Anosov and is a Hölder reparameterization of the geodesic flow $U_0\Gamma$ of Γ as defined by Gromov. We then see that entropy varies analytically over any smooth analytic family of convex, Anosov homomorphisms of Γ into $\mathrm{SL}_m(\mathbb{R})$. As a consequence, again using the Plücker embedding, we see that the Hausdorff dimension of the limit set varies analytically over analytic families of convex cocompact representations into a rank one semi-simple Lie group. We also introduce a renormalized intersection \mathbf{J} on the space of convex, Anosov representations. Our metric is given by the Hessian of this renormalised intersection \mathbf{J} .

We now introduce the notation necessary to give more careful statements of our results. Let Γ be a word hyperbolic group with Gromov boundary $\partial_\infty\Gamma$. A representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is said to be *convex* if there exist continuous ρ -equivariant maps $\xi : \partial_\infty\Gamma \rightarrow \mathbb{RP}(m)$ and $\theta : \partial_\infty\Gamma \rightarrow \mathbb{RP}(m)^*$ such that if x and y are distinct points in $\partial_\infty\Gamma$, then

$$\xi(x) \oplus \theta(y) = \mathbb{R}^m$$

(where we identify $\mathbb{RP}(m)^*$ with the Grassmanian of $(m-1)$ -dimensional vector subspaces of \mathbb{R}^m).

We shall specialize to *convex Anosov representation*, see section 2.1 for a careful definition. For a convex, Anosov representation, the image of every element is *proximal*, i.e. its action on $\mathbb{RP}(m)$ has an attracting fixed point. Loosely speaking a representation is convex Anosov if the proximality “spreads uniformly”. In particular, by Guichard–Wienhard [24, Proposition 4.10], every irreducible convex representation is convex Anosov.

If ρ is a convex Anosov representation, we can associate to every conjugacy class $[\gamma]$ in Γ its *spectral radius* $\Lambda(\gamma)(\rho)$. The collection of these radii form the *radius spectrum* of ρ . For every positive real number T we define

$$R_T(\rho) = \{[\gamma] \mid \log(\Lambda(\gamma)(\rho)) \leq T\}.$$

We will see that $R_T(\rho)$ is finite (Proposition 2.8). We also define the *entropy* of a representation by

$$h(\rho) = \lim_{T \rightarrow \infty} \frac{1}{T} \log \#(R_T(\rho)).$$

If ρ_0 and ρ_1 are two convex Anosov representations, we define their *intersection*

$$\mathbf{I}(\rho_0, \rho_1) = \lim_{T \rightarrow \infty} \left(\frac{1}{\#(R_T(\rho_0))} \sum_{[\gamma] \in R_T(\rho_0)} \frac{\log(\Lambda(\gamma)(\rho_1))}{\log(\Lambda(\gamma)(\rho_0))} \right).$$

We also define the *renormalised intersection* as

$$\mathbf{J}(\rho_0, \rho_1) = \frac{h_{\rho_1}}{h_{\rho_0}} \mathbf{I}(\rho_0, \rho_1).$$

We prove, see Theorem 1.3, that all these quantities are well defined and obtain the following inequality and rigidity result for the renormalised intersection. Let $\pi_m : \mathbf{SL}_m(\mathbb{R}) \rightarrow \mathbf{PSL}_m(\mathbb{R})$ be the projection map.

Theorem 1.1. [INTERSECTION] *If Γ is a word hyperbolic group and $\rho_1 : \Gamma \rightarrow \mathbf{SL}_{m_1}(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathbf{SL}_{m_2}(\mathbb{R})$ are convex Anosov representations, then*

$$\mathbf{J}(\rho_1, \rho_2) \geq 1.$$

Moreover, if $\mathbf{J}(\rho_1, \rho_2) = 1$ and the Zariski closures \mathbf{G}_1 and \mathbf{G}_2 of $\rho_1(\Gamma)$ and $\rho_2(\Gamma)$ are connected, irreducible and simple, then there exists a group isomorphism

$$g : \pi_{m_1}(\mathbf{G}_1) \rightarrow \pi_{m_2}(\mathbf{G}_2)$$

such that

$$\pi_{m_1} \circ \rho_1 = g \circ \pi_{m_2} \circ \rho_2.$$

We also establish a spectral rigidity result. If $\rho : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ is convex Anosov and $\gamma \in \Gamma$, then let $\mathbf{L}(\gamma)(\rho)$ denote the eigenvalue of maximal absolute value of $\rho(\gamma)$, so

$$\Lambda(\gamma)(\rho) = |\mathbf{L}(\gamma)(\rho)|.$$

Theorem 1.2. [SPECTRAL RIGIDITY] *Let Γ be a word hyperbolic group and let $\rho_1 : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ be convex Anosov representations with limit maps ξ_1 and ξ_2 such that*

$$\mathbf{L}(\gamma)(\rho_1) = \mathbf{L}(\gamma)(\rho_2)$$

for every γ in Γ . Then there exists $g \in \mathbf{GL}_m(\mathbb{R})$ such that $g\xi_1 = \xi_2$.

Moreover, if ρ_1 is irreducible, then $g\rho_1g^{-1} = \rho_2$.

We now introduce the deformation spaces which occur in our work. In section 4, we will see that each of these deformation spaces is a real analytic manifold. Let us introduce some terminology. Recall first that a representation is *reductive* if it can be written as a sum of irreducible representations. If \mathbf{G} is a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$, we say that an element of \mathbf{G} is *generic* if its centralizer is a maximal torus in \mathbf{G} . For example, an element of $\mathrm{SL}_m(\mathbb{R})$ is generic if and only if it is diagonalizable over \mathbb{C} with distinct eigenvalues. We say that a representation $\rho : \Gamma \rightarrow \mathbf{G}$ is *\mathbf{G} -generic* if the Zariski closure of $\rho(\Gamma)$ contains a generic element of \mathbf{G} . Finally, we say that $\rho \in \mathrm{Hom}(\Gamma, \mathbf{G})$ is *regular* if it is a smooth point of the algebraic variety $\mathrm{Hom}(\Gamma, \mathbf{G})$.

- Let $\mathcal{C}(\Gamma, m)$ denote the space of (conjugacy classes of) regular, irreducible, convex representations of Γ into $\mathrm{SL}_m(\mathbb{R})$.
- Let $\mathcal{C}_g(\Gamma, \mathbf{G}) \subset \mathcal{C}(\Gamma, m)$ denote the space of \mathbf{G} -generic, regular, irreducible, convex representations.

We show that the entropy and the renormalised intersection vary analytically over our deformation spaces. Moreover, we obtain analyticity on analytic families of convex Anosov homomorphisms. An analytic family of convex Anosov homomorphisms is a continuous map $\beta : M \rightarrow \mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$ such that M is an analytic manifold, $\beta_m = \beta(m)$ is convex Anosov for all $m \in M$, and $m \rightarrow \beta_m(\gamma)$ is an analytic map of M into $\mathrm{SL}_m(\mathbb{R})$ for all $\gamma \in \Gamma$.

Theorem 1.3. [ANALYTICITY] *If Γ is a word hyperbolic group, then the entropy h and the renormalised intersection \mathbf{J} are well-defined positive, $\mathrm{Out}(\Gamma)$ -invariant analytic functions on the spaces $\mathcal{C}(\Gamma, m)$ and $\mathcal{C}(\Gamma, m) \times \mathcal{C}(\Gamma, m)$ respectively. More generally, they are analytic functions on any analytic family of convex Anosov homomorphisms.*

Moreover, let $\gamma : (-1, 1) \rightarrow \mathcal{C}(\Gamma, m)$ be any analytic path with values in the deformation space, let $\mathbf{J}^\gamma(t) = \mathbf{J}(\gamma(0), \gamma(t))$ then

$$\left. \frac{d}{dt} \right|_{t=0} \mathbf{J}^\gamma = 0 \text{ and } \left. \frac{d^2}{dt^2} \right|_{t=0} \mathbf{J}^\gamma \geq 0. \quad (1)$$

Theorem 1.3 allows us to define a non-negative analytic 2-tensor on $\mathcal{C}_g(\Gamma, \mathbf{G})$. The pressure form is defined to be the Hessian of the restriction of the renormalised intersection \mathbf{J} . Our main result is the following.

Theorem 1.4. [PRESSURE METRIC] *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$. The pressure form is an analytic $\mathrm{Out}(\Gamma)$ -invariant Riemannian metric on $\mathcal{C}_g(\Gamma, \mathbf{G})$.*

If S is a closed, connected, orientable, hyperbolic surface, Hitchin [28] exhibited a component $\mathcal{H}_m(S)$ of $\mathrm{Hom}(\pi_1(S), \mathrm{PSL}_m(\mathbb{R})/\mathrm{PGL}_m(\mathbb{R}))$

now called the *Hitchin component*, which is an analytic manifold diffeomorphic to a ball. Each Hitchin component contains a Fuchsian locus which consists of representations obtained by composing Fuchsian representations of $\pi_1(S)$ into $\mathrm{PSL}_2(\mathbb{R})$ with the irreducible representation $\tau_m : \mathrm{PSL}_2(\mathbb{R}) \rightarrow \mathrm{PSL}_m(\mathbb{R})$. The representations in a Hitchin component are called *Hitchin representations* and can be lifted to representations into $\mathrm{SL}_m(\mathbb{R})$. Labourie [32] showed that lifts of Hitchin representations are convex, Anosov and $\mathrm{SL}_m(\mathbb{R})$ -generic. In particular, if $\rho_i : \pi_1(S) \rightarrow \mathrm{PSL}_m(\mathbb{R})$ are Hitchin representations, then one can define $h(\rho_i)$, $\mathbf{I}(\rho_1, \rho_2)$ and $\mathbf{J}(\rho_1, \rho_2)$ just as for convex Anosov representations.

Guichard has recently announced a classification of the possible Zariski closures of Hitchin representations, see Section 12.3 for a statement. As a corollary of Theorem 1.1 and Guichard's work we obtain a stronger rigidity result for Hitchin representations.

Corollary 1.5. [HITCHIN RIGIDITY] *Let S be a closed, orientable surface and let $\rho_1 \in \mathcal{H}_{m_1}(S)$ and $\rho_2 \in \mathcal{H}_{m_2}(S)$ be two Hitchin representations such that*

$$\mathbf{J}(\rho_1, \rho_2) = 1.$$

Then,

- *either $m_1 = m_2$ and $\rho_1 = \rho_2$ in $\mathcal{H}_{m_1}(S)$,*
- *or there exists an element ρ of the Teichmüller space $\mathcal{T}(S)$ so that $\rho_1 = \tau_{m_1}(\rho)$ and $\rho_2 = \tau_{m_2}(\rho)$.*

In section 12.4 we use work of Benoist [5, 6] to obtain a similar rigidity result for Benoist representations. We recall that Benoist representations arise as monodromies of strictly convex projective structures on compact manifolds with word hyperbolic fundamental group.

Each Hitchin component lifts to a component of $\mathcal{C}_g(\pi_1(S), m)$. As a corollary of Theorem 1.4 and work of Wolpert [56] we obtain:

Corollary 1.6. [HITCHIN COMPONENT] *The pressure form on the Hitchin component is an analytic Riemannian metric which is invariant under the mapping class group and restricts to the Weil-Petersson metric on the Fuchsian locus.*

Li [37] has used the work of Loftin [39] and Labourie [34] to exhibit a metric on $\mathcal{H}_3(S)$, which she calls the Loftin metric, which is invariant with respect to the mapping class group, restricts to a multiple of the Weil-Petersson metric on the Fuchsian locus and such that the Fuchsian locus is totally geodesic. She further shows that a metric on $\mathcal{H}_3(S)$ constructed earlier by Darvishzadeh and Goldman [21] restricts to a multiple of the Weil-Petersson metric on the Fuchsian locus.

If Γ is a word hyperbolic group, we let $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ denote the space of (conjugacy classes of) convex cocompact representations of Γ into $\mathrm{PSL}_2(\mathbb{C})$. In Section 3 we produce a representation, called the Plücker representation, $\alpha : \mathrm{PSL}_2(\mathbb{C}) \rightarrow \mathrm{SL}_m(\mathbb{R})$ (for some m), so that if $\rho \in \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$, then $\alpha \circ \rho$ is convex Anosov. The deformation space $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is an analytic manifold and we may define a renormalised intersection \mathbf{J} and thus a pressure form on $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$. The following corollary is a direct generalization of Bridgeman's pressure metric on quasifuchsian space (see [9]).

Corollary 1.7. [KLEINIAN GROUPS] *Let Γ be a torsion-free word hyperbolic group. The pressure form gives rise to a $\mathrm{Out}(\Gamma)$ -invariant metric on the analytic manifold $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ which is Riemannian on the open subset consisting of Zariski dense representations. Moreover,*

- (1) *If Γ does not have a finite index subgroup which is either a free group or a surface group, then the metric is Riemannian at all points in $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$.*
- (2) *If Γ is the fundamental group of a closed, connected, orientable surface, then the metric is Riemannian off of the Fuchsian locus in $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ and restricts to a multiple of the Weil-Petersson metric on the Fuchsian locus.*

If G is a rank one semi-simple Lie group, then work of Patterson [45], Sullivan [54], Yue [57] and Corlette-Iozzi [17] shows that the entropy of a convex cocompact representation $\rho : \Gamma \rightarrow G$ agrees with the Hausdorff dimension of the limit set of $\rho(\Gamma)$. We may then apply Theorem 1.3 and the Plücker representation to conclude that the Hausdorff dimension of the limit set varies analytically over analytic families of convex cocompact representations into rank one semi-simple Lie groups.

Corollary 1.8. [ANALYTICITY OF HAUSDORFF DIMENSION] *If Γ is a finitely generated group and G is a rank one semi-simple Lie group, then the Hausdorff dimension of the limit set varies analytically on any analytic family of convex cocompact representations of Γ into G . In particular, the Hausdorff dimension varies analytically over $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$*

One may further generalize our construction into the setting of virtually Zariski dense Anosov representations into an arbitrary semi-simple Lie group G . A representation $\rho : \Gamma \rightarrow G$ is *virtually Zariski dense* if the Zariski closure of $\rho(\Gamma)$ is a finite index subgroup of G . If Γ is a word hyperbolic group, G is a semi-simple Lie group with finite center and P is a non-degenerate parabolic subgroup, then we let $\mathcal{Z}(\Gamma; G, P)$ denote the space of (conjugacy classes of) regular virtually Zariski dense

(G, P) -Anosov representations of Γ into G . The space $\mathcal{Z}(\Gamma; G, P)$ is an analytic orbifold, see Proposition 4.3, and we can again use a Plücker representation to define a pressure metric on $\mathcal{Z}(\Gamma; G, P)$. If G is connected, then $\mathcal{Z}(\Gamma; G, P)$ is an analytic manifold.

Corollary 1.9. [ANOSOV REPRESENTATIONS] *Suppose that Γ is a word hyperbolic group, G is a semi simple Lie group with finite center and P is a non-degenerate parabolic subgroup of G . There exists an $\text{Out}(\Gamma)$ -invariant analytic Riemannian metric on the orbifold $\mathcal{Z}(\Gamma; G, P)$.*

A key tool in our proof is the introduction of a metric Anosov flow $U_\rho\Gamma$ associated to a convex Anosov representation ρ . This flow seems likely to be of independent interest. Let $\rho : \Gamma \rightarrow \text{SL}_m(\mathbb{R})$ be a convex Anosov representation with limit maps ξ and θ . Let F be the total space of the principal \mathbb{R} -bundle over $\mathbb{RP}(m) \times \mathbb{RP}(m)^*$ whose fiber at the point (x, y) is the space of metrics on the line $\xi(x)$. There is a natural \mathbb{R} -action on F which takes a metric u on x to the metric $e^{-t}u$. Let F_ρ be \mathbb{R} -principal bundle over

$$\partial_\infty\Gamma^{(2)} = \partial_\infty\Gamma \times \partial_\infty\Gamma \setminus \{(x, x) \mid x \in \partial_\infty\Gamma\}.$$

which is the pull back of F by (ξ, θ) . The \mathbb{R} -action on F gives rise to a flow on F_ρ . We now relate all this data to the *Gromov geodesic flow* $U_0\Gamma$ of Γ introduced and discussed in [22, 15, 43] and prove a hyperbolicity property for the corresponding flow.

Theorem 1.10. [GEODESIC FLOW] *The action of Γ on F_ρ is proper and cocompact. Moreover, the \mathbb{R} action on $U_\rho\Gamma = F_\rho/\Gamma$ is a topologically transitive metric Anosov flow which is Hölder orbit equivalent to the geodesic flow $U_0\Gamma$.*

Theorem 1.10 allows us to make use of the thermodynamic formalism. We show that if f_ρ is the Hölder function regulating the change of speed of $U_\rho\Gamma$ and $U_0\Gamma$, then $\Phi_\rho = -h(\rho)f_\rho$ is a pressure zero function on $U_0\Gamma$. Therefore, we get a mapping

$$\mathfrak{T} : \mathcal{C}(\Gamma, m) \rightarrow \mathcal{H}(U_0\Gamma),$$

called the *thermodynamic mapping*, from $\mathcal{C}(\Gamma, m)$ into the space $\mathcal{H}(U_0\Gamma)$ of Livšic cohomology classes of pressure zero Hölder functions on $U_0\Gamma$. Given any $[\rho] \in \mathcal{C}(\Gamma, m)$, there exists an open neighborhood U of $[\rho]$ and a lift of $\mathfrak{T}|_U$ to an analytic map of U into the space $\mathcal{P}(U_0\Gamma)$ of pressure zero Hölder functions on $U_0\Gamma$. Our pressure form is obtained as a pullback of the pressure 2-tensor on $\mathcal{P}(U_0\Gamma)$ with respect to this lift.

Remarks and references: Convex representations were introduced by Sambarino in his thesis [50] and are a natural generalization of the hyperconvex representations studied by Labourie [32]. Labourie [32] and Guichard [23] showed that a representation of a closed surface group into $\mathrm{SL}_m(\mathbb{R})$ is hyperconvex if and only if it lies in the Hitchin component. Anosov representations were introduced by Labourie [32] and studied extensively by Guichard and Wienhard [24].

Pollicott and Sharp [46] applied the thermodynamic formalism and work of Dreyer [20] to show that a closely related entropy gives rise to an analytic function on any Hitchin component. Sambarino [52] also studied continuity properties of several related entropies.

McMullen [42] gave a pressure metric formulation of the Weil–Petersson metric on Teichmüller space, building on work of Bridgeman and Taylor [10]. Bridgeman [9] developed a pressure metric on quasifuchsian space which restricts to the Weil–Petersson metric on the Fuchsian locus. Our Theorem 1.4 is a natural generalization of Bridgeman’s work into the setting of convex, Anosov representations, while Corollary 1.7 is a generalization into the setting of general deformation spaces of convex cocompact representations into $\mathrm{PSL}_2(\mathbb{C})$.

Corollary 1.8 was established by Ruelle [48] for quasifuchsian representations, *i.e.* when $\Gamma = \pi_1(S)$ and $G = \mathrm{PSL}_2(\mathbb{C})$, and by Anderson and Rocha [2] for function groups, *i.e.* when Γ is a free product of surface groups and free groups and $G = \mathrm{PSL}_2(\mathbb{C})$. Previous work of Tapie [55] implies that the Hausdorff dimension of the limit set is a C^1 function on $\mathcal{C}_c(\Gamma, G)$.

Coornaert–Papadoapoulos [16] showed that if Γ is word hyperbolic, then there is a symbolic coding of its geodesic flow $U_0\Gamma$. However, this coding is not necessarily one-to-one on a large enough set to apply the thermodynamic formalism. Therefore, word hyperbolic groups admitting a convex Anosov representations represent an interesting class of groups from the point of view of symbolic dynamics.

The geodesic flow (Theorem 1.10) of an irreducible convex representation was first studied by Sambarino [51] for $\Gamma = \pi_1(M)$ where M is closed and negatively curved.

Acknowledgements: We thank Bill Goldman, Alex Lubotzky, François Ledrappier, Olivier Guichard, Frédéric Paulin, Hans-Henrik Rugh, Ralf Spatzier and Amie Wilkinson for helpful discussions. This research was begun while the authors were participating in the program on *Geometry and Analysis of Surface Group Representations* held at the Institut Henri Poincaré in Winter 2012. The first two authors thank the GEAR

network for providing partial support during their attendance of this program.

CONTENTS

1. Introduction	1
2. Convex and Anosov representations	10
2.1. Convex Anosov representations	10
2.2. Convex irreducible representations	14
2.3. Anosov representations	16
2.4. G -generic representations	17
3. Plücker representations	18
4. Deformation spaces of convex representations	21
4.1. Convex irreducible representations	21
4.2. Virtually Zariski dense representations	23
4.3. Kleinian groups	26
4.4. Hitchin components	26
5. The geodesic flow of a convex representation	27
6. The geodesic flow is a metric Anosov flow	31
6.1. Metric Anosov flows	31
6.2. The geodesic flow as a metric space	33
6.3. Stable and unstable leaves	35
6.4. The leaf lift and the distance	36
6.5. The geodesic flow is Anosov	37
7. Thermodynamics formalism	40
7.1. Hölder flows on compact spaces	40
7.2. Metric Anosov flows	42
7.3. Entropy and pressure for Anosov flows	43
7.4. Intersection and renormalised intersection	44
7.5. Variation of the pressure and the pressure metric	45
7.6. Analyticity of entropy, pressure and intersection	47
8. Analytic variation of the dynamics	48
8.1. Transverse regularity	50
8.2. Analytic variation of the limit maps	57
8.3. Analytic variation of the reparameterization	59
9. Thermodynamic formalism on the deformation space of convex Anosov representations	64
9.1. Analyticity of entropy and intersection	64
9.2. The thermodynamic mapping and the pressure form	66
10. Degenerate vectors for the pressure metric	68
10.1. Trace functions	68
10.2. Technical lemmas	71

10.3. Degenerate vectors have log-type zero	75
11. Variation of length and cohomology classes	76
11.1. Invariance of the cross-ratio	77
11.2. An useful immersion	79
11.3. Vectors with log type zero	80
12. Rigidity results	82
12.1. Spectral rigidity	83
12.2. Renormalized intersection rigidity	85
12.3. Rigidity for Hitchin representations	87
12.4. Convex projective structures	89
13. Proofs of main results	90
14. Appendix	93
References	93

2. CONVEX AND ANOSOV REPRESENTATIONS

In this section we recall the definition of convex representations, due to Sambarino [51], and explain their relationship with Anosov representations, which were introduced by Labourie [32] and further developed by Guichard-Wienhard [24]

2.1. Convex Anosov representations. We begin by defining convex Anosov representations and developing their basic properties.

Definition 2.1. *Let Γ be a word hyperbolic group and ρ be a representation of Γ in $\mathrm{SL}_m(\mathbb{R})$. We say ρ is convex if there exist ρ -equivariant continuous maps $\xi : \partial_\infty \Gamma \rightarrow \mathbb{RP}(m)$ and $\theta : \partial_\infty \Gamma \rightarrow \mathbb{RP}(m)^*$ such that if $x \neq y$, then*

$$\xi(x) \oplus \theta(y) = \mathbb{R}^m.$$

Convention: We will constantly identify $\mathbb{RP}(m)^*$ with the Grassmannian $\mathrm{Gr}_{m-1}(\mathbb{R}^m)$ of $(m-1)$ -dimensional subspaces of \mathbb{R}^m , via $\varphi \mapsto \ker \varphi$. The action of $\mathrm{SL}_m(\mathbb{R})$ on $\mathbb{RP}(m)^*$ consistent with this identification is

$$g \cdot \varphi = \varphi \circ g^{-1}.$$

We will also assume throughout this paper that our word hyperbolic group does not have a finite index cyclic subgroup. Since all the word hyperbolic groups we study are linear, Selberg's Lemma implies that they contain finite index torsion-free subgroups.

A convex representation is convex Anosov if the flat bundle over its Gromov geodesic flow has a contraction property we will define carefully

below. We first recall basic properties of the geodesic flow and discuss a splitting of the flat bundle associated to a convex representation.

Gromov [22] defined a geodesic flow $U_0\Gamma$ for a word hyperbolic group – that we shall call the *Gromov geodesic flow* – (see Champetier [15] and Mineyev [43] for details). He defines a proper cocompact action of Γ on $\partial_\infty\Gamma^{(2)} \times \mathbb{R}$ which commutes with the action of \mathbb{R} by translation on the final factor. The action of Γ restricted to $\partial_\infty\Gamma^{(2)}$ is the diagonal action arising from the standard action of Γ on $\partial_\infty\Gamma$. There is a metric on $\partial_\infty\Gamma^{(2)} \times \mathbb{R}$, well-defined up to Hölder equivalence, so that Γ acts by isometries, every orbit of the \mathbb{R} action gives a quasi-isometric embedding and the geodesic flow acts by Lipschitz homeomorphisms. The flow on

$$\widetilde{U_0\Gamma} = \partial_\infty\Gamma^{(2)} \times \mathbb{R}$$

descends to a flow on the quotient

$$U_0\Gamma = \partial_\infty\Gamma^{(2)} \times \mathbb{R}/\Gamma.$$

In the case that M is a closed negatively curved manifold and $\Gamma = \pi_1(M)$, $U_0\Gamma$ may be identified with T^1M in such a way that the flow on $U_0\Gamma$ is identified with the geodesic flow on T^1M . Since the action of Γ on $\partial_\infty\Gamma^2$ is topologically transitive, the Gromov geodesic flow is topologically transitive.

If ρ is a convex representation, let E_ρ be the associated flat bundle over the geodesic flow of the word hyperbolic group $U_0\Gamma$. Recall that

$$E_\rho = \widetilde{U_0\Gamma} \times \mathbb{R}^m / \Gamma$$

where the action of $\gamma \in \Gamma$ on \mathbb{R}^m is given by $\rho(\gamma)$. The limit maps ξ and θ induce a splitting of E_ρ as

$$E_\rho = \Xi \oplus \Theta$$

where Ξ and Θ are sub-bundles, parallel along the geodesic flow, of rank 1 and $m - 1$ respectively. Explicitly, if we lift Ξ and Θ to sub-bundles $\tilde{\Xi}$ and $\tilde{\Theta}$ of the bundle $\widetilde{U_0\Gamma} \times \mathbb{R}^m$ over $\widetilde{U_0\Gamma}$, then the fiber of $\tilde{\Xi}$ above (x, y, t) is simply $\xi(x)$ and the fiber of $\tilde{\Theta}$ is $\theta(y)$.

The \mathbb{R} -action on $\widetilde{U_0\Gamma}$ extends to a flow $\{\tilde{\psi}_t\}_{t \in \mathbb{R}}$ on $\widetilde{U_0\Gamma} \times \mathbb{R}^m$ (which acts trivially on the \mathbb{R}^m factor). The flow $\{\tilde{\psi}_t\}_{t \in \mathbb{R}}$ descends to a flow $\{\psi_t\}_{t \in \mathbb{R}}$ on E_ρ which is a lift of the geodesic flow on $U_0\Gamma$. In particular, the flow respects the splitting $E_\rho = \Xi \oplus \Theta$.

In general, we say that a vector bundle E over a compact topological space whose total space is equipped with a flow $\{\phi_t\}_{t \in \mathbb{R}}$ of bundle automorphisms is *contracted* by the flow if for any metric $\|\cdot\|$ on E , there

exists $t_0 > 0$ such that if $v \in E$, then

$$\|\phi_{t_0}(v)\| \leq \frac{1}{2}\|v\|.$$

Observe that if bundle is contracted by a flow, its dual is contracted by the inverse flow. Moreover, if the flow is contracting, it is also *uniformly contracting*, i.e. given any metric, there exists positive constants A and c such that

$$\|\phi_t(v)\| \leq Ae^{-ct}\|v\|$$

for any $v \in E$.

Definition 2.2. A convex representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is Anosov if the bundle $\mathrm{Hom}(\Theta, \Xi)$ is contracted by the flow $\{\psi_t\}_{t \in \mathbb{R}}$.

In the sequel, we will use the notation $\Theta^* = \mathrm{Hom}(\Theta, \mathbb{R})$. The following alternative description will be useful.

Proposition 2.3. A convex representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ with limit maps ξ and θ is convex Anosov if and only if there exists $t_0 > 0$ such that for all $Z \in \mathcal{U}_0\Gamma$, $v \in \Xi_Z \setminus \{0\}$ and $w \in \Theta_Z \setminus \{0\}$,

$$\frac{\|\psi_{t_0}(v)\|}{\|\psi_{t_0}(w)\|} \leq \frac{1}{2} \frac{\|v\|}{\|w\|}. \quad (2)$$

Proof. Given a convex Anosov representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ and a metric $\|\cdot\|$ on E_ρ , let t_0 be chosen so that

$$\|\psi_{t_0}(\eta)\| \leq \frac{1}{2}\|\eta\|.$$

for all $\eta \in \Xi \otimes \Theta^*$. If $Z \in \mathcal{U}_0\Gamma$, $v \in \Xi_Z \setminus \{0\}$ and $w \in \Theta_Z \setminus \{0\}$, then there exists $\eta \in \mathrm{Hom}(\Theta_Z, \Xi_Z) = (\Xi \otimes \Theta^*)_Z$ such that $\eta(w) = v$ and $\|\eta\| = \|v\|/\|w\|$. Then,

$$\frac{\|\psi_{t_0}(v)\|}{\|\psi_{t_0}(w)\|} \leq \|\psi_{t_0}(\eta)\| \leq \frac{1}{2}\|\eta\| = \frac{\|v\|}{\|w\|}.$$

The converse is immediate. \square

Furthermore, convex Anosov representations are contracting on Ξ .

Lemma 2.4. If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is convex Anosov, then $\{\psi_t\}_{t \in \mathbb{R}}$ is contracting on Ξ .

Proof. Since the bundle $\Xi \otimes \Theta^*$ is contracted, so is

$$\Omega = \det(\Xi \otimes \Theta^*) = \Xi \otimes \det(\Theta^*).$$

One may define an isomorphism from Ξ to $\det(\Theta)^*$ by taking u to the map $\alpha \rightarrow \mathrm{Vol}(u \wedge \alpha)$. Since $\det(\Theta)^*$ is isomorphic to $\det(\Theta^*)$, it follows that Ω is isomorphic to $\Xi^{\otimes 2}$. Thus Ξ is contracted. \square

It follows from standard techniques in hyperbolic dynamics that our limit maps are Hölder. We will give a proof of a more general statement in Section 8 (see [32, Proposition 3.2] for a proof in a special case).

Lemma 2.5. *Let ρ be a convex Anosov representation, then the limit maps ξ and θ are Hölder.*

If γ is an infinite order element of Γ , then there is a periodic orbit of $U_0\Gamma$ associated to γ : if γ^+ is the attracting fixed point of γ on $\partial_\infty\Gamma$ and γ^- is its other fixed point, then this periodic orbit is the image of $(\gamma^+, \gamma^-) \times \mathbb{R}$. Inequality (2) and Lemma 2.4 applied to the periodic orbit of $U_0\Gamma$ associated to γ imply that $\rho(\gamma)$ is proximal and that $\xi(\gamma^+)$ is the eigenspace associated to the largest modulus eigenvalue of $\rho(\gamma)$.

Let $L(\gamma)(\rho)$ denote the eigenvalue of $\rho(\gamma)$ of maximal absolute value and let $\Lambda(\gamma)(\rho)$ denote the spectral radius of $\rho(\gamma)$, so $\Lambda(\gamma)(\rho) = |L(\gamma)(\rho)|$. If S is a fixed generating set for Γ and $\gamma \in \Gamma$, then we let $l(\gamma)$ denote the translation length of the action of γ on the Cayley graph of Γ with respect to S ; more explicitly, $l(\gamma)$ is the minimal word length of any element conjugate to γ . Since the contraction is uniform and the length of the periodic orbit of $U_0\Gamma$ associated to γ is comparable to $l(\gamma)$, we obtain the following uniform estimates:

Proposition 2.6. *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex, Anosov representation, then there exists $\delta \in (0, 1)$ such that if $\gamma \in \Gamma$ has infinite order, then $L(\gamma)(\rho)$ and $(L(\gamma^{-1})(\rho))^{-1}$ are both eigenvalues of $\rho(\gamma)$ of multiplicity one and*

$$\rho(\gamma) = L(\gamma)(\rho)p_\gamma + m_\gamma + \frac{1}{L(\gamma^{-1})(\rho)}q_\gamma$$

where

- p_γ is the projection on $\xi(\gamma^+)$ parallel to $\theta(\gamma^-)$,
- $q_\gamma = p_{\gamma^{-1}}$,
- $m_\gamma = A \circ (1 - q_\gamma - p_\gamma)$ and A is an endomorphism of $\theta(\gamma^-) \cap \theta(\gamma^+)$ whose spectral radius is less than

$$\delta^{\ell(\gamma)}\Lambda(\gamma)(\rho).$$

Moreover, we see that ρ is well-displacing in the following sense:

Proposition 2.7. [DISPLACING PROPERTY] *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex Anosov representation, then there exists constants $K > 0$ and $C > 0$, and a neighborhood U of ρ_0 in $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$ such that that for every $\gamma \in \Gamma$ and $\rho \in U$ we have*

$$\frac{1}{K}\ell(\gamma) - C \leq \log(\Lambda(\gamma)(\rho)) \leq K\ell(\gamma) + C, \quad (3)$$

Proposition 2.7 immediately implies:

Proposition 2.8. *For every real number T , the set*

$$R_T(\rho) = \{[\gamma] \mid \log(\Lambda(\gamma)(\rho)) \leq T\}$$

is finite.

Remark: Proposition 2.6 is a generalization of results of Labourie [32, Proposition 3.4], Sambarino [51, Lemma 5.1] and Guichard-Wienhard [24, Lemma 3.1]. Proposition 2.7 is a generalization of a result of Labourie [35, Theorem 1.0.1] and a special case of a result of Guichard-Wienhard [24, Theorem 5.14]. See [19] for a discussion of well-displacing representations and their relationship with quasi-isometric embeddings.

2.2. Convex irreducible representations. Guichard and Wienhard [24, Proposition 4.10] proved that irreducible convex representations are convex Anosov (see also [32] for hyperconvex representations).

Proposition 2.9. [GUICHARD–WIENHARD] *If Γ is a word hyperbolic group, then every irreducible convex representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is convex Anosov.*

It will be useful to note that if $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is convex and irreducible, then $\xi(\partial_\infty \Gamma)$ contains a projective frame for $\mathbb{RP}(m)$. We recall that a collection of $m + 1$ elements in $\mathbb{RP}(m)$ is a *projective frame* if every subset containing m elements spans \mathbb{R}^m . We first prove the following lemma.

Lemma 2.10. *Let $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ be a representation with a continuous equivariant map $\xi : \partial_\infty \Gamma \rightarrow \mathbb{RP}(m)$, then the preimage $\xi^{-1}(V)$ of a vector subspace $V \subset \mathbb{R}^m$ is either $\partial_\infty \Gamma$ or has empty interior on $\partial_\infty \Gamma$.*

Proof. Choose $\{x_1, \dots, x_p\} \subset \partial_\infty \Gamma$ so that $\{\xi(x_1), \dots, \xi(x_p)\}$ spans the vector subspace $\langle \xi(\partial_\infty \Gamma) \rangle$ spanned by $\xi(\partial_\infty \Gamma)$.

Suppose that $\xi^{-1}(V) = \{x \in \partial_\infty \Gamma : \xi(x) \in V\}$ has non-empty interior in $\partial_\infty \Gamma$. Choose $\gamma \in \Gamma$ so that $\gamma^- \notin \{x_1, \dots, x_p\}$ and γ^+ belongs to the interior of $\xi^{-1}(V)$.

Since $\gamma^n(x_i) \rightarrow \gamma^+$ for every $i \in \{1, \dots, p\}$, if we choose n large enough, then $\gamma^n(x_i)$ is contained in the interior of $\xi^{-1}(V)$, so $\xi(\gamma^n x_i) \in V$. Since $\{\xi(\gamma^n(x_1)), \dots, \xi(\gamma^n(x_p))\}$ still spans $\langle \xi(\partial_\infty \Gamma) \rangle$, we see that $\langle \xi(\partial_\infty \Gamma) \rangle \subset V$, in which case $\xi^{-1}(V) = \partial_\infty \Gamma$. \square

The following generalization of the fact that every convex, irreducible representation admits a projective frame will be useful in Section 12.

Lemma 2.11. *Let $\rho_1 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ be convex Anosov representations with limit maps ξ_1 and ξ_2 such that $\dim \langle \xi_1(\partial_\infty \Gamma) \rangle = \dim \langle \xi_2(\partial_\infty \Gamma) \rangle = p$. Then there exist $p + 1$ distinct points $\{x_0, \dots, x_p\}$ in $\partial_\infty \Gamma$ such that*

$$\{\xi_1(x_0), \dots, \xi_1(x_p)\} \text{ and } \{\xi_2(x_0), \dots, \xi_2(x_p)\}$$

are projective frames of $\langle \xi_1(\partial_\infty \Gamma) \rangle$ and $\langle \xi_2(\partial_\infty \Gamma) \rangle$ respectively.

Proof. We first proceed by iteration to produce $\{x_1, \dots, x_p\}$ so that $\{\xi_1(x_1), \dots, \xi_1(x_p)\}$ and $\{\xi_2(x_1), \dots, \xi_2(x_p)\}$ generate

$$V = \langle \xi_1(\partial_\infty \Gamma) \rangle \text{ and } W = \langle \xi_2(\partial_\infty \Gamma) \rangle.$$

Assume we have found $\{x_1, \dots, x_k\}$ so that $\{\xi_1(x_1), \dots, \xi_1(x_k)\}$ and $\{\xi_2(x_1), \dots, \xi_2(x_k)\}$ are both linearly independent. Define

$$V_k = \langle \{\xi_1(x_1), \dots, \xi_1(x_k)\} \rangle \text{ and } W_k = \langle \{\xi_2(x_1), \dots, \xi_2(x_k)\} \rangle.$$

By the previous lemma, if $k < p$, then $\xi_1^{-1}(V_k)$ and $\xi_2^{-1}(W_k)$ have empty interior, so their complements must intersect. Pick

$$x_{k+1} \in \xi_1^{-1}(V_k)^c \cap \xi_2^{-1}(W_k)^c.$$

This process is complete when $k = p$.

It remains to find x_0 . For each $i = 1, \dots, p$, let

$$U_i^1 = \langle \{\xi_1(x_1), \dots, \xi_1(x_p)\} \setminus \{\xi_1(x_i)\} \rangle$$

and

$$U_i^2 = \langle \{\xi_2(x_1), \dots, \xi_2(x_p)\} \setminus \{\xi_2(x_i)\} \rangle.$$

Then, choose

$$x_0 \in \bigcap_i \xi_1^{-1}(U_i^1)^c \cap \xi_2^{-1}(U_i^2)^c.$$

One easily sees that $\{x_0, \dots, x_p\}$ has the claimed properties. \square

If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is convex and irreducible, then $\langle \xi(\partial_\infty \Gamma) \rangle = \mathbb{R}^m$ (since $\langle \xi(\partial_\infty \Gamma) \rangle$ is $\rho(\Gamma)$ -invariant), so Lemma 2.11 immediately gives:

Lemma 2.12. *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex irreducible representation with limit maps ξ and θ , then there exist $\{x_0, \dots, x_m\} \subset \partial_\infty \Gamma$ so that $\{\xi(x_0), \dots, \xi(x_m)\}$ is a projective frame for $\mathbb{RP}(m)$.*

2.3. Anosov representations. In this section, we recall the general definition of an Anosov representation and note that convex Anosov and Hitchin representations are examples of Anosov representations.

We first recall some notation and definitions. Let G be a semi-simple Lie group with finite center and Lie algebra \mathfrak{g} . Let A be a Cartan subgroup of G and let \mathfrak{a} be the Cartan subalgebra of \mathfrak{g} .

For $a \in \mathfrak{a}$, let M be the connected component of the centralizer of a which contains the identity, and let \mathfrak{m} denote its Lie algebra. Let E_λ be the eigenspace of the action of a on \mathfrak{g} with eigenvalue λ and consider

$$\begin{aligned} \mathfrak{n}^+ &= \bigoplus_{\lambda > 0} E_\lambda, \\ \mathfrak{n}^- &= \bigoplus_{\lambda < 0} E_\lambda, \end{aligned}$$

so that

$$\mathfrak{g} = \mathfrak{m} \oplus \mathfrak{n}^+ \oplus \mathfrak{n}^-, \quad (4)$$

Then \mathfrak{n}^+ and \mathfrak{n}^- are Lie algebras normalized by M . Let P^\pm the connected Lie subgroups of G whose Lie algebras are $\mathfrak{p}^\pm = \mathfrak{m} \oplus \mathfrak{n}^\pm$. We may identify a point $([X], [Y])$ in $G/P^+ \times G/P^-$ with the pair of *opposite parabolic* subgroups $(\text{Ad}(X)P^+, \text{Ad}(Y)P^-)$. We will say that P^+ is *non-degenerate* if \mathfrak{p}^+ does not contain a simple factor of \mathfrak{g} .

The pair $(\text{Ad}(X)P^+, \text{Ad}(Y)P^-)$ is *transverse* if their intersection $\text{Ad}(X)P^+ \cap \text{Ad}(Y)P^-$ is conjugate to M .

We now suppose that $\rho : \Gamma \rightarrow G$ is a representation of word hyperbolic group Γ and $\xi^+ : \partial_\infty \Gamma \rightarrow G/P^+$ and $\xi^- : \Gamma \rightarrow G/P^-$ are ρ -equivariant maps. We say that ξ^+ and ξ^- are *transverse* if given any two distinct points $x, y \in \partial_\infty \Gamma$, $\xi^+(x)$ and $\xi^-(y)$ are transverse. The G -invariant splitting described by Equation (4) then gives rise to bundles over $U_0 \Gamma$. Let $\tilde{\mathcal{N}}_\rho^+$ and $\tilde{\mathcal{N}}_\rho^-$ be the bundles over $\widetilde{U_0 \Gamma}$ whose fibers over the point (x, y, t) are

$$\text{Ad}(\xi^-(y))\mathfrak{n}^+ \quad \text{and} \quad \text{Ad}(\xi^+(x))\mathfrak{n}^-.$$

There is a natural action of Γ on $\tilde{\mathcal{N}}_\rho^+$ and $\tilde{\mathcal{N}}_\rho^-$, where the action on the fiber is given by $\rho(\Gamma)$, and we denote the quotient bundles over $U_0 \Gamma$ by \mathcal{N}_ρ^+ and \mathcal{N}_ρ^- . We may lift the geodesic flow to a flow on the bundles \mathcal{N}_ρ^+ and \mathcal{N}_ρ^- which acts trivially on the fibers.

Definition 2.13. *Suppose that G is a semi-simple Lie group with finite center, P^+ is a parabolic subgroup of G and Γ is a word hyperbolic group. A representation $\rho : \Gamma \rightarrow G$ is (G, P^+) -Anosov if there exist transverse*

ρ -equivariant maps

$$\xi^+ : \partial_\infty \Gamma \rightarrow \mathbf{G}/\mathbf{P}^+ \text{ and } \xi^- : \partial_\infty \Gamma \rightarrow \mathbf{G}/\mathbf{P}^-$$

so that the geodesic flow is contracting on the associated bundle \mathcal{N}_ρ^- and the inverse flow is contracting on the bundle \mathcal{N}_ρ^+ .

We now recall some basic properties of Anosov representations which were established by Labourie, [32, Proposition 3.4] and [35, Theorem 6.1.3], and Guichard-Wienhard [24, Theorem 5.3 and Lemma 3.1]. We recall that an element $g \in \mathbf{G}$ is *proximal* relative to \mathbf{P}^+ if g has fixed points $x^+ \in \mathbf{G}/\mathbf{P}^+$ and $x^- \in \mathbf{G}/\mathbf{P}^-$ so that x^+ is transverse to x^- and if $x \in \mathbf{G}/\mathbf{P}^+$ is transverse to x^- then $\lim_{n \rightarrow \infty} g^n(x) = x^+$.

Theorem 2.14. *Let \mathbf{G} be a semi-simple Lie group, \mathbf{P}^+ a parabolic subgroup, Γ a word hyperbolic group and $\rho : \Gamma \rightarrow \mathbf{G}$ a $(\mathbf{G}, \mathbf{P}^+)$ -Anosov representation.*

- (1) ρ has finite kernel, so Γ is virtually torsion-free.
- (2) ρ is well-displacing, so $\rho(\Gamma)$ is discrete.
- (3) If $\gamma \in \Gamma$ has infinite order, then $\rho(\gamma)$ is proximal relative to \mathbf{P}^+

In this parlance, convex Anosov representations are exactly the same as $(\mathbf{SL}_m(\mathbb{R}), \mathbf{P}^+)$ -Anosov representations where \mathbf{P}^+ is the stabilizer of a line in \mathbb{R}^m .

Proposition 2.15. *Let \mathbf{P}^+ be the stabilizer of a line in \mathbb{R}^n . A representation $\rho : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ is convex Anosov if and only if it is $(\mathbf{SL}_m(\mathbb{R}), \mathbf{P}^+)$ -Anosov. Moreover, the limit maps ξ and θ in the definition of convex Anosov representation agree with the limit maps ξ^+ and ξ^- in the definition of a $(\mathbf{SL}_m(\mathbb{R}), \mathbf{P}^+)$ -Anosov representation.*

Proof. First suppose that ρ is convex Anosov with limit maps ξ and θ . One may identify $\mathbf{SL}_m(\mathbb{R})/\mathbf{P}^+$ with $\mathbb{RP}(m)$ and $\mathbf{SL}_m(\mathbb{R})/\mathbf{P}^-$ with $\mathbb{RP}(m)^*$ so that, after letting $\xi^+ = \xi$ and $\xi^- = \theta$, \mathcal{N}_ρ^+ is identified with $\Xi \otimes \Theta^*$ and \mathcal{N}_ρ^- is identified with $\Xi^* \otimes \Theta$. By definition, the geodesic flow is contracting on $\Xi \otimes \Theta^*$. Inequality (2) quickly implies that the inverse flow is contracting on $\Xi^* \otimes \Theta$. Therefore, ρ is $(\mathbf{SL}_m(\mathbb{R}), \mathbf{P}^+)$ -Anosov.

Conversely, if ρ is $(\mathbf{SL}_m(\mathbb{R}), \mathbf{P}^+)$ -Anosov with associated limit maps ξ^+ and ξ^- , then we let $\xi = \xi^+$ and $\theta = \xi^-$, and the fact that the geodesic flow is contracting on \mathcal{N}_ρ^+ is equivalent to the geodesic flow being contracting on $\Xi \otimes \Theta^*$. Therefore, ρ is convex Anosov. \square

2.4. G-generic representations. Let \mathbf{G} be a reductive subgroup of $\mathbf{SL}_m(\mathbb{R})$. We recall that an element in \mathbf{G} is *generic* if its centralizer is a maximal torus in \mathbf{G} . We say that a representation $\rho : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ of Γ

is \mathbf{G} -generic if $\rho(\Gamma) \subset \mathbf{G}$ and the Zariski closure $\overline{\rho(\Gamma)}^Z$ of $\rho(\Gamma)$ contains a \mathbf{G} -generic element.

We will need the following observation.

Lemma 2.16. *If \mathbf{G} is a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$ and $\rho : \Gamma \rightarrow \mathbf{G}$ is a \mathbf{G} -generic representation, then there exists $\gamma \in \Gamma$ such that $\rho(\gamma)$ is a generic element of \mathbf{G} .*

Proof. We first note that the set of non-generic elements of \mathbf{G} is Zariski closed in \mathbf{G} , so the set of generic elements is Zariski open in \mathbf{G} . Therefore, if the Zariski closure of $\rho(\Gamma)$ contains generic elements of \mathbf{G} , then $\rho(\Gamma)$ must itself contain generic elements of \mathbf{G} . \square

3. PLÜCKER REPRESENTATIONS

In this section we show how to obtain a convex Anosov representation from any Anosov representation. We shall make crucial use of the following result of Guichard–Weinhard [24, Proposition 4.3]:

Theorem 3.1. *Let $\phi : \mathbf{G} \rightarrow \mathrm{SL}(V)$ be a finite dimensional irreducible representation. Let $x \in \mathbb{P}(V)$ and assume that*

$$\mathbf{P} = \{g \in \mathbf{G} : \phi(g)(x) = x\}$$

is a parabolic subgroup of \mathbf{G} with opposite parabolic \mathbf{Q} . If Γ is a word hyperbolic group, then a representation $\rho : \Gamma \rightarrow \mathbf{G}$ is (\mathbf{G}, \mathbf{P}) -Anosov if and only if $\phi \circ \rho$ is convex Anosov.

Furthermore, if ρ is (\mathbf{G}, \mathbf{P}) -Anosov with limit maps ξ^+ and ξ^- , then the limit maps of $\phi \circ \rho$ are given by $\xi = \beta \circ \xi^+$ and $\theta = \beta^ \circ \xi^-$ where $\beta : \mathbf{G}/\mathbf{P} \rightarrow \mathbb{P}(V)$ and $\beta^* : \mathbf{G}/\mathbf{Q} \rightarrow \mathbb{P}(V^*)$ are the maps induced by ϕ .*

We are interested in the following corollary.

Corollary 3.2. *For any parabolic subgroup \mathbf{P} of a semi-simple Lie group \mathbf{G} with finite center, there exists a finite dimensional irreducible representation $\alpha : \mathbf{G} \rightarrow \mathrm{SL}(V)$ such that if Γ is a word hyperbolic group and $\rho : \Gamma \rightarrow \mathbf{G}$ is a (\mathbf{G}, \mathbf{P}) -Anosov representation, then $\alpha \circ \rho$ is convex Anosov.*

Moreover, if \mathbf{P} is non-degenerate, then $\ker(\alpha) = Z(\mathbf{G})$ and α is an immersion.

The representation given by the corollary will be called the *Plücker representation* of \mathbf{G} with respect to \mathbf{P} .

Proof. In view of Theorem 3.1 it suffices to find a finite dimensional irreducible representation $\alpha : \mathbf{G} \rightarrow \mathrm{SL}(V)$ such that $\alpha(\mathbf{P})$ is the stabilizer (in $\alpha(\mathbf{G})$) of a line in V .

This is standard in representation theory, but we include the proof for completeness (see also Remark 4.12 in Guichard-Wienhard [24]). We continue the notation of Section 2.3. Let $\Lambda^k W$ denote the k -th exterior power of the vector space W .

Let $n = \dim \mathfrak{n}^+ = \dim \mathfrak{n}^-$ and consider $\alpha : \mathbf{G} \rightarrow \mathrm{SL}(\Lambda^n \mathfrak{g})$ given by

$$\alpha(g) = \Lambda^n \mathrm{Ad}(g).$$

Notice that $\Lambda^n \mathfrak{n}^+$ is a line in $\Lambda^n \mathfrak{g}$. One may easily check that

$$\mathbf{P} = \{g \in \mathbf{G} : \alpha(g)(\Lambda^n \mathfrak{n}^+) = \Lambda^n \mathfrak{n}^+\}.$$

Let V be the subspace of $\Lambda^n \mathfrak{g}$ generated by the \mathbf{G} -orbit of $\Lambda^n \mathfrak{n}^+$, i.e.

$$V = \langle \mathbf{G} \cdot \Lambda^n \mathfrak{n}^+ \rangle.$$

The subspace V is preserved by $\alpha(\mathbf{G})$, so it remains to show that the restriction $\alpha|_V : \mathbf{G} \rightarrow \mathrm{SL}(V)$ is irreducible.

Let $\beta : \mathbf{G}/\mathbf{P} \rightarrow \mathbb{P}(V)$ be the map induced by α . Suppose that W is a $\alpha(\mathbf{G})$ -invariant subspace of V . Fix a norm $\|\cdot\|$ for V and choose a finite basis $\{v_1, \dots, v_d\}$ for W so that each v_i lies in $\beta(x_i)$ for some $x_i \in \mathbf{G}/\mathbf{P}$. We can choose $g \in \mathbf{G}$ so that g is proximal relative to \mathbf{P} and g^- is transverse to x_i for all $i = 1, \dots, d$. Given $w \in W$ we may write it as

$$w = a_1 v_1 + \dots + a_d v_d.$$

If $x \in \mathbf{G}/\mathbf{P}$ is transverse to g^- , then $g^n x \rightarrow g^+$. Thus, any possible limit of the sequence in W given by

$$\frac{\alpha(g)^n(w)}{\|\alpha(g)^n(w)\|} = \frac{a_1 \alpha(g)^n(v_1) + \dots + a_d \alpha(g)^n(v_d)}{\|\alpha(g)^n(w)\|}$$

lies in the line $\beta(g^+)$. Therefore, $\beta(g^+)$ lies in W and, since W is $\alpha(\mathbf{G})$ -invariant, so does its \mathbf{G} -orbit, i.e.

$$\beta(\mathbf{G} \cdot g^+) = \beta(\mathbf{G}/\mathbf{P}) \subset W.$$

It follows that $W = V$, so $\alpha|_V$ is irreducible.

If \mathbf{P} is non-degenerate, then $\ker(\alpha|_V)$ is a normal subgroup of \mathbf{G} which is contained in \mathbf{P} , so $\ker(\alpha|_V)$ is contained in $Z(\mathbf{G})$ (see [47]). Since $Z(\mathbf{G})$ is in the kernel of the adjoint representation, we see that $\ker(\alpha|_V) = Z(\mathbf{G})$. Since $\alpha|_V$ is algebraic and $Z(\mathbf{G})$ is finite, it follows that $\alpha|_V$ is an immersion. \square

If \mathbf{G} has rank one, then it contains a unique conjugacy class of parabolic subgroups. A representation $\rho : \Gamma \rightarrow \mathbf{G}$ is Anosov if and only if it is convex cocompact (see [24, Theorem 5.15]). We then get the following.

Corollary 3.3. *Let \mathbf{G} be a rank one semi-simple Lie group, let Γ be a word hyperbolic group, and let $\alpha : \mathbf{G} \rightarrow \mathrm{SL}(V)$ be the Plücker representation. If $\rho : \Gamma \rightarrow \mathbf{G}$ is convex cocompact, then $\alpha \circ \rho$ is convex Anosov. Moreover, there exists $K > 0$ such that for any γ in Γ ,*

$$\log(\Lambda(\alpha(\rho(\gamma)))) = Kd(\rho(\gamma))$$

where $d(\rho(\gamma))$ is the translation length of the action of $\rho(g)$ on the symmetric space of \mathbf{G} .

Corollary 3.3 follows immediately from Corollary 3.2 and the following observation.

Lemma 3.4. *Let \mathbf{G} be a rank one semi-simple Lie group and let $\alpha : \mathbf{G} \rightarrow \mathrm{SL}(V)$ be the Plücker representation. Then there exists $K > 0$ so that if $g \in \mathbf{G}$ is hyperbolic, then*

$$\log(\Lambda(\alpha(g))) = Kd(g).$$

Proof. Let \mathbf{A} be a Cartan subgroup of \mathbf{G} and let a be a generator of the Lie algebra of \mathbf{A} . Let

$$K = \frac{\log(\Lambda(\alpha(e^a)))}{d(e^a)},$$

First, observe that if $h = e^{ta}$ is an arbitrary element of \mathbf{A} , then

$$\frac{\log(\Lambda(\alpha(h)))}{d(h)} = \frac{t \log(\Lambda(\alpha(e^a)))}{td(a)} = \frac{\log(\Lambda(\alpha(e^a)))}{d(e^a)} = K.$$

Let g be a hyperbolic element in \mathbf{G} . Then we can write

$$g = u(he)u^{-1},$$

where $h \in \mathbf{A}$ and e is an elliptic element commuting with h . Observe then that

$$\begin{aligned} \log(\Lambda(\alpha(g))) &= \log(\Lambda(\alpha(he))) = \log(\Lambda(\alpha(h))) \\ &= Kd(h) = Kd(he) = Kd(g). \end{aligned}$$

which completes the proof. \square

We recall that the topological entropy of a convex cocompact representation $\rho : \Gamma \rightarrow \mathbf{G}$ of a word hyperbolic group into a rank one semi-simple Lie group is given by

$$h(\rho) = \lim_{T \rightarrow \infty} \frac{1}{T} \log(\#\{[\gamma] \mid d(\rho(\gamma)) \leq T\}).$$

We obtain the following immediate corollary.

Corollary 3.5. *Let \mathbf{G} be a rank one semi-simple Lie group, let Γ be a word hyperbolic group and let $\alpha : \mathbf{G} \rightarrow \mathrm{SL}(V)$ be the Plücker representation. There exists $K > 0$, such that if $\rho : \Gamma \rightarrow \mathbf{G}$ is convex cocompact, then $\alpha \circ \rho$ is convex Anosov and*

$$h(\alpha \circ \rho) = \frac{h(\rho)}{K}.$$

4. DEFORMATION SPACES OF CONVEX REPRESENTATIONS

In this section, we collect a few facts about the structure of deformation spaces of convex, Anosov representations of Γ into $\mathrm{SL}_m(\mathbb{R})$ and their relatives. Recall that a word hyperbolic group is finitely presented. Thus, if \mathbf{G} is a reductive Lie group, $\mathrm{Hom}(\Gamma, \mathbf{G})$ has the structure of an algebraic variety.

4.1. Convex irreducible representations. We first observe that our deformation spaces $\mathcal{C}(\Gamma, m)$ and $\mathcal{C}_g(\Gamma, \mathbf{G})$ are real analytic manifolds. Let

$$\tilde{\mathcal{C}}(\Gamma, m) \subset \mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$$

denote the set of regular, convex, irreducible representations. If \mathbf{G} is a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$, then we similarly let

$$\tilde{\mathcal{C}}_g(\Gamma, \mathbf{G}) \subset \mathrm{Hom}(\Gamma, \mathbf{G})$$

denote the space of \mathbf{G} -generic, regular, convex irreducible representations.

Proposition 4.1. *Suppose that Γ is a word hyperbolic group. Then*

- (1) *The deformation spaces $\mathcal{C}(\Gamma, m)$ and $\mathcal{C}_g(\Gamma, \mathrm{SL}_m(\mathbb{R}))$ have the structure of a real analytic manifold compatible with the algebraic structure on $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$*
- (2) *If \mathbf{G} is a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$, then $\mathcal{C}_g(\Gamma, \mathbf{G})$ has the structure of a real analytic manifold compatible with the algebraic structure on $\mathrm{Hom}(\Gamma, \mathbf{G})$.*

Proof. We may regard $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$ as a subset of $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{C}))$. We first notice that an irreducible homomorphism in $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$ is also irreducible when regarded as a homomorphism in $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{C}))$. Lubotzky and Magid ([40, Proposition 1.21 and Theorem 1.28]) proved that the set of irreducible homomorphisms form an open subset of $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{C}))$, so they also form an open subset of $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$. Results of Labourie [32, Prop. 2.1] and Guichard-Wienhard [24, Theorem 5.13] imply that the set of convex Anosov homomorphisms is an open subset of $\mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$ (see also Proposition 8.1). Therefore,

$\tilde{\mathcal{C}}(\Gamma, m)$ is an open subset of $\text{Hom}(\Gamma, \text{SL}_m(\mathbb{R}))$. Since the former consists of regular homomorphisms, it is an analytic manifold.

Lubotzky–Magid ([40, Theorem 1.27]) also proved that $\text{SL}_m(\mathbb{C})$ acts properly (by conjugation) on the set of irreducible representations in $\text{Hom}(\Gamma, \text{SL}_m(\mathbb{C}))$. It follows that $\text{SL}_m(\mathbb{R})$ acts properly on $\tilde{\mathcal{C}}(\Gamma, m)$. Schur’s Lemma guarantees that the centralizer of an irreducible representation is contained in the center of $\text{SL}_m(\mathbb{R})$. Therefore, $\text{PSL}_m(\mathbb{R})$ acts freely, analytically and properly on the analytic manifold $\tilde{\mathcal{C}}(\Gamma, m)$, so its quotient $\mathcal{C}(\Gamma, m)$ is also an analytic manifold.

Since the set of \mathbf{G} -generic elements of \mathbf{G} is an open \mathbf{G} -invariant subset of \mathbf{G} , we may argue exactly as above to show that $\tilde{\mathcal{C}}_g(\Gamma, \mathbf{G})$ is an open subset of $\text{Hom}(\Gamma, \mathbf{G})$ which is an analytic manifold. The action of $\mathbf{G}/Z(\mathbf{G})$ on $\tilde{\mathcal{C}}_g(\Gamma, \mathbf{G})$ is again free, analytic and proper, so its quotient $\mathcal{C}_g(\Gamma, \mathbf{G})$ is again an analytic manifold. \square

If $\rho \in \tilde{\mathcal{C}}(\Gamma, m)$, then one may identify $T_\rho \tilde{\mathcal{C}}(\Gamma, m)$ with the space $Z_\rho^1(\Gamma, \mathfrak{sl}_m(\mathbb{R}))$ of cocycles and one may then identify $T_{[\rho]} \mathcal{C}(\Gamma, m)$ with the cohomology group $H_\rho^1(\Gamma, \mathfrak{sl}_m(\mathbb{R}))$ (see [40, 29]). In particular, the space $B_\rho^1(\Gamma, \mathfrak{sl}_m(\mathbb{R}))$ is identified with the tangent space of the $\text{SL}_m(\mathbb{R})$ -orbit of ρ . Similarly, if $\rho \in \tilde{\mathcal{C}}_g(\Gamma, \mathbf{G})$, we identify $T_\rho \tilde{\mathcal{C}}_g(\Gamma, \mathbf{G})$ with $Z^1(\Gamma, \mathfrak{g})$ and $T_{[\rho]} \mathcal{C}_g(\Gamma, \mathbf{G})$ with $H_\rho^1(\Gamma, \mathfrak{g})$. More generally, if ρ is an irreducible representation in $\text{Hom}(\Gamma, \mathbf{G})$, the tangent vector to any analytic path through ρ may be identified with an element of $Z_\rho^1(\Gamma, \mathfrak{g})$ (see [29, Section 2]).

A simple calculation in cohomology gives that convex irreducible representations of fundamental groups of 3-manifolds with non-empty boundary are regular.

Proposition 4.2. *If Γ is isomorphic to the fundamental group of a compact orientable three manifold M with non empty boundary, then $\mathcal{C}(\Gamma, m)$ is the set of conjugacy classes of convex irreducible representations.*

Proof. Let $\Gamma = \pi_1(M)$ where M is a compact orientable 3-manifold with non-empty boundary. It suffices to show that the open subset of $\text{Hom}(\Gamma, \text{SL}_m(\mathbb{R}))$ consisting of convex, irreducible homomorphisms consists entirely of regular points. We recall that $\rho_0 \in \text{Hom}(\Gamma, \text{SL}_m(\mathbb{R}))$ is regular if there exists a neighborhood U of ρ_0 so that $\dim(Z_\rho^1(M, \mathfrak{g}))$ is constant on U and the centralizer of any representation $\rho \in U$ is trivial [40].

If ρ_0 is convex and irreducible, we can take U to be any open neighborhood of ρ_0 consisting of convex irreducible representations. Since

$\rho \in U$ is irreducible, Schur's Lemma guarantees that the centralizer of $\rho(\Gamma)$ is the center of $\mathrm{SL}_m(\mathbb{R})$. Moreover, if $\rho \in U$, then

$$\dim(H_\rho^0(M, \mathfrak{g})) - \dim(H_\rho^1(M, \mathfrak{g})) + \dim(H_\rho^2(M, \mathfrak{g})) = \chi(M) \dim(\mathbf{G}).$$

Since the centralizer is trivial, $\dim(H_\rho^0(M, \mathfrak{g})) = 0$. By Poincaré duality, $\dim(H_\rho^2(M, \mathfrak{g})) = \dim(H_\rho^0(M, \partial M, \mathfrak{g}))$. Since $\dim(H_\rho^0(M, \mathfrak{g})) = 0$, the long exact sequence for relative homology implies that $\dim(H_\rho^0(M, \partial M, \mathfrak{g})) = 0$. Thus,

$$\dim(H_\rho^1(M, \mathfrak{g})) = -\chi(M) \dim(\mathbf{G}).$$

Therefore, $\dim(Z_\rho^1(M, \mathfrak{g})) = (1 - \chi(M)) \dim(\mathbf{G})$ for all $\rho \in U$, so ρ is a regular point. \square

4.2. Virtually Zariski dense representations. We also need an analogous result for deformation spaces of virtually Zariski dense Anosov representations.

Proposition 4.3. *Suppose that Γ is a word hyperbolic group, \mathbf{G} is a semi-simple Lie group with finite center and \mathbf{P} is a non-degenerate parabolic subgroup of \mathbf{G} . Then $\mathcal{Z}(\Gamma; \mathbf{G}, \mathbf{P})$ is a real analytic orbifold.*

Moreover, if \mathbf{G} is connected, then $\mathcal{Z}(\Gamma; \mathbf{G}, \mathbf{P})$ is a real analytic manifold.

Proof. Let $\mathrm{Hom}^*(\Gamma, \mathbf{G})$ be the set of regular homomorphisms. By definition, $\mathrm{Hom}^*(\Gamma, \mathbf{G})$ is an open subset of $\mathrm{Hom}(\Gamma, \mathbf{G})$ and hence it is an analytic manifold, since it is the set of smooth points of a real algebraic manifold. Results of Labourie [32, Prop. 2.1] and Guichard-Wienhard [24, Theorem 5.13] again imply that the set of (\mathbf{G}, \mathbf{P}) -Anosov homomorphisms is open in $\mathrm{Hom}^*(\Gamma, \mathbf{G})$. The main difficulty in the proof is to show that the set $\tilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$ of virtually Zariski dense Anosov homomorphisms is open in $\mathrm{Hom}^*(\Gamma, \mathbf{G})$ and hence an analytic manifold.

Once we have shown that $\tilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$ is an analytic manifold, we may complete the proof in the same spirit as the proof of Proposition 4.1. We observe that if $\rho \in \tilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$ then its centralizer is finite, since the Zariski closure of $\rho(\Gamma)$ has finite index in \mathbf{G} . Then, $\mathbf{G}/Z(\mathbf{G})$ acts properly and analytically on $\tilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$ with finite point stabilizers, so the quotient $\mathcal{Z}(\Gamma; \mathbf{G}, \mathbf{P})$ is an analytic orbifold. If \mathbf{G}^0 is the connected component of \mathbf{G} , then the Zariski closure of any representation $\rho \in \tilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$ contains \mathbf{G}^0 , so the intersection of the centralizer of ρ with \mathbf{G}^0 is simply $Z(\mathbf{G}) \cap \mathbf{G}^0$. Therefore, $\tilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})/\mathbf{G}^0$ is an analytic manifold. In particular, if \mathbf{G} is connected, $\mathcal{Z}(\Gamma; \mathbf{G}, \mathbf{P})$ is an analytic manifold.

We complete the proof by showing that the set of virtually Zariski dense (\mathbf{G}, \mathbf{P}) -Anosov homomorphisms is open in $\mathrm{Hom}^*(\Gamma, \mathbf{G})$. If not,

then there exists a sequence $\{\rho_m\}_{m \in \mathbb{N}}$ of (G, P) -Anosov representations which are not virtually Zariski dense converging to a virtually Zariski dense (G, P) -Anosov representation ρ_0 .

Since G has finitely many components, $\rho_n^{-1}(G^0)$ has bounded finite index for all n . Since Γ is finitely generated, it contains only finitely many subgroups of a given index, so we may pass to a finite index subgroup Γ_0 of Γ so that $\rho_n(\Gamma_0)$ is contained in the identity component G^0 of G for all n . Since each $\rho_n|_{\Gamma_0}$ is (G, P) -Anosov and $\rho_0(\Gamma_0)$ is also virtually Zariski dense, we may assume for the remainder of the proof that G is the Zariski closure of G^0 .

Let Z_n be the Zariski closure of $\text{Im}(\rho_n)$ and let \mathfrak{z}_n be the Lie algebra of Z_n . Consider the decomposition of the Lie algebra \mathfrak{g} of G

$$\mathfrak{g} = \bigoplus_{i=1}^p \mathfrak{g}_i,$$

where \mathfrak{g}_i are simple Lie algebras. Let $G_i = \text{Aut}(\mathfrak{g}_i)$. We consider the adjoint representation $\text{Ad} : G \rightarrow \text{Aut}(\mathfrak{g})$. Let H be the subgroup of G consisting of all $g \in G$ so that $\text{Ad}(g)$ preserves the factors of \mathfrak{g} . Then H is a finite index, Zariski closed subgroup of G . Hence, with our assumptions, $H = G$. Therefore, we get a well-defined projection map $\pi_i : G \rightarrow G_i$. If \mathfrak{p} is the Lie algebra of P , then $\mathfrak{p} = \bigoplus_{i=1}^p \mathfrak{p}_i$, where \mathfrak{p}_i is a Lie subalgebra of \mathfrak{g}_i . Let P_i be the stabilizer of \mathfrak{p}_i in G_i . Then we also obtain a G -equivariant projection, also denoted π_i ,

$$\pi_i : G/P \rightarrow G_i/P_i = G\mathfrak{p}_i \subset \text{Gr}_{\dim(\mathfrak{p}_i)}(\mathfrak{g}_i)$$

where $\text{Gr}_{\dim(\mathfrak{p}_i)}(\mathfrak{g}_i)$ is the Grassmanian space of $\dim(\mathfrak{p}_i)$ -dimensional vector spaces in \mathfrak{g}_i .

If $\xi_n : \partial_\infty \Gamma \rightarrow G/P$ is the limit map of ρ_n , $\pi_i \circ \xi_n$ is a ρ_n -equivariant map from $\partial_\infty \Gamma$ to G_i/P_i . If $\pi_i \circ \xi_n$ is constant, then $\rho_n(\Gamma)$ would normalize a conjugate of \mathfrak{p}_i . So, if $\pi_i \circ \xi_n$ is constant for infinitely many n , then $\rho_0(\Gamma)$ would normalize a conjugate of \mathfrak{p}_i , which is impossible since $\rho_0(\Gamma)$ is Zariski dense and P_i is a proper parabolic subgroup of G_i . Therefore, we may assume that $\pi_i \circ \xi_n$ is non-constant for all i and all n . Since Γ acts topologically transitively on $\partial_\infty \Gamma$, we then know that the image must then be infinite. Therefore, for all i and n ,

$$\dim(\pi_i(\mathfrak{z}_n)) > 0. \quad (5)$$

We may thus assume that $\{\mathfrak{z}_n\}$ converges to a proper Lie subalgebra \mathfrak{z}_0 which is normalized by $\rho_0(\Gamma)$ with

$$\dim(\mathfrak{z}_0) > 0. \quad (6)$$

Since ρ_0 is virtually Zariski dense, \mathfrak{z}_0 must be a strict factor in the Lie algebra \mathfrak{g} of G . Thus, after reordering, we may assume that

$$\mathfrak{z}_0 = \bigoplus_{i=1}^q \mathfrak{g}_i. \quad (7)$$

For n large enough, \mathfrak{z}_n is thus a graph of an homomorphism

$$f_n : \mathfrak{z}_0 \rightarrow \mathfrak{h} = \bigoplus_{i=q+1}^p \mathfrak{g}_i.$$

Since there are only finitely many conjugacy classes (under the adjoint representation) of homomorphisms of \mathfrak{z}_0 into \mathfrak{h} , we may pass to a subsequence such that

$$f_n = \text{Ad}(g_n) \circ f_0 \circ \pi_{\mathfrak{h}_1},$$

where f_0 is a fixed isomorphism from an ideal \mathfrak{h}_1 in \mathfrak{z}_0 to an ideal \mathfrak{h}_2 in \mathfrak{h} , $\pi_{\mathfrak{h}_1}$ is the projection from \mathfrak{z}_0 to \mathfrak{h}_1 and $g_n \in H_2$ where H_i is the subgroup of G whose Lie algebra is \mathfrak{h}_i . Let A_1 be a Cartan subgroup of the subgroup Z_0 of G whose Lie algebra is \mathfrak{z}_0 and let A_2 be a Cartan subgroup of H_2 so that $f_0(\pi_{\mathfrak{h}_1}(A_1)) = A_2$. Let \mathfrak{a}_1 and \mathfrak{a}_2 be the Lie algebras of A_1 and A_2 respectively. Considering the Cartan decomposition $H_2 = KA_2K$ of H_2 where K is a maximal compact subgroup, we may write $g_n = k_n a_n c_n$ with $a_n \in A_2$ and $k_n, c_n \in K$. Moreover we may write $\text{Ad}(c_n) = f_0(\text{Ad}(d_n))$, where d_n lies in a fixed compact subgroup of H_1 . Thus, if $u \in \mathfrak{a}_1$, since A_2 is commutative, we have

$$f_n(\text{Ad}(d_n^{-1})u) = \text{Ad}(g_n)f_0(\text{Ad}(d_n^{-1})u) = \text{Ad}(k_n)f_0(u).$$

We may extract a subsequence so that that $\{k_n\}_{n \in \mathbb{N}}$ and $\{d_n\}_{n \in \mathbb{N}}$ converge respectively to k_0 and d_0 . Therefore,

$$\{(\text{Ad}(d_0^{-1})u, \text{Ad}(k_0)f_0(u)) \mid u \in \mathfrak{a}_1\} \subset \mathfrak{z}_0,$$

which contradicts the fact that $\mathfrak{z}_0 = \bigoplus_{i=1}^q \mathfrak{g}_i$. This contradiction establishes the fact that the set of Anosov, virtually Zariski dense regular homomorphisms is open, which completes the proof. \square

We record the following observation, established in the proof of Proposition 4.3 which will be useful in the proof of Corollary 1.9.

Proposition 4.4. *Suppose that Γ is a word hyperbolic group, G is a semi-simple Lie group with finite center and P is a non-degenerate parabolic subgroup of G . Then $\tilde{Z}(\Gamma; G, P)/G^0$ is an analytic manifold.*

4.3. Kleinian groups. Let $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ be the set of (conjugacy classes of) convex cocompact representations of Γ into $\mathrm{PSL}_2(\mathbb{C})$. We say that a convex cocompact representation ρ in $\mathrm{PSL}_2(\mathbb{C})$ is *Fuchsian* if its image is conjugate into $\mathrm{PSL}_2(\mathbb{R})$. Since every non-elementary Zariski closed, connected subgroup of $\mathrm{PSL}_2(\mathbb{C})$ is conjugate to $\mathrm{PSL}_2(\mathbb{R})$, we note that $\rho \in \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is Zariski dense unless ρ is *almost Fuchsian*, i.e. there exists a finite index subgroup of $\rho(\Gamma)$ which is conjugate into $\mathrm{PSL}_2(\mathbb{R})$ (see also Johnson-Millson [29, Lemma 3.2]). Notice that if ρ is almost Fuchsian, then $\rho(\Gamma)$ contains a finite index subgroup which is isomorphic to a free group or a closed surface group.

Bers [8] proved that $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is a complex analytic manifold. which has real dimension $-6\chi(\Gamma)$ if Γ is torsion-free. (See also Kapovich [30, Section 8.8] where a proof of this is given in the spirit of Proposition 4.1.) We summarize these results in the following proposition.

Proposition 4.5. *Let Γ be a word hyperbolic group. Then*

- (1) $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is a smooth analytic manifold.
- (2) $\rho \in \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is Zariski dense if and only if ρ is not almost Fuchsian.
- (3) If Γ is torsion-free, then $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ has dimension $-6\chi(\Gamma)$.

4.4. Hitchin components. Let S be a closed orientable surface of genus at least 2 and let $\tau_m : \mathrm{PSL}_2(\mathbb{R}) \rightarrow \mathrm{PSL}_m(\mathbb{R})$ be an irreducible homomorphism. If $\rho : \pi_1(S) \rightarrow \mathrm{PSL}_2(\mathbb{R})$ is discrete and faithful, hence uniformizes S , then $\tau_m \circ \rho$ is called a *Fuchsian representation*. A representation $\rho : \pi_1(S) \rightarrow \mathrm{PSL}_m(\mathbb{R})$ that can be deformed into a Fuchsian representation is called a *Hitchin representation*. Lemma 10.1 of [32] implies that all Hitchin representations are irreducible.

Let $H_m(S)$ be the space of Hitchin representations into $\mathrm{PSL}_m(\mathbb{R})$ and let

$$\mathcal{H}_m(S) = H_m(S) / \mathrm{PGL}_m(\mathbb{R}).$$

Each $\mathcal{H}_m(S)$ is called a *Hitchin component* and Hitchin [28] proved that $H_m(S)$ is an analytic manifold diffeomorphic to $\mathbb{R}^{(m^2-1)|\chi(S)|}$.

One may identify the Teichmüller space $\mathcal{T}(S)$ with $\mathcal{H}_2(S)$. The irreducible representation gives rise to an analytic embedding that we also denote τ_m , of $\mathcal{T}(S)$ into the Hitchin component $\mathcal{H}_m(S)$ and we call its image the *Fuchsian locus* of the Hitchin component.

Each Hitchin representation lifts to a representation into $\mathrm{SL}_m(\mathbb{R})$. Labourie [32] showed that all lifts of Hitchin representations are convex, irreducible, and $(\mathrm{SL}_m(\mathbb{R}), \mathbf{B})$ -Anosov where \mathbf{B} is a minimal parabolic subgroup of $\mathrm{SL}_m(\mathbb{R})$. In particular, Hitchin representations are convex Anosov. Moreover, Labourie [32] showed that the image of

every non-trivial element of $\pi_1(S)$ under the lift of a Hitchin representation is diagonalizable with distinct eigenvalues. In particular, every lift of a Hitchin representation is $\mathrm{SL}_m(\mathbb{R})$ -generic, so is contained in $\mathcal{C}_g(\pi_1(S), \mathrm{SL}_m(\mathbb{R}))$. Moreover, notice that distinct lifts of a given Hitchin representation must be contained in distinct components of $\mathcal{C}_g(\pi_1(S), \mathrm{SL}_m(\mathbb{R}))$.

We summarize what we need from Hitchin and Labourie's work in the following result.

Theorem 4.6. *Every Hitchin component lifts to a component of the analytic manifold $\mathcal{C}_g(\pi_1(S), \mathrm{SL}_m(\mathbb{R}))$.*

5. THE GEODESIC FLOW OF A CONVEX REPRESENTATION

In this section, we define a flow $(\mathrm{U}_\rho\Gamma, \{\phi_t\}_{t \in \mathbb{R}})$ associated to a convex, Anosov representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$. We will show that $\mathrm{U}_\rho\Gamma$ is a Hölder reparameterization of the geodesic flow $\mathrm{U}_0\Gamma$ of the domain group Γ , so it will make sense to refer to $\mathrm{U}_\rho\Gamma$ as the *geodesic flow* of the representation.

Let F be the total space of the bundle over

$$\mathbb{RP}(m)^{(2)} = \mathbb{RP}(m) \times \mathbb{RP}(m)^* \setminus \{(U, V) \mid U \not\subset V\},$$

whose fiber at the point (U, V) is the space

$$\mathbf{M}(U, V) = \{(u, v) \mid u \in U, v \in V, \langle v|u \rangle = 1\} / \sim,$$

where $(u, v) \sim (-u, -v)$ and $\mathbb{RP}(m)^*$ is identified with the projective space of the dual space $(\mathbb{R}^m)^*$. Notice that u determines v , so that F is an \mathbb{R} -bundle. One may also identify $\mathbf{M}(U, V)$ with the space of metrics on U .

Then F is equipped with a natural \mathbb{R} -action, given by

$$\phi_t(U, V, (u, v)) = (U, V, (e^t u, e^{-t} v)).$$

If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex, Anosov representation and ξ and θ are the associated limit maps, we consider the associated pullback bundle

$$F_\rho = (\xi, \theta)^* F$$

over $\partial_\infty \Gamma^{(2)}$ which inherits an \mathbb{R} action from the action on F . The action of Γ on $\partial_\infty \Gamma^{(2)}$ extends to an action on F_ρ . If we let

$$\mathrm{U}_\rho\Gamma = F_\rho / \Gamma,$$

then the \mathbb{R} -action on F_ρ descends to a flow $\{\phi_t\}_{t \in \mathbb{R}}$ on $\mathrm{U}_\rho\Gamma$, which we call the *geodesic flow* of the representation.

The aim of this section is to establish the following proposition.

Proposition 5.1. [THE GEODESIC FLOW] *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex Anosov representation, then the action of Γ on F_ρ is proper and cocompact. Moreover, the flow $\{\phi_t\}_{t \in \mathbb{R}}$ on $\mathrm{U}_\rho \Gamma$ is Hölder conjugate to a Hölder reparameterization of the Gromov geodesic flow on $\mathrm{U}_0 \Gamma$ and the orbit associated to $[\gamma]$, for any infinite order primitive element $\gamma \in \Gamma$, has period $\Lambda(\rho)(\gamma)$.*

We produce a Γ -invariant Hölder orbit equivalence between $\widetilde{\mathrm{U}_0 \Gamma}$ and F_ρ which is a homeomorphism. Recall that $\widetilde{\mathrm{U}_0 \Gamma} = \partial_\infty \Gamma^{(2)} \times \mathbb{R}$ and that $\widetilde{\mathrm{U}_0 \Gamma} / \Gamma = \mathrm{U}_0 \Gamma$. Since the action of Γ on $\widetilde{\mathrm{U}_0 \Gamma}$ is proper and cocompact, it follows immediately that $\mathrm{U}_\rho \Gamma$ is Hölder conjugate to a Hölder reparameterization of the Gromov geodesic flow on $\mathrm{U}_0 \Gamma$.

Proposition 5.2. *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex, Anosov representation, there exists a Γ -equivariant Hölder orbit equivalence*

$$\tilde{\nu} : \widetilde{\mathrm{U}_0 \Gamma} \rightarrow F_\rho$$

which is a homeomorphism.

Let E_ρ be the flat bundle associated to ρ on $\mathrm{U}_0 \Gamma$. Recall that E_ρ splits as

$$E_\rho = \Xi \oplus \Theta.$$

Let $\{\psi_t\}_{t \in \mathbb{R}}$ be the lift of the geodesic flow on $\mathrm{U}_0 \Gamma$ to a flow on E_ρ . We first observe that we may produce a Hölder metric on the bundle Ξ which is contracting on all scales.

Lemma 5.3. *There exists a Hölder metric G^0 on the bundle Ξ and $\beta > 0$ such that for all $t > 0$ we have,*

$$\psi_t^*(G^0) < e^{-\beta t} G^0.$$

Proof. Let G be any Hölder metric on Ξ . Since ρ is convex and Anosov, Lemma 2.4 implies that there exists $t_0 > 0$ such that

$$\psi_{t_0}^*(G) \leq \frac{1}{4} G.$$

Choose $\beta > 0$ so that $2 < e^{\beta t_0} < 4$ and, for all s , let $G_s = \psi_s^*(G)$. Let

$$G^0 = \int_0^{t_0} e^{\beta s} G_s \, ds.$$

Notice that G^0 has the same regularity as G . If $t > 0$, then

$$\begin{aligned} \psi_t^*(G^0) &= \int_0^{t_0} e^{\beta s} G_{t+s} \, ds \\ &= e^{-\beta t} \int_t^{t+t_0} e^{\beta u} G_u \, du \end{aligned} \tag{8}$$

Now observe that

$$\begin{aligned} \int_t^{t+t_0} e^{\beta u} G_u \, du &= G^0 + \int_{t_0}^{t+t_0} e^{\beta u} G_u \, du - \int_0^t e^{\beta u} G_u \, du \\ &= G^0 + \int_0^t e^{\beta u} \psi_u^* (e^{\beta t_0} \psi_{t_0}^*(G) - G) \, du. \end{aligned} \quad (9)$$

But

$$e^{\beta t_0} \psi_{t_0}^*(G) \leq \frac{e^{\beta t_0}}{4} G < G.$$

Thus

$$\int_t^{t+t_0} e^{\beta u} G_u \, du < G^0.$$

and the result follows from Inequality (8). \square

5.0.1. *Proof of Proposition 5.2.* Let G^0 be the metric provided by Lemma 5.3 and let β be the associated positive number. Let $\tilde{\Xi}$ denote the line bundle over $\partial_\infty \Gamma^{(2)} \times \mathbb{R}$ which is the lift of Ξ . Notice that G^0 lifts to a Hölder metric \tilde{G}^0 on $\tilde{\Xi}$. Our Hölder orbit equivalence

$$\tilde{\nu} : \partial_\infty \Gamma^{(2)} \times \mathbb{R} \rightarrow F_\rho$$

will be given by

$$\tilde{\nu}(x, y, t) = (x, y, (u(x, y, t), v(x, y, t))),$$

where $\tilde{G}_{(x,y,t)}^0(u(x, y, t)) = 1$ and $\tilde{G}_{(x,y,t)}^0$ is the metric on the line $\xi(x)$ induced by the metric \tilde{G}^0 by regarding $\xi(x)$ as the fiber of $\tilde{\Xi}$ over the point (x, y, t) . The fact that $\psi_t^* G^0 < G^0$ for all $t > 0$ implies that $\tilde{\nu}$ is injective. Since \tilde{G}^0 is Hölder and ρ -equivariant, $\tilde{\nu}$ is also Hölder and ρ -equivariant.

It remains to prove that $\tilde{\nu}$ is proper. We will argue by contradiction. If $\tilde{\nu}$ is not proper, then there exists a sequence $\{(x_n, y_n, t_n)\}_{n \in \mathbb{N}}$ leaving every compact subset of $\partial_\infty \Gamma^{(2)} \times \mathbb{R}$, such that $\{\tilde{\nu}(x_n, y_n, t_n)\}_{n \in \mathbb{N}}$ converges to $(x, y, (u, v))$ in F_ρ . Letting $\tilde{\nu}(x_n, y_n, t_n) = (x_n, y_n, (u_n, v_n))$, we see immediately that

$$\lim_{n \rightarrow \infty} x_n = x, \quad \lim_{n \rightarrow \infty} y_n = y, \quad \text{and} \quad \lim_{n \rightarrow \infty} (u_n, v_n) = (u, v).$$

Writing $\tilde{\nu}(x_n, y_n, 0) = (x_n, y_n, (\hat{u}_n, \hat{v}_n))$ and $\tilde{\nu}(x, y, 0) = (x, y, (\hat{u}, \hat{v}))$, we obtain, by the continuity of the map $\tilde{\nu}$,

$$\lim_{n \rightarrow \infty} (\hat{u}_n, \hat{v}_n) = (\hat{u}, \hat{v}).$$

If $t > 0$, then

$$\frac{\tilde{G}_{(x,y,t)}^0}{\tilde{G}_{(x,y,0)}^0} = \frac{\psi_t^* (\tilde{G}_{(x,y,0)}^0)}{\tilde{G}_{(x,y,0)}^0} < e^{-\beta t}.$$

In particular,

$$\left| \frac{\langle v | u_n \rangle}{\langle v | \hat{u}_n \rangle} \right| < e^{-\beta t_n}. \quad (10)$$

Without loss of generality, either $t_n \rightarrow \infty$ or $t_n \rightarrow -\infty$. If $t_n \rightarrow \infty$, then by Inequality (10),

$$0 = \lim_{n \rightarrow \infty} \frac{\langle v | u_n \rangle}{\langle v | \hat{u}_n \rangle},$$

on the other hand,

$$\lim_{t \rightarrow \infty} \frac{\langle v | u_n \rangle}{\langle v | \hat{u}_n \rangle} = \frac{\langle v | u \rangle}{\langle v | \hat{u} \rangle} \neq 0.$$

We have thus obtained a contradiction. Symmetrically, if $t_n \rightarrow -\infty$, then

$$0 = \lim_{n \rightarrow \infty} \frac{\langle v | \hat{u}_n \rangle}{\langle v | u_n \rangle} = \frac{\langle v | \hat{u} \rangle}{\langle v | u \rangle} \neq 0,$$

which is again a contradiction.

The restriction of $\tilde{\nu}$ to each orbit $\{(x, y)\} \times \mathbb{R}$ is a proper, continuous, injection into the fiber of F_ρ over (x, y) (which is also homeomorphic to \mathbb{R}). It follows that the restriction of $\tilde{\nu}$ to each orbit is a homeomorphism onto the image fiber. We conclude that $\tilde{\nu}$ is surjective and hence a proper, continuous, bijection. Therefore, $\tilde{\nu}$ is a homeomorphism. This completes the proof of Proposition 5.2.

In order to complete the proof of Proposition 5.1, it only remains to compute the period of the orbit associated to $[\gamma]$ for an infinite order primitive element $\gamma \in \Gamma$. Since ρ is convex Anosov, Proposition 2.6 implies that $\rho(\gamma)$ is proximal, $\xi(\gamma^+)$ is the attracting line and $\theta(\gamma^-)$ is the repelling hyperplane. If $u \in \xi(\gamma^+)$ and $v \in \theta(\gamma^-)$ one sees that

$$\rho(\gamma)(u) = \mathbf{L}(\gamma)(\rho) u \text{ and } \rho(\gamma)(v) = \frac{1}{\mathbf{L}(\gamma)(\rho)} v.$$

Thus, $(\gamma^+, \gamma^-, (u, v))$ and

$$(\gamma^+, \gamma^-, \mathbf{L}(\gamma)(\rho)u, \frac{1}{\mathbf{L}(\gamma)(\rho)}v) = \phi_{\log(\mathbf{L}(\gamma)(\rho))}(\gamma^+, \gamma^-, (u, v))$$

project to the same point on $\mathbf{U}_\rho \Gamma$. (Recall that

$$(\mathbf{L}(\gamma)(\rho)u, \frac{1}{\mathbf{L}(\gamma)(\rho)}v) \sim (-\mathbf{L}(\gamma)(\rho)u, \frac{-1}{\mathbf{L}(\gamma)(\rho)}v)$$

in $M(\xi(\gamma^+), \theta(\gamma^-))$.) Since γ is primitive, this finishes the proof.

6. THE GEODESIC FLOW IS A METRIC ANOSOV FLOW

In this section, we prove that the geodesic flow of a convex Anosov representation is a metric Anosov flow:

Proposition 6.1. [ANOSOV] *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex, Anosov representation, then the geodesic flow $(\mathrm{U}_\rho \Gamma, \{\phi_t\}_{t \in \mathbb{R}})$ is a topologically transitive metric Anosov flow.*

We recall that a flow $\{\phi_t\}_{t \in \mathbb{R}}$ on a metric space X is *topologically transitive* if given any two open sets U and V in X , there exists $t \in \mathbb{R}$ so that $\phi_t(U) \cap V$ is non-empty. The topological transitivity of $(\mathrm{U}_\rho \Gamma, \{\phi_t\}_{t \in \mathbb{R}})$ follows immediately from the topological transitivity of the action of Γ on $\partial_\infty \Gamma^2$. The definition of a metric Anosov flow is given in the next section and a more precise version of the statement is given in Proposition 6.8.

The reader with a background in hyperbolic dynamics may be convinced by the following heuristic argument: essentially the splitting of an Anosov representation yields a section of some (product of) flag manifolds and the graph of this section should be thought as a Smale locally maximal hyperbolic set; then the result follows from the “fact” that the restriction of the flow on such a set is a metric Anosov flow. However, the above idea does not exactly work, and moreover it is not easy to extricate it from the existing literature in the present framework. Therefore, we give a detailed and *ad-hoc* construction, although the result should be true in a rather general setting.

We begin by giving the definition of a metric Anosov flow in Section 6.1. We then define a metric on the geodesic flow in Section 6.2, introduce the stable and unstable leaves in Section 6.3, explain how to control the metric along the unstable leaves in Section 6.4 and finally proceed to the proof in Section 6.5.

6.1. Metric Anosov flows. Let X be metric space. Let \mathcal{L} be an equivalence relation on X . We denote by \mathcal{L}_x the equivalence class of x and call it the *leaf* through x , so that we have a partition of X into leaves

$$X = \bigsqcup_{y \in Y} \mathcal{L}_y,$$

where Y is the collection of equivalence classes of \mathcal{L} . Such a partition is a *lamination* if for every x in X , there exist two topological spaces U and K , a homeomorphism ν called a *chart* from $U \times K$ to an open subset of X such that $\nu(u, z) \mathcal{L} \nu(v, z)$ for all $u, v \in U$ and $z \in K$. A *plaque open set* in the chart corresponding to ν is a set of the form $\nu(O \times \{z_0\})$ where $x = \nu(y_0, z_0)$ and O is an open set in U .

The *plaque topology* on \mathcal{L}_x is the topology generated by the plaque open sets. A *plaque neighborhood* of x is a neighborhood for the plaque topology on \mathcal{L}_x .

We say that two laminations \mathcal{L}^\pm define a *local product structure*, if for any point x in X there exist plaque neighborhoods U^\pm of x in \mathcal{L}_x^\pm and a homeomorphism η from $U^+ \times U^-$ to an open neighborhood of x such that

$$\eta(u, y) \mathcal{L}^+ \eta(v, y) \quad \text{and} \quad \eta(u, y) \mathcal{L}^- \eta(u, z)$$

for all $u, v \in U^+$ and $y, z \in U^-$.

If \mathcal{L} is a lamination invariant by a flow $\{\phi_t\}_{t \in \mathbb{R}}$, we say that the lamination is *contracted by the flow*, if there exists $t_0 > 0$ such that for all $x \in X$, there exists a chart $\nu_x : U \times K \rightarrow V$ of an open neighborhood V of x , such that if

$$z = \nu_x(u, k), \quad \text{and} \quad y = \nu_x(v, k),$$

then for all $t > t_0$

$$d(\phi_t(z), \phi_t(y)) < \frac{1}{2}d(z, y).$$

If $\{\phi_t\}_{t \in \mathbb{R}}$ is a flow on X and \mathcal{L}^c is a lamination on X which is invariant under the flow, we say \mathcal{L}^c is *transverse to the flow*, if for every x in X , there exists a plaque neighborhood U of x in \mathcal{L}_x , a topological space K , $\epsilon > 0$, and a chart

$$\nu : U \times K \times (-\epsilon, \epsilon),$$

such that

$$\phi_t(\nu(u, k, s)) = \nu(u, k, s + t).$$

If \mathcal{L}^c is tranverse to the flow, we define a new lamination, called the *central lamination* with respect to \mathcal{L}^c , and denoted $\mathcal{L}^{c,0}$ by letting $x \mathcal{L}^{c,0} y$ if and only if there exists s such that $\phi_s(x) \mathcal{L}^c y$.

Definition 6.2. [METRIC ANOSOV FLOW] *A flow $\{\phi_t\}_{t \in \mathbb{R}}$ on a compact metric space X is metric Anosov, if there exists two laminations \mathcal{L}^+ and \mathcal{L}^- such that*

- (1) $(\mathcal{L}^+, \mathcal{L}^{-,0})$ defines a local product structure,
- (2) $(\mathcal{L}^-, \mathcal{L}^{+,0})$ defines a local product structure,
- (3) the leaves of \mathcal{L}^+ are contracted by the flow, and
- (4) the leaves of \mathcal{L}^- are contracted by the inverse flow.

Then \mathcal{L}^+ , \mathcal{L}^- , $\mathcal{L}^{+,0}$, $\mathcal{L}^{-,0}$ are respectively called the stable, unstable, central stable and central unstable laminations.

6.2. The geodesic flow as a metric space. Recall that F is the total space of an \mathbb{R} -bundle over $\mathbb{RP}(m)^{(2)}$ whose fiber at the point (U, V) is the space $\mathbf{M}(U, V) = \{(u, v) \mid u \in U, v \in V, \langle v|u \rangle = 1\} / \sim$. Since $\mathbb{RP}(m)^{(2)} \subset \mathbb{RP}(m) \times \mathbb{RP}(m)^*$, any Euclidean metric on \mathbb{R}^m gives rise to a metric on F which is a subset of $\mathbb{RP}(m) \times \mathbb{RP}(m)^* \times \mathbb{R}^m \times (\mathbb{R}^m)^*$. The metric on F pulls back to a metric on F_ρ . A metric on F_ρ obtained by this procedure is called a *linear metric*. Any two linear metrics are bilipschitz equivalent.

The following lemma allows us to use a linear metric to study F_ρ .

Lemma 6.3. *There exists a Γ -invariant metric d_0 on F_ρ which is locally bilipschitz equivalent to any of the linear metrics.*

The Γ -invariant metric d_0 descends to a metric on $\mathbf{U}_\rho \Gamma$ which we will also call d_0 and is defined for every x and y in F_ρ by

$$d_0(\pi(x), \pi(y)) = \inf_{\gamma \in \Gamma} (x, \gamma(y)),$$

where π is the projection $F_\rho \rightarrow \mathbf{U}_\rho \Gamma$.

Proof. We first notice that all linear metrics on F_ρ are bilipschitz to one another, so that it suffices to construct a metric which is locally bilipschitz to a fixed linear metric d .

Let U be an open subset of F_ρ with compact closure which contains a closed fundamental domain for the action of Γ on F_ρ . Since the action of Γ on F_ρ is proper, $\{U_\gamma = \gamma(U)\}_{\gamma \in \Gamma}$ is a locally finite cover of F_ρ . Let $\{d_\gamma = \gamma^*d\}_{\gamma \in \Gamma}$ be the associated family of metrics on F_ρ . Since each element of Γ acts as a bilipschitz automorphism with respect to any linear metric, any two metrics in the family $\{d_\gamma = \gamma^*d\}_{\gamma \in \Gamma}$ are bilipschitz equivalent.

We will use this cover and the associated family of metrics to construct a Γ -invariant metric on F_ρ . A *path* joining two points x and y in X is a pair of tuples

$$\mathcal{P} = ((z_0, \dots, z_n), (\gamma_0, \dots, \gamma_n)),$$

where (z_0, \dots, z_n) is an n -tuple of points in F_ρ and $(\gamma_0, \dots, \gamma_n)$ is an n -tuple of elements of Γ such that

- $x = z_0 \in U_{\gamma_0}$ and $y = z_n \in U_{\gamma_n}$,
- for all $n > i > 0$, $z_i \in U_{\gamma_{i-1}} \cap U_{\gamma_i}$.

The *length* of a path is given by

$$\ell(\mathcal{P}) = \frac{1}{2} \left(\sum_{i=0}^{n-1} d_{\gamma_i}(z_i, z_{i+1}) + d_{\gamma_{i+1}}(z_i, z_{i+1}) \right)$$

We then define

$$d_0(x, y) = \inf\{\ell(\mathcal{P}) \mid \mathcal{P} \text{ joins } x \text{ and } y\}.$$

It is clear that d_0 is a Γ -invariant pseudo metric. It remains to show that d_0 is a metric which is locally bilipschitz to d .

Let z be a point in F_ρ . Then there exists a neighborhood V of z so that

$$A = \{\gamma \mid U_\gamma \cap V \neq \emptyset\},$$

is a finite set. Choose $\alpha > 0$ so that

$$\bigcup_{\gamma \in A} \{x \mid d_\gamma(z, x) \leq \alpha\} \subset V.$$

Let K be chosen so that if $\alpha, \beta \in A$, then d_α and d_β are K -bilipschitz. Finally, let

$$W = \bigcap_{\gamma \in A} \left\{x \mid d_\gamma(z, x) \leq \frac{\alpha}{10K}\right\}.$$

By construction, if x and y belong to W , then for all $\gamma \in A$,

$$d_\gamma(x, y) \leq \frac{\alpha}{2K}. \quad (11)$$

Let x be a point in W . Let $\mathcal{P} = ((z_0, \dots, z_n), (\gamma_0, \dots, \gamma_n))$ be a path joining x to a point y .

If there exists j such that $\gamma_j \notin A$, then

$$\begin{aligned} \ell(\mathcal{P}) &\geq \frac{1}{2} \sum_{i=0}^{j-1} d_{\gamma_i}(z_{i-1}, z_i) \\ &\geq \frac{1}{2K} \left(\sum_{i=0}^{j-1} d_{\gamma_{j-1}}(z_i, z_{i+1}) \right) \\ &\geq \frac{1}{2K} d_{\gamma_{j-1}}(z_0, z_j) \geq \frac{1}{2K} (d_{\gamma_{j-1}}(z, z_j) - d_{\gamma_{j-1}}(z_0, z)) \\ &\geq \frac{1}{2K} \left(\alpha - \frac{\alpha}{10K} \right) \geq \frac{\alpha}{5K}. \end{aligned} \quad (12)$$

If $\gamma_j \in A$ for all j , then the triangle inequality and the definition of K immediately imply that for all $\gamma \in A$,

$$\ell(\mathcal{P}) \geq \frac{1}{K} d_\gamma(x, y). \quad (13)$$

Inequalities (12) and (13) imply that

$$d_0(x, y) \geq \frac{1}{K} \inf \left(\frac{\alpha}{5}, d_\gamma(x, y) \right) > 0, \quad (14)$$

hence d_0 is a metric. Moreover, if $x, y \in W$, then by inequalities (14) and (11),

$$d_0(x, y) \geq \frac{1}{K} d_\gamma(x, y). \quad (15)$$

By construction, and taking the path $\mathcal{P}_0 = ((x, y), (\gamma, \gamma))$ with γ in A , we also get

$$d_0(x, y) \leq \ell(\mathcal{P}_0) = d_\gamma(x, y). \quad (16)$$

As consequence of inequalities (15) and (16), d_0 is bilipschitz on W to any d_γ with $\gamma \in A$.

Since d is bilipschitz to d_γ for any $\gamma \in A$, we see that d_0 is bilipschitz to d on W .

Since z was arbitrary, it follows that d_0 is locally bilipschitz to d . \square

6.3. Stable and unstable leaves. In this section, we define the stable and unstable laminations of the geodesic flow F_ρ . Let

$$X = (x_0, y_0, (u_0, v_0))$$

be a point in F_ρ .

(1) The *stable leaf through X* is

$$\mathcal{L}_X^+ = \{(x, y_0, (u, v_0)) \mid x \in \partial_\infty \Gamma, u \in \xi(x), \langle v_0 | u \rangle = 1\}.$$

The *central stable leaf through X* is

$$\begin{aligned} \mathcal{L}_X^{+,0} &= \{(x, y_0, (u, v)) \mid x \in \partial_\infty \Gamma, (u, v) \in \mathbf{M}(\xi(x), \theta(y_0))\} \\ &= \bigcup_{t \in \mathbb{R}} \phi_t(\mathcal{L}_X^+). \end{aligned}$$

(2) The *unstable leaf through X* is

$$\mathcal{L}_X^- = \{(x_0, y, (u_0, v)) \mid y \in \partial_\infty \Gamma, v \in \theta(y), \langle v | u_0 \rangle = 1\}.$$

The *central unstable leaf through X* is

$$\begin{aligned} \mathcal{L}_X^{-,0} &= \{(x_0, y, (u, v)) \mid y \in \partial_\infty \Gamma, (u, v) \in \mathbf{M}(\xi(x_0), \theta(y))\} \\ &= \bigcup_{t \in \mathbb{R}} \phi_t(\mathcal{L}_X^-). \end{aligned}$$

Observe that \mathcal{L}_X^+ is homeomorphic to $\partial_\infty \Gamma \setminus \{x_0\}$ and \mathcal{L}_X^- is homeomorphic to $\partial_\infty \Gamma \setminus \{y_0\}$.

The following two propositions are immediate from our construction.

Proposition 6.4. [INVARIANCE] *If $\gamma \in \Gamma$ and $t \in \mathbb{R}$, then*

$$\mathcal{L}_{\gamma(X)}^\pm = \gamma(\mathcal{L}_X^\pm) \quad \text{and} \quad \mathcal{L}_{\phi_t(X)}^\pm = \phi_t(\mathcal{L}_X^\pm).$$

Proposition 6.5. [PRODUCT STRUCTURE] *The (two) pairs of lamination $(\mathcal{L}^\pm, \mathcal{L}^{\mp,0})$ define a local product structure on F_ρ , and hence on $\cup_\rho \Gamma$.*

Remark: Throughout this section, we abuse notation by allowing $\{\phi_t\}_{t \in \mathbb{R}}$ to denote both the flow on $U_\rho \Gamma$ and the flow on F_ρ which covers it and letting \mathcal{L}^\pm denote both the lamination on F_ρ and the induced lamination on $U_\rho \Gamma$.

6.4. The leaf lift and the distance. In this section we introduce the *leaf lift* and shows that it helps in controlling distances in F_ρ .

We first define the leaf lift for points in the bundle F . Let $A = (U, V, (u_0, v_0))$ be a point in F . We observe that there exists a unique continuous map, called the *leaf lift* from

$$O_A = \{w \in \mathbb{RP}(m)^* \mid U \cap \ker(w) = \{0\}\}.$$

to $((\mathbb{R}^m)^* \setminus \{0\}) / \pm 1$ such that w is taken to $\Omega_{w,A}$ such that

$$\Omega_{w,A} \in w, \quad \langle \Omega_{w,A} | u_0 \rangle = 1. \quad (17)$$

In particular, $\Omega_{v_0,A} = v_0$. Observe that at this stage the leaf lift is just a rebranding of the classical notion of an affine chart.

The following lemma records immediate properties of the leaf lift .

Lemma 6.6. *Let $\|\cdot\|_1$ be a Euclidean norm on \mathbb{R}^n and d_1 the associated metric on $\mathbb{RP}(m)^*$. If $A = (x, y, (u, v)) \in F$, then there exist constants $K_1 > 0$ and $\alpha_1 > 0$ such that for $w_0, w_1 \in \mathbb{RP}(m)^*$*

- *If $d_1(w_i, y) \leq \alpha_1$, for $i = 0, 1$, then*

$$\|\Omega_{w_0,A} - \Omega_{w_1,A}\|_1 \leq K_1 d_1(w_0, w_1),$$

- *If $\|\Omega_{w_i,A} - \Omega_{y,A}\|_1 \leq \alpha_1$ for $i = 0, 1$, then*

$$d_1(w_0, w_1) \leq K_1 \|\Omega_{w_0,A} - \Omega_{w_1,A}\|_1.$$

If $Z = (x, y, (u_0, v_0)) \in F_\rho$ and $W = (x, w, (u_0, v)) \in \mathcal{L}_Z^-$, then we define the *leaf lift*

$$\omega_{W,Z} = \Omega_{\xi^*(w), (\xi(x), \xi^*(y), (u_0, v_0))} = v.$$

Let d_0 be the metric on F_ρ produced by Proposition 6.6. Let $\|\cdot\|$ be a continuous Γ -equivariant map from F_ρ to the space of metrics on \mathbb{R}^m .

The following result allows us to use the leaf lift to bound distances in F_ρ

Proposition 6.7. *Let d_0 be a Γ -invariant metric on F_ρ which is locally bilipschitz equivalent to a linear metric and let $\|\cdot\|$ be a Γ -invariant map from F_ρ into the space of Euclidean metrics on \mathbb{R}^m . There exist positive constants K and α such that for any $Z \in F_\rho$ and any $W \in \mathcal{L}_Z^-$,*

- *if $d_0(W, Z) \leq \alpha$, then*

$$\|\omega_{W,Z} - \omega_{Z,Z}\|_Z \leq K d_0(W, Z), \quad (18)$$

- if $\|\omega_{W,Z} - \omega_{Z,Z}\|_Z \leq \alpha$ then

$$d_0(W, Z) \leq K \|\omega_{W,Z} - \omega_{Z,Z}\|_Z. \quad (19)$$

Proof. Since Γ acts cocompactly on F_ρ and both d_0 and the section $\|\cdot\|$ are Γ -invariant, it suffices to prove the previous assertion for Z in a compact subset R of F_ρ . Observe first that d_0 is uniformly C -bilipschitz on R to any of the linear metrics d_Z coming from $\|\cdot\|_Z$ for Z in R for some constant C .

Lemma 6.6 implies that, for all $Z \in R$, there exist positive constants K_Z and α_Z such that if $W_0, W_1 \in \mathcal{L}_Z^- \cap O$, then

- If $d_0(W_i, Z) \leq \alpha_Z$ for $i = 0, 1$, then

$$\|\omega_{W_0,Z} - \omega_{W_1,Z}\|_Z \leq K_Z d_0(W_0, W_1),$$

- If $\|\omega_{W_i,Z} - \omega_{Z,Z}\|_Z \leq \alpha_Z$ for $i = 0, 1$, then

$$d_0(W_0, W_1) \leq K_Z \|\omega_{W_0,Z} - \omega_{W_1,Z}\|_Z.$$

Since R is compact, one may apply the classical argument which establishes that continuous functions are uniformly continuous on compact sets, to show that there are positive constants K and α which work for all $Z \in R$. \square

6.5. The geodesic flow is Anosov. The following result completes the proof of Proposition 6.1

Proposition 6.8. [ANOSOV PROPERTY] *Let $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ be a convex Anosov representation, and let \mathcal{L}_X^\pm be the laminations on $\mathrm{U}_\rho \Gamma$ defined above. Then there exists a metric on $\mathrm{U}_\rho \Gamma$, Hölder equivalent to the Hölder structure on $\mathrm{U}_\rho \Gamma$, such that*

- (1) \mathcal{L}^+ is contracted by the flow,
- (2) \mathcal{L}^- is contracted by the inverse flow,

We first show that the leaf lift is contracted by the inverse flow.

Lemma 6.9. *There exists a Γ -invariant map $Z \mapsto \|\cdot\|_Z$ from F_ρ into the space of Euclidean metrics on \mathbb{R}^m , such that for every positive integer n , there exists $t_0 > 0$ such that if $t < -t_0$, $Z \in F_\rho$, and $W \in \mathcal{L}_Z^-$ then*

$$\|\omega_{\phi_t(W), \phi_t(Z)} - \omega_{\phi_t(Z), \phi_t(Z)}\|_{\phi_t(Z)} \leq \frac{1}{2^n} \|\omega_{W,Z} - \omega_{Z,Z}\|_Z. \quad (20)$$

The following notation will be used in the proof.

- For a vector space A and a subspace $B \subset A$, let

$$B^\perp = \{\omega \in A^* \mid B \subset \ker(\omega)\}.$$

- We consider the Γ -invariant splitting of the trivial \mathbb{R}^m -bundle

$$F_\rho \times \mathbb{R}^m = \hat{\Xi} \oplus \hat{\Theta}$$

- where $\hat{\Xi}$ is the line bundle over F_ρ such that the fiber above $(x, y, (u, v))$ is given by $\xi(x)$ and
- $\hat{\Theta}$ is a hyperplane bundle over F_ρ with fiber $\theta(y)$ above the point $(x, y, (u, v)) \in F_\rho$.

Proof. Suppose that $Z = (x, y, (u_0, v_0))$ and $W = (x, w, (u_0, v)) \in \mathcal{L}_Z^-$, then by the definition of the leaf lift

$$(\omega_{W,Z} - \omega_{Z,Z})(u_0) = 0,$$

and thus

$$\omega_{W,Z} = \alpha_{W,Z} + \omega_{Z,Z},$$

where $\alpha_{W,Z} \in \xi(x)^\perp$. Then

$$\phi_t(\omega_{W,Z}) = \phi_t(\alpha_{W,Z}) + \phi_t(\omega_{Z,Z}).$$

We choose a Γ -invariant map from F_ρ into the space of Euclidean metrics on \mathbb{R}^m so that for all $Y \in F_\rho$

$$\|\omega_{Y,Y}\|_Y = 1.$$

Then

$$\omega_{\phi_t(Z), \phi_t(Z)} = \frac{1}{\|\phi_t(\omega_{Z,Z})\|_{\phi_t(Z)}} \phi_t(\omega_{Z,Z}),$$

hence

$$\omega_{\phi_t(W), \phi_t(Z)} = \frac{\phi_t(\alpha_{W,Z})}{\|\phi_t(\omega_{Z,Z})\|_{\phi_t(Z)}} + \omega_{\phi_t(Z), \phi_t(Z)}.$$

It follows that

$$\|\omega_{\phi_t(W), \phi_t(Z)} - \omega_{\phi_t(Z), \phi_t(Z)}\|_{\phi_t(Z)} = \frac{\|\phi_t(\alpha_{W,Z})\|_{\phi_t(Z)}}{\|\phi_t(\omega_{Z,Z})\|_{\phi_t(Z)}}$$

Since ρ is convex Anosov, and $(U_\rho \Gamma, \{\phi_t\}_{t \in \mathbb{R}})$ is a Hölder reparameterization of $(U_0 \Gamma, \{\psi_t\}_{t \in \mathbb{R}})$, there exists $t_1 > 0$ so that for all $Z \in F_\rho$ and for all $t < -t_1$, if $v \in \hat{\Xi}_Z^\perp$ and $w \in \hat{\Theta}_Z^\perp$, then

$$\frac{\|\phi_t(v)\|_{\phi_t(Z)}}{\|\phi_t(w)\|_{\phi_t(Z)}} \leq \frac{1}{2} \frac{\|v\|_Z}{\|w\|_Z}.$$

Thus, since $\alpha_{W,Z} \in \hat{\Xi}_Z^\perp$ and $\omega_{Z,Z} \in \hat{\Theta}_Z^\perp$, for all $n \in \mathbb{N}$ and $t < -nt_1$, we have

$$\|\omega_{\phi_t(W), \phi_t(Z)} - \omega_{\phi_t(Z), \phi_t(Z)}\|_{\phi_t(Z)} \leq \frac{1}{2^n} \frac{\|\alpha_{W,Z}\|_Z}{\|\omega_{Z,Z}\|_Z}.$$

Since $\alpha_{W,Z} = \omega_{W,Z} - \omega_{Z,Z}$ and $\|\omega_{Z,Z}\|_Z = 1$, the previous assertion yields the result with $t_0 = -nt_1$. \square

We are now ready to establish Proposition 6.8.

Proof of Proposition 6.8: Let K and α be as in Proposition 6.7. Choose $n \in \mathbb{N}$ so that

$$\frac{K}{2^n} \leq 1, \quad \frac{K^2}{2^n} \leq \frac{1}{2}. \quad (21)$$

Let t_0 be the constant from Lemma 6.9 with our choice of n .

Suppose that $Z \in F_\rho$, $W \in \mathcal{L}_Z^-$ and $d_0(W, Z) \leq \alpha$. Then, by Inequality (18),

$$\|\omega_{W,Z} - \omega_{Z,Z}\| \leq K d_0(W, Z). \quad (22)$$

By Lemma 6.9,

$$\|\omega_{\phi_t(W), \phi_t(Z)} - \omega_{\phi_t(Z), \phi_t(Z)}\|_{\phi_t(Z)} \leq \frac{1}{2^n} \|\omega_{W,Z} - \omega_{Z,Z}\|_Z. \quad (23)$$

In particular, combining Equations (22), (23) and (21),

$$\|\omega_{\phi_t(W), \phi_t(Z)} - \omega_{\phi_t(Z), \phi_t(Z)}\|_{\phi_t(Z)} \leq \frac{1}{2^n} K \alpha \leq \alpha. \quad (24)$$

Thus, using Inequality (19),

$$d_0(\phi_t(W), \phi_t(Z)) \leq K \|\omega_{\phi_t(W), \phi_t(Z)} - \omega_{\phi_t(Z), \phi_t(Z)}\|_{\phi_t(Z)}. \quad (25)$$

Combining finally Equations (22), (23), (23) and (21), we get that

$$d_0(\phi_t(W), \phi_t(Z)) \leq \frac{K^2}{2^n} d_0(W, Z) \leq \frac{1}{2} d_0(W, Z) \quad (26)$$

for all $t < -t_0$.

Therefore \mathcal{L}^- is contracted by the inverse flow on F_ρ .

Let us now consider what happens in the quotient $\mathcal{U}_\rho \Gamma = F_\rho / \Gamma$. For any $Z \in F_\rho$ and $\epsilon > 0$, let

$$\mathcal{L}_\epsilon^\pm(Z) = \mathcal{L}_Z^\pm \cap B(Z, \epsilon).$$

and let

$$K_\epsilon(Z) = \Pi_Z (\mathcal{L}_\epsilon^+(Z) \times \mathcal{L}_\epsilon^-(Z) \times (-\epsilon, \epsilon)),$$

where Π_Z is the product structure of Proposition 6.5. By Proposition 5.1, there exists $\epsilon_0 > 0$ such that for all $\gamma \in \Gamma \setminus \{1\}$ and $Z \in F_\rho$,

$$\gamma(K_{\epsilon_0}(X)) \cap K_{\epsilon_0} = \emptyset$$

Let $\epsilon \in (0, \min\{\epsilon_0/2, \alpha\})$ and $\hat{Z} \in \mathcal{U}_\rho \Gamma$. Choose $Z \in F_\rho$ in the pre image of \hat{Z} , then inequality (26) holds for the inverse flow on $\mathcal{U}_\rho \Gamma$ for points in the chart which is the projection of $K_\epsilon(Z)$. Therefore, \mathcal{L}^- is contracted by the inverse flow on $\mathcal{U}_\rho \Gamma$.

A symmetric proof holds for the central stable leaf.

7. THERMODYNAMICS FORMALISM

7.1. Hölder flows on compact spaces. Let X be a compact metric space with a Hölder continuous flow $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ without fixed points. We denote by $\frac{\partial}{\partial t}$ the vector field along the orbits generating ϕ

7.1.1. Flows and parametrisations. Let $f : X \rightarrow \mathbb{R}$ be a positive Hölder continuous function. The *reparametrization* of the flow ϕ by f is the flow $\phi^f = \{\phi_t^f\}_{t \in \mathbb{R}}$ on X generated, along the orbits, by the vector field $f \frac{\partial}{\partial t}$.

7.1.2. Livšic-cohomology classes. Two Hölder functions $f, g : X \rightarrow \mathbb{R}$ are *Livšic-cohomologous* if there exists $V : X \rightarrow \mathbb{R}$ of class C^1 in the flow's direction such that

$$f(x) - g(x) = \left. \frac{\partial}{\partial t} \right|_{t=0} V(\phi_t(x)).$$

Then one easily notices that:

- (1) If f and g are Livšic cohomologous then they have the same integral over any ϕ -invariant measure, and
- (2) If f and g are both positive and Livšic cohomologous, then the flows ϕ^f and ϕ^g are Hölder conjugate.

7.1.3. Periods and measures. Let O be the set of periodic orbits of ϕ . If $a \in O$ then its *period* as a $\{\phi_t^f\}$ periodic orbit is

$$\int_0^{p(a)} f(\phi_s(x)) ds$$

where $p(a)$ is the period of a for ϕ and $x \in a$. In particular, if $\widehat{\delta}_a$ is the probability measure invariant by the flow and supported by the orbit a , and if

$$\widehat{\delta}_a = \frac{\delta_a}{\langle \delta_a | 1 \rangle},$$

then

$$\langle \delta_a | f \rangle = \int_0^{p(a)} f(\phi_s(x)) ds \quad \text{and} \quad p(a) = \langle \delta_a | 1 \rangle.$$

In general, if μ is a ϕ -invariant measure on X and $f : X \rightarrow \mathbb{R}$ is a Hölder function, we will use the notation

$$\langle \mu | f \rangle = \int_X f d\mu.$$

Let μ be a ϕ -invariant probability measure on X and let ϕ^f be the reparametrization of ϕ by f . We define $\widehat{f.\mu}$ to be the probability measure

$$\widehat{f.\mu} = \frac{1}{\langle \mu | f \rangle} f.\mu.$$

Then the map $\mu \mapsto \widehat{f.\mu}$ induces a bijection from the space of ϕ -invariant probability measures to the space of ϕ^f -invariant probability measures. If $\widehat{\delta}_a^f$ is the unique ϕ_f invariant probability measure supported by a , then $\widehat{\delta}_a^f = \widehat{f.\delta_a}$. In particular, we have

$$\langle \widehat{\delta}_a^f | g \rangle = \frac{\langle \delta_a | f.g \rangle}{\langle \delta_a | f \rangle} \quad (27)$$

7.1.4. Entropy, pressure and equilibrium states. If $\psi = \{\psi_t\}_{t \in \mathbb{R}}$ is a flow on a metric space X and μ is a ψ -invariant probability measure on X , then we define $h(\psi, \mu)$ to be the metric entropy of ψ with respect to μ . The Abramov formula [1] relates the metric entropies of a flow and its reparameterization:

$$h(\phi^f, \widehat{f.\mu}) = \frac{1}{\int f d\mu} h(\phi, \mu). \quad (28)$$

Let \mathcal{M}^ϕ denote the set of ϕ -invariant probability measures. The *pressure* of a function $f : X \rightarrow \mathbb{R}$ is defined as

$$\mathbf{P}(\phi, f) = \sup_{m \in \mathcal{M}^\phi} \left(h(\phi, m) + \int_X f dm \right). \quad (29)$$

In particular,

$$h_{\text{top}}(\phi) = \mathbf{P}(\phi, 0)$$

is the *topological entropy* of the flow ϕ .

A measure $m \in \mathcal{M}^\phi$ on X such that

$$\mathbf{P}(\phi, f) = h(\phi, m) + \int_X f dm,$$

is called an *equilibrium state* of f .

An equilibrium state for the function $f \equiv 0$ is called a *measure of maximal entropy*.

Remark: The pressure $\mathbf{P}(\phi_t, f)$ only depends on the Livšic cohomology class of f .

The following lemma from Sambarino [51] is a consequence of the definition and the Abramov formula.

Lemma 7.1. (Sambarino [51, Lemma 2.4]) *If ϕ is a Hölder continuous flow on a compact metric space X and $f : X \rightarrow \mathbb{R}$ is a positive Hölder continuous function, then*

$$P(\phi, -hf) = 0$$

if and only if $h = h_{\text{top}}(\phi^f)$.

Moreover, if $h = h_{\text{top}}(\phi^f)$ and m is an equilibrium state of $-hf$, then $\widehat{f.m}$ is a measure of maximal entropy for the reparameterised flow ϕ^f .

7.2. Metric Anosov flows. We shall assume from now on that the flow $\{\phi_t\}_{t \in \mathbb{R}}$ is a topologically transitive metric Anosov flow on a compact metric space X (recall that metric Anosov flows are defined in Subsection §6.5).

7.2.1. Livšic's Theorem. Livšic [38] shows that the Livšic cohomology class of a Hölder function $f : X \rightarrow \mathbb{R}$ is determined by its periods:

Theorem 7.2. *If ϕ is a topologically transitive metric Anosov flow on a compact metric space X and $f : X \rightarrow \mathbb{R}$ is a Hölder function, then $\langle \delta_a | f \rangle = 0$ for every $a \in O$ if and only if f is Livšic cohomologous to zero.*

7.2.2. Coding. We say that the triplet (Σ_A, π, r) is a *Markov coding* for $\{\phi_t\}_{t \in \mathbb{R}}$ if Σ_A is a subshift of finite type, $\pi : \Sigma_A \rightarrow X$ and $r : \Sigma_A \rightarrow \mathbb{R}_+^*$ are Hölder continuous and the function $\pi_r : \Sigma_A \times \mathbb{R} \rightarrow X$ defined as

$$\pi_r(x, t) = \phi_t \pi(x)$$

verifies the following conditions:

- (i) π_r is surjective and Hölder,
- (ii) let $\sigma : \Sigma_A \rightarrow \Sigma_A$ be the shift and let $\hat{r} : \Sigma_A \times \mathbb{R} \rightarrow \Sigma_A \times \mathbb{R}$ be defined as $\hat{r}(x, t) = (\sigma x, t - r(x))$, then π_r is \hat{r} -invariant,
- (iii) $\pi_r : \Sigma_A \times \mathbb{R} / \hat{r} \rightarrow X$ is bounded-to-one and injective on a residual set which is of full measure for every ergodic invariant measure of total support (for σ_t^f),
- (iv) consider the translation flow $\sigma_t^r : \Sigma_A \times \mathbb{R} / \hat{r} \rightarrow \Sigma_A \times \mathbb{R} / \hat{r}$ then $\pi_r \sigma_t^r = \phi_t \pi_r$.

One has the following theorem of Bowen [12, 13].

Theorem 7.3. *A topologically transitive metric Anosov flow on a compact metric space admits a Markov coding.*

Remark: Bowen's original work is done in the setting of flows on smooth manifolds. Mañé [41, Section IV.9] generalizes Bowen's techniques to the setting of hyperbolic homeomorphisms on compact metric spaces. We use Mañé's formulation of the definition of a Markov coding

which also applies in our setting. Mañé also discusses the analogues of Theorems 7.4 and 7.6 in his setting.

7.3. Entropy and pressure for Anosov flows. The thermodynamic formalism of suspensions of subshifts of finite type extends thus to topologically transitive metric Anosov flows. For a positive Hölder function $f : X \rightarrow \mathbb{R}_+$ and $T \in \mathbb{R}$, we define

$$R_T(f) = \{a \in O \mid \langle \delta_a | f \rangle \leq T\}.$$

Observe that $R_T(f)$ only depends on the cohomology class of f .

7.3.1. Entropy. For a topologically transitive metric Anosov flow Bowen [12] showed:

Proposition 7.4. *The topological entropy of a topologically transitive metric Anosov flow $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ on a compact metric space X is finite and positive. Moreover,*

$$h_{\text{top}}(\phi) = \lim_{T \rightarrow \infty} \frac{1}{T} \log \# \{a \in O \mid p(a) \leq T\}.$$

In particular, for a nowhere vanishing Hölder continuous function f ,

$$h_f = \lim_{T \rightarrow \infty} \frac{1}{T} \log \# (R_T(f)) = h_{\text{top}}(\phi^f)$$

is finite and positive.

7.3.2. Pressure. The Markov coding may be used to show the pressure of a Hölder function $g : X \rightarrow \mathbb{R}$ is finite and that there is a unique equilibrium state of g . We shall denote this equilibrium state as m_g .

Theorem 7.5. [BOWEN–RUELLE [14]] *Let $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ be a topologically transitive metric Anosov flow on a compact metric space X and let $g : X \rightarrow \mathbb{R}$ be a Hölder function, then there exists a unique equilibrium state m_g for g . Moreover, if $f : X \rightarrow \mathbb{R}$ is a Hölder function such that $m_f = m_g$, then $f - g$ is Livšic cohomologous to a constant.*

The pressure function has the following alternative formulation in this setting (see Bowen–Ruelle [14]):

$$\mathbf{P}(\phi, g) = \lim_{T \rightarrow \infty} \frac{1}{T} \log \left(\sum_{a \in R_T(1)} e^{\langle \delta_a | g \rangle} \right). \quad (30)$$

7.3.3. *Measure of maximal entropy.* We have the following equidistribution result of Bowen [12].

Theorem 7.6. *A topologically transitive metric Anosov flow $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ on a compact metric space X has a unique probability measure μ_ϕ of maximal entropy. Moreover,*

$$\mu_\phi = \lim_{T \rightarrow \infty} \left(\frac{1}{\#R_T(1)} \sum_{a \in R_T(1)} \widehat{\delta}_a \right). \quad (31)$$

The probability measure of maximal entropy for ϕ is called the *Bowen–Margulis measure* of ϕ .

7.4. Intersection and renormalised intersection.

7.4.1. *Intersection.* Let $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ be a topologically transitive metric Anosov flow on a compact metric space X . Consider a positive Hölder function $f : X \rightarrow \mathbb{R}_+$ and a continuous function $g : X \rightarrow \mathbb{R}$. We define the *intersection of f and g* as

$$\mathbf{I}(f, g) = \int \frac{g}{f} d\mu_{\phi^f},$$

where μ_{ϕ^f} is the Bowen–Margulis measure of the flow ϕ^f . We also have the following two alternative ways to define the intersection

$$\mathbf{I}(f, g) = \lim_{T \rightarrow \infty} \left(\frac{1}{\#R_T(f)} \sum_{a \in R_T(f)} \frac{\langle \delta_a | g \rangle}{\langle \delta_a | f \rangle} \right) \quad (32)$$

$$\mathbf{I}(f, g) = \frac{\int g \, dm_{-h_f.f}}{\int f \, dm_{-h_f.f}} \quad (33)$$

where h_f is the topological entropy of ϕ^f , and $m_{-h_f.f}$ is the equilibrium state of $-h_f.f$. The first equality follows from Theorem 7.6 and Equation (27), the second equality follows from the second part of Lemma 7.1.

Since $\langle \delta_a | f \rangle$ depends only on the Livšic cohomology class of f and $\langle \delta_a | g \rangle$ depends only on the Livšic cohomology class of g , the intersection $\mathbf{I}(f, g)$ depends only on the Livšic cohomology classes of f and g .

7.4.2. *A lower bound on the renormalized intersection.* For two positive Hölder functions $f, g : X \rightarrow \mathbb{R}_+$ define the *renormalized intersection* as

$$\mathbf{J}(f, g) = \frac{h_g}{h_f} \mathbf{I}(f, g),$$

where h_f and h_g are the topological entropies of ϕ^f and ϕ^g . Uniqueness of equilibrium states together with the definition of the pressure imply the following proposition.

Proposition 7.7. *If $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ is a topologically transitive metric Anosov flow on a compact metric space X , and $f : X \rightarrow \mathbb{R}_+$ and $g : X \rightarrow \mathbb{R}_+$ are positive Hölder functions, then*

$$\mathbf{J}(f, g) \geq 1.$$

Moreover, $\mathbf{J}(f, g) = 1$ if and only if $h_f f$ and $h_g g$ are Livšic cohomologous.

Proof. Since $\mathbf{P}(\phi, -h_g g) = 0$,

$$h_g \int g \, dm \geq h(\phi, m)$$

for all $m \in \mathcal{M}^\phi$ and, by Theorem 7.5, equality holds only for $m = m_{-h_g g}$, the equilibrium state of $-h_g g$. Applying the analogous inequality for $m_{-h_f f}$, together with Abramov's formula (28) and Lemma 7.1, one sees that

$$h_g \int g \, dm_{-h_f f} \geq h(\phi, m_{-h_f f}) = h_f \int f \, dm_{-h_f f},$$

which implies that $\mathbf{J}(f, g) \geq 1$.

If $\mathbf{J}(f, g) = 1$, then $m_{-h_g g} = m_{-h_f f}$ and thus, applying theorem 7.5, one sees that $h_g g - h_f f$ is Livšic cohomologous to a constant c . Thus,

$$0 = \mathbf{P}(\phi, -h_g g) = \mathbf{P}(\phi, -h_f f - c) = \mathbf{P}(\phi, -h_f f) - c = -c.$$

Therefore, $h_g g$ and $h_f f$ are Livšic cohomologous. \square

7.5. Variation of the pressure and the pressure metric.

7.5.1. *First and second derivatives.* Define the *variance* of a function g with respect to f as

$$\text{Var}(g, m_f) = \lim_{T \rightarrow \infty} \frac{1}{T} \int \left(\int_0^T g(\phi_s(x)) \, ds \right)^2 dm_f(x),$$

where m_f is the equilibrium state of f . We shall omit the background flow in the notation of the pressure function and simply write

$$\mathbf{P}(\cdot) = \mathbf{P}(\phi, \cdot).$$

Proposition 7.8. (PARRY-POLLICOTT [44, Prop. 4.10, 4.11], RUELLE [49]) *Suppose that $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ is a topologically transitive metric Anosov flow on a compact metric space X , and $f : X \rightarrow \mathbb{R}$ and $g : X \rightarrow \mathbb{R}$ are Hölder functions. If m_f is the equilibrium state of f , then*

- (1) The function $t \mapsto \mathbf{P}(f + tg)$ is analytic,
- (2) The first derivative is given by

$$\left. \frac{\partial \mathbf{P}(f + tg)}{\partial t} \right|_{t=0} = \int g \, dm_f,$$

- (3) If $\int g \, dm_f = 0$ then

$$\left. \frac{\partial^2 \mathbf{P}(f + tg)}{\partial t^2} \right|_{t=0} = \text{Var}(g, m_f),$$

- (4) If $\text{Var}(g, m_f) = 0$ then g is Livšic cohomologous to zero.

7.5.2. *Pressure zero functions.* Let $C^h(X)$ be the set of real valued Hölder continuous functions on X . Define $\mathcal{P}(X)$ to be the set of Livšic cohomology classes of pressure zero Hölder functions on X , i.e.,

$$\mathcal{P}(X) = \{ \Phi \in C^h(X) : \mathbf{P}(\Phi) = 0 \} / \sim.$$

The tangent space of $\mathcal{P}(X)$ at Φ is the set

$$\mathbf{T}_\Phi \mathcal{P}(X) = \ker d_\Phi \mathbf{P} = \left\{ g \in C^h(X) \mid \int g \, dm_\Phi = 0 \right\} / \sim$$

where m_Φ is the equilibrium state of Φ . Define the *pressure norm* of $g \in \mathbf{T}_\Phi \mathcal{P}(X)$ as

$$\|g\|_{\mathbf{P}}^2 = -\frac{\text{Var}(g, m_\Phi)}{\int \Phi \, dm_\Phi}.$$

One has the following computation.

Lemma 7.9. *Let $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ be a topologically transitive metric Anosov flow on a compact metric space X . If $\{\Phi_t\}_{t \in (-1,1)}$ is a smooth one parameter family contained in $\mathcal{P}(X)$, then*

$$\|\dot{\Phi}_0\|_{\mathbf{P}}^2 = \frac{\int \ddot{\Phi}_0 \, dm_{\Phi_0}}{\int \Phi_0 \, dm_{\Phi_0}}.$$

Proof. As $\mathbf{P}(\Phi_t) = 0$ by differentiating twice we get the equation

$$\mathbf{D}^2 \mathbf{P}(\Phi_0)(\dot{\Phi}_0, \dot{\Phi}_0) + \mathbf{D} \mathbf{P}(\Phi_0)(\ddot{\Phi}_0) = 0 = \text{Var}(\dot{\Phi}_0, m_{\Phi_0}) + \int \ddot{\Phi}_0 \, dm_{\Phi_0}.$$

Thus

$$\|\dot{\Phi}_0\|_{\mathbf{P}}^2 = -\frac{\text{Var}(\dot{\Phi}_0, m_\Phi)}{\int \Phi_0 \, dm_{\Phi_0}} = \frac{\int \ddot{\Phi}_0 \, dm_{\Phi_0}}{\int \Phi_0 \, dm_{\Phi_0}}.$$

□

We then have the following relation, generalizing Bonahon [11], between the renormalized intersection and the pressure metric.

Proposition 7.10. *Let $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ be a topologically transitive metric Anosov flow on a compact metric space X . If $\{f_t : X \rightarrow \mathbb{R}_+\}_{t \in (-1,1)}$ is a one-parameter family of positive Hölder functions and $\Phi_t = -h_{f_t} f_t$ for all $t \in (-1,1)$, then*

$$\left. \frac{\partial^2}{\partial t^2} \right|_{t=0} \mathbf{J}(f_0, f_t) = \|\dot{\Phi}_0\|_{\mathbf{P}}^2.$$

Proof. By Equation (33) and the definition of the renormalised intersection, we see that

$$\mathbf{J}(f_0, f_t) = \frac{\int \Phi_t \, dm_{\Phi_0}}{\int \Phi_0 \, dm_{\Phi_0}}.$$

Differentiating twice and applying the previous lemma, one obtains

$$\left. \frac{\partial^2}{\partial t^2} \right|_{t=0} \mathbf{J}(f_0, f_t) = \frac{\int \ddot{\Phi}_0 \, dm_{\Phi_0}}{\int \Phi_0 \, dm_{\Phi_0}} = \|\dot{\Phi}_0\|_{\mathbf{P}}^2$$

which completes the proof. \square

7.6. Analyticity of entropy, pressure and intersection. We now show that pressure, entropy and intersection vary analytically for analytic families of positive Hölder functions.

Proposition 7.11. *Let $\phi = \{\phi_t\}_{t \in \mathbb{R}}$ be a topologically transitive metric Anosov flow on a compact metric space X . Let $\{f_u : X \rightarrow \mathbb{R}\}_{u \in D}$ and $\{g_v : X \rightarrow \mathbb{R}\}_{v \in D}$ be two analytic families of Hölder functions. Then the function*

$$u \mapsto \mathbf{P}(f_u)$$

is analytic. Moreover, if the family $\{f_u\}_{u \in D}$ consists of positive functions then the functions

$$u \mapsto h_u = h_{f_u}, \tag{34}$$

$$(u, v) \mapsto \mathbf{I}(f_u, g_v). \tag{35}$$

are both analytic.

Proof. Since the Pressure function is analytic on the space of Hölder functions, see Parry-Pollicott [44, Prop. 4.7] or Ruelle [49, Cor. 5.27], the function $u \mapsto \mathbf{P}(f_u)$ is analytic.

Since the family $\{f_u\}_{u \in D}$ consists of positive functions, Proposition 7.8 implies that

$$\left. \frac{d}{dt} \right|_{t=h_u} \mathbf{P}(-tf_u) = -h_u \int f_u \, dm_{-h_u f_u} < 0.$$

Thus an application of the Implicit Function Theorem yields that $u \mapsto h_u$ is analytic.

We also get that

$$(u, v, t) \mapsto \left. \frac{d}{dt} \right|_{t=0} \mathbf{P}(-h_u f_u + t g_v),$$

is analytic. But, applying Proposition 7.8 again

$$\left. \frac{d}{dt} \right|_{t=0} \mathbf{P}(-h_u f_u + t g_v) = \int g_v dm_{-h_u f_u}.$$

Thus the function $(u, v) \mapsto \int g_v dm_{-h_u f_u}$ is analytic. Similarly (taking $g_v = f_u$), the function $u \mapsto \int f_u dm_{-h_u f_u}$ is analytic. Thus, we get, by Equation (33) that

$$(u, v) \mapsto \mathbf{I}(f_u, g_v) = \frac{\int g_v dm_{-h_u f_u}}{\int f_u dm_{-h_u f_u}},$$

is analytic. □

8. ANALYTIC VARIATION OF THE DYNAMICS

In order to apply the thermodynamic formalism we need to check that if $\{\rho_u\}_{u \in M}$ is an analytic family of convex Anosov representations, then the associated limit maps and reparameterizations of the Gromov geodesic flow may be chosen to vary analytically, at least locally. Our proofs generalize earlier proofs of the stability of Anosov representations, see Labourie [32, Proposition 2.1] and Guichard-Wienhard [24, Theorem 5.13], and that the limit maps vary continuously, see Guichard-Wienhard [24, Theorem 5.13]. In the process, we also see that our limit maps are Hölder.

We will make use of the following concrete description of the analytic structure of $\text{Hom}(\Gamma, \mathbf{G})$. Suppose that Γ is a word hyperbolic group, hence finitely presented, and let $\{g_1, \dots, g_m\}$ be a generating set for Γ . If \mathbf{G} is a real semi-simple Lie group, then $\text{Hom}(\Gamma, \mathbf{G})$ has the structure of a real algebraic variety. An *analytic family* $\beta : M \rightarrow \text{Hom}(\Gamma, \mathbf{G})$ of homomorphisms of Γ into \mathbf{G} is a map with domain an analytic manifold M so that, for each i , the map $\beta_i : M \rightarrow \mathbf{G}$ given by $\beta_i(u) = \beta(u)(g_i)$ is real analytic. If $\mathbf{G}^{\mathbb{C}}$ is a complex Lie group, we may similarly define complex analytic families of homomorphisms of a complex analytic manifold into $\text{Hom}(\Gamma, \mathbf{G}^{\mathbb{C}})$.

We first show that the limit maps of an analytic family of Anosov homomorphisms vary analytically. We begin by setting our notation. If $\alpha > 0$, X is a compact metric space and D and M are real-analytic manifolds, then we let $C^\alpha(X, M)$ denote the space of α -Hölder maps of X into M and let $C^\omega(D, M)$ denote the space of real analytic maps of

D into M . If D and M are complex analytic manifolds, we will abuse notation by letting $C^\omega(D, M)$ denote the space of complex analytic maps.

Theorem 8.1. *Let G be a real semi-simple Lie group and let P be a parabolic subgroup of G . Let $\{\rho_u\}_{u \in D}$ be a real analytic family of homomorphisms of Γ into G parameterized by a disk D about 0. If ρ_0 is a (G, P) -Anosov homomorphism with limit map $\xi_0 : \partial_\infty \Gamma \rightarrow G/P$, then there exists a sub-disk D_0 of D (containing 0), $\alpha > 0$ and a continuous map*

$$\xi : D_0 \times \partial_\infty \Gamma \rightarrow G/P$$

with the following properties:

- (1) *If $u \in D_0$, then ρ_u is a (G, P) -Anosov homomorphism with α -Hölder limit map $\xi_u : \partial_\infty \Gamma \rightarrow G/P$ given by $\xi_u(\cdot) = \xi(u, \cdot)$.*
- (2) *If $x \in \partial_\infty \Gamma$, then $\xi_x : D_0 \rightarrow G/P$ given by $\xi_x = \xi(\cdot, x)$ is real analytic*
- (3) *The map from $\partial_\infty \Gamma$ to $C^\omega(D_0, G/P)$ given by $x \mapsto \xi_x$ is α -Hölder.*
- (4) *The map from D_0 to $C^\alpha(\partial_\infty \Gamma, G/P)$ given by $u \mapsto \xi_u$ is real analytic.*

Recall, from Section 6.1, that given a convex Anosov representation $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$, we constructed a geodesic flow $U_\rho \Gamma$ which is a reparameterization of the Gromov geodesic flow $U_0 \Gamma$. In this section, we show that given a real analytic family of convex Anosov representations, one may choose the parameterizing functions to vary analytically.

Proposition 8.2. *Let $\{\rho_u\}_{u \in D}$ be a real analytic family of convex Anosov homomorphisms of Γ into $\mathrm{SL}_m(\mathbb{R})$ parameterized by a disk about 0. Then, there exists a sub-disk D_0 about 0 and a real analytic family $\{f_u : U_0 \Gamma \rightarrow \mathbb{R}\}_{u \in D_0}$ of positive Hölder functions such that the reparametrisation of $U_0 \Gamma$ by f_u is Hölder conjugate to $U_{\rho_u} \Gamma$ for all $u \in D_0$.*

We actually derive Theorem 8.1 from the following more general statement for complex analytic families by complexifying.

Theorem 8.3. *Let $G^\mathbb{C}$ be a complex semi-simple Lie group and let $P^\mathbb{C}$ be a parabolic subgroup of $G^\mathbb{C}$. Let $\{\rho_u\}_{u \in D^\mathbb{C}}$ be a complex analytic (or C^k for $k > 1$) family of homomorphisms of Γ into G parameterized by a complex disk $D^\mathbb{C}$ about 0. If ρ_0 is a $(G^\mathbb{C}, P^\mathbb{C})$ -Anosov homomorphism with limit map $\xi_0 : \partial_\infty \Gamma \rightarrow G^\mathbb{C}/P^\mathbb{C}$, then there exists a sub-disk $D_0^\mathbb{C}$ of $D^\mathbb{C}$ (containing 0), $\alpha > 0$ and a continuous map*

$$\xi : D_0^\mathbb{C} \times \partial_\infty \Gamma \rightarrow G/P$$

with the following properties:

- (1) If $u \in D_0^{\mathbb{C}}$, then ρ_u is a $(G^{\mathbb{C}}, P^{\mathbb{C}})$ -Anosov homomorphism with α -Hölder limit map $\xi_u : \partial_{\infty}\Gamma \rightarrow G^{\mathbb{C}}/P^{\mathbb{C}}$ given by $\xi_u(\cdot) = \xi(u, \cdot)$.
- (2) If $x \in \partial_{\infty}\Gamma$, then $\xi_x : D_0^{\mathbb{C}} \rightarrow G^{\mathbb{C}}/P^{\mathbb{C}}$ given by $\xi_x = \xi(\cdot, x)$ is complex analytic (respectively C^k)
- (3) The map from $\partial_{\infty}\Gamma$ to $C^{\omega}(D_0^{\mathbb{C}}, G^{\mathbb{C}}/P^{\mathbb{C}})$ (respectively $C^k(D_0^{\mathbb{C}}, G^{\mathbb{C}}/P^{\mathbb{C}})$) given by $x \mapsto \xi_x$ is α -Hölder.
- (4) The map from $D_0^{\mathbb{C}}$ to $C^{\alpha}(\partial_{\infty}\Gamma, G^{\mathbb{C}}/P^{\mathbb{C}})$ given by $u \mapsto \xi_u$ is complex analytic (respectively C^{k-1}).

We now show that Theorem 8.1 follows from Theorem 8.3.

Proof of Theorem 8.1: Observe that a (G, P) -Anosov representation is automatically a $(G_{\mathbb{C}}, P_{\mathbb{C}})$ -Anosov representation. On a sub-disk D_1 of D , containing 0, one may extend $\{\rho_u\}_{u \in D_1}$ to a complex analytic family $\{\rho_u\}_{u \in D_1^{\mathbb{C}}}$ of homomorphisms of Γ into $G^{\mathbb{C}}$ defined on the complexification $D_1^{\mathbb{C}}$ of D_1 . The map $\xi : D_0^{\mathbb{C}} \times \partial_{\infty}\Gamma \rightarrow G^{\mathbb{C}}/P^{\mathbb{C}}$ provided by Theorem 8.3 restricts to a map $\xi|_{D_0} : D_0 \times \partial_{\infty}\Gamma \rightarrow G/P$ with the properties required by Theorem 8.1. Notice that the real analyticity in properties (2) and (4) follows from the fact that restrictions of complex analytic functions to real analytic submanifolds are real analytic.

8.1. Transverse regularity. The proof of Theorem 8.3 makes use of a version of the C^r -section Theorem of Hirsch-Pugh-Shub [27, Theorem 3.8] which keeps track of the transverse regularity of the resulting section.

8.1.1. Definitions. We begin by introducing the terminology necessary to keep track of the desired transverse regularity.

Definition 8.4. [TRANSVERSELY REGULAR FUNCTIONS] *Let $D^{\mathbb{C}}$ be a complex disk, let X be a compact metric space and let M be a complex analytic manifold. A continuous function $f : D^{\mathbb{C}} \times X \rightarrow M$ is transversely complex analytic if X is a complex analytic manifold and*

- *For every $x \in X$, the function $f_x : D^{\mathbb{C}} \rightarrow M$ given by $f_x(\cdot) = f(\cdot, x)$ is complex analytic, and*
- *The function from X to $C^{\omega}(D^{\mathbb{C}}, M)$ given by $x \mapsto f_x$ is continuous.*

Furthermore, we say that f is α -Hölder (or Lipschitz) transversely complex analytic if the map in (2) is α -Hölder (or Lipschitz).

If we replace $D^{\mathbb{C}}$ with a real disk D and M with a real analytic manifold (or C^k -manifold), we can similarly define α -Hölder (or Lipschitz) transversely real analytic (or C^k) functions by requiring that the

maps in (1) are real analytic (or C^k) and requiring in (2) that the map from X to $C^\omega(D, M)$ (or to $C^p(D, M)$ for all $p \leq k$) is α -Hölder (or Lipschitz).

Similarly, we define transverse regularity of bundles in terms of the transverse regularity of their trivializations.

Definition 8.5. [TRANVERSALLY REGULAR BUNDLES] *Suppose that the fiber of a bundle $\pi : E \rightarrow D^\mathbb{C} \times X$ is a complex analytic manifold M . We say that E is transversely complex analytic if it admits a family of trivializations of the form $\{D^\mathbb{C} \times U_\alpha \times M\}$ (where $\{U_\alpha\}$ is an open cover of X) so that the corresponding change of coordinate functions are transversely complex analytic. We similarly say $\pi : E \rightarrow D^\mathbb{C} \times X$ is α -Hölder (or Lipschitz) transversely complex analytic if it admits a family of trivializations which are α -Hölder (or Lipschitz) transversely complex analytic.*

In this case, a section of E is α -Hölder (or Lipschitz) transversely complex analytic, if in any of the trivializations the corresponding map to M is α -Hölder (or Lipschitz) transversely complex analytic

Clearly, if we replace $D^\mathbb{C}$ with a real disk D and M with a real analytic manifold (or C^k -manifold), then we can similarly define α -Hölder (or Lipschitz) transversely real analytic (or C^k) bundles and sections.

8.1.2. A C^r -Section Theorem. We are now ready to state the result we will use in the proof of Theorem 8.3. See Hirsch-Pugh-Shub [27, Theorem 3.8] and Shub [53, Theorem 5.18] for complete treatments of the C^r -Section Theorem.

Theorem 8.6. *Let X be a compact metric space and let M be a complex analytic (or C^k) manifold. Suppose that $\pi : E \rightarrow D^\mathbb{C} \times X$ (or $\pi : E \rightarrow D \times X$) is a Lipschitz transversely complex analytic (or C^k) bundle with fibre M . Let $f : X \rightarrow X$ be a Lipschitz homeomorphism and let F be a Lipschitz transversely complex analytic (or C^k) bundle automorphism of E lifting $\text{id} \times f$.*

Suppose that σ_0 is a section of the restriction of E over $\{0\} \times X$ which is fixed by F and that F contracts along σ_0 . Then then there exists a neighborhood U of 0 in $D^\mathbb{C}$ (or in D), a positive number $\alpha > 0$, and a α -Hölder transversely complex analytic (or C^k) section η over $D_0^\mathbb{C} \times X$ (or $D_0 \times X$) and a neighborhood B of $\eta(U \times X)$ in $\pi^{-1}(U \times X)$ such that

- (1) F fixes η ,
- (2) F contracts E along η ,
- (3) $\eta|_{\{0\} \times X} = \sigma_0$, and

- (4) if $\nu : U \times X \rightarrow E$ is a section so that $\nu(U \times X) \subset B$ and ν is fixed by F , then $\nu = \eta$.

We recall that if U is a subset of $D^{\mathbb{C}}$ (or of D), then a section σ over $U \times X$ is *fixed* by F if $F(\sigma(u, x)) = \sigma(u, f(x))$. In such a case, we further say that F *contracts* along σ if there exists a continuously varying fibrewise Riemannian metric $\|\cdot\|$ on the bundle E such that if

$$D^f F_{\sigma(u, x)} : T_{\sigma(u, x)} \pi^{-1}(u, x) \rightarrow T_{\sigma(u, f(x))} \pi^{-1}(u, f(x))$$

is the fibrewise tangent map, then

$$\|D^f F_{\sigma(u, x)}\| < 1.$$

We will derive Theorem 8.6 from the following version of the C^r -section theorem which is a natural generalization of the ball bundle version of the C^r -section theorem in Shub [53, Theorem 5.18].

Theorem 8.7. [FIXED SECTIONS] *Let X be a compact metric space equipped with a Lipschitz homeomorphism $f : X \rightarrow X$. Suppose that $\pi : W \rightarrow D^{\mathbb{C}} \times X$ (or $\pi : W \rightarrow D \times X$) is a Lipschitz transversely complex analytic (or C^k) Banach space bundle, $B \subset W$ is the closed ball sub-bundle of radius r , and F is a Lipschitz transversely complex analytic (or C^k) bundle morphism of B lifting the homeomorphism $\text{id} \times f : D \times X \rightarrow X$.*

If F contracts B , then there exists a unique α -Hölder transversely complex analytic (or C^k) section η of B which is fixed by F (for some $\alpha > 0$).

Notice that we have not assumed that F is either linear or bijective.

Proof. Let σ be the zero section of B . Observe that σ has the same regularity as W and is thus transversally complex analytic (or C^k).

We first assume that $\pi : W \rightarrow D \times M$ is a Lipschitz transversely C^k -bundle. The existence of a unique continuous fixed section η is a standard application of the contraction mapping theorem. Explicitly, for all $(u, x) \in D \times X$, we let

$$\eta(u, x) = \lim_{n \rightarrow \infty} F^n(\sigma(u, f^{-n}(x))). \quad (36)$$

We must work harder to show that η is α -Hölder transversely complex analytic (or C^k). We first assume that W is transversely C^k —and so is σ —and obtain the C^k -regularity of η . For any $p \in \mathbb{N}$, let Γ^p be the Lipschitz Banach bundle over X whose fibers over a point $x \in X$ is the Banach space Γ_x^p of C^p -sections of the restriction of W to $D \times \{x\}$. Let B^p be the sub-bundle whose fiber B_x^p over x is the set of those sections with values in B .

Notice that each fiber B_x^p can be identified with $C^p(D \times \{x\}, B_0)$ where B_0 is a closed ball of radius r in the fiber Banach space. Let F_*^p be the bundle automorphism of Γ_p given by

$$[F_*^p(\nu)](u, x) = F(\nu(u, f^{-1}(x)))$$

We can renormalise the metric on D , so that all the derivatives of F of order n (with $p \geq n \geq 1$) along D are arbitrarily small. Thus after this renormalisation the metric on D , F_*^p is contracting, since F is contracting. We now apply Theorem 3.8 of Hirsch-Pugh-Shub [27] (see also Shub [53, Theorem 5.18]) to obtain an invariant α -Hölder section ω . By the uniqueness of fixed sections, we see that

$$\eta(u, x) = \omega(x)(u)$$

for all $1 \leq p \leq k$. It follows that η is α -Hölder transversely C^k .

Now suppose that $\pi : E \rightarrow D^{\mathbb{C}} \times X$ is Lipschitz transversely complex analytic bundle. We see, from the above paragraph, that there exists a unique α -Hölder transversely C^k section η_k for all k . By the uniqueness η_k is independent of k and we simply denote it by η . Then, by Formula (36), for all $x \in X$, $\eta|_{D^{\mathbb{C}} \times \{x\}}$ is a C^k -limit of a sequence of complex analytic sections for all k , hence is complex analytic itself. It follows that η is α -Hölder transversely complex analytic. \square

We now notice that one may identify a neighborhood of the section σ_0 in the statement of Theorem 8.6 with a ball sub-bundle of a vector bundle. We first prove the statement we need assuming the existence of a section defined in a neighborhood of $\{0\} \times X$.

Lemma 8.8. *Let $\pi : E \rightarrow D^{\mathbb{C}} \times X$ (or $\pi : E \rightarrow D \times X$) be a transversely complex analytic (or C^k) bundle over $D^{\mathbb{C}} \times X$ and let σ be a section of E defined over $D^{\mathbb{C}} \times X$ (or $D \times X$). Then there exists*

- a neighborhood U of zero in D ,
- a transversely complex analytic (or C^k) closed ball bundle B of radius R in a complex vector bundle F ,
- a transversely complex analytic (or C^k) bijective map from B to a neighborhood of the graph of σ_0 so that
 - the graph of $\sigma_0 = \sigma|_{\{0\} \times X}$ is in the image of the graph of the zero section,
 - the fibrewise metric on B coincides along σ_0 with the fibrewise metric on E .

Proof. Let Z be the transversely complex analytic (or C^k) vector bundle over $U \times X$ so that the fibre over the point (u, x) is given by $T_{\sigma(u, x)}(\pi^{-1}(u, x))$. We equip Z with a Riemannian metric coming from E and let $B(r)$ be the closed ball sub-bundle of radius $r > 0$.

Using the trivializations, we can find, after possibly further restricting U ,

- a finite cover $\{O_i\}_{1 \leq i \leq n}$ of X ,
- an open neighborhood W of the graph of σ ,
- transversely holomorphic bundle maps ϕ_i defined on $W|_{U \times O_i}$ with values in $Z|_{U \times O_i}$ so that for all $(u, x) \in U \times O_i$

$$\begin{aligned} \phi_i(\sigma(u, x)) &= 0 \in \mathsf{T}_{\sigma(u, x)}(\pi^{-1}(u, x)) \\ \mathsf{D}_{\sigma(u, x)}^f \phi_i &= \text{Id}. \end{aligned} \quad (37)$$

Let $\{\psi_i\}_{1 \leq i \leq n}$ be a partition of unity on X subordinate to $\{O_i\}_{1 \leq i \leq n}$ and, for each i , let $\hat{\psi}_i : W \rightarrow [0, 1]$ be obtained by composing the projection of W to X with ψ_i . One may then define $\Phi : W \rightarrow Z$ by letting

$$\Phi = \sum_{i=1}^n \hat{\psi}_i \phi_i.$$

Since $\hat{\psi}_i$ is constant in the direction of D , Φ is transversely holomorphic,

$$\Phi(\sigma(u, x)) = 0 \quad \text{and} \quad \mathsf{D}_{\sigma(y)}^f \Phi = \text{Id}.$$

It then follows from the implicit function theorem, that one may further restrict U and W so that Φ is a transversely holomorphic isomorphism of W with $B(r)$ for some r . \square

We now obtain a version of Lemma 8.8 where we only assume the existence of a section defined over $\{0\} \times X$.

Lemma 8.9. *Let $\pi : E \rightarrow D^{\mathbb{C}} \times X$ (or $\pi : E \rightarrow D \times X$) be a transversely complex analytic (or C^k) bundle over $D^{\mathbb{C}} \times X$ and let σ_0 a section of E defined over $\{0\} \times X$. Then there exists*

- a neighborhood U of zero in D ,
- a transversely complex analytic (or C^k) closed ball bundle B of radius R in a complex (or real) vector bundle V ,
- a transversely complex analytic (or C^k) bijective map from B to a neighborhood of the graph of σ_0 so that
 - the graph of σ_0 is in the image of the graph of the zero section,
 - the fibrewise metric on B coincide along σ_0 with the fibrewise metric on E .

Proof. By Lemma 8.8, it suffices to extend the section σ_0 to a section σ defined over $U \times X$ where U is a neighborhood of 0 in $D^{\mathbb{C}}$ (or in D). Composing π with the projection $\pi_2 : D^{\mathbb{C}} \times X \rightarrow X$ (or the projection $\pi_2 : D \times X \rightarrow X$), we may consider the bundle $\pi_2 \circ \pi : E \rightarrow X$.

Then σ_0 is a section of $\pi_2 \circ \pi$. We now apply the previous Lemma, where the disk is 0-dimensional, to identify, in a complex analytic way, a neighborhood of the graph of σ_0 with a ball bundle B in a vector bundle F over X .

Now π restricts to a bundle morphism from $\pi \circ \pi_2 : B \rightarrow X$ to $\pi_2 : D^{\mathbb{C}} \times X \rightarrow X$ (or $\pi_2 : D \times X \rightarrow X$) which is a fiberwise complex analytic (or C^k) submersion and whose fiberwise derivatives vary continuously. Let W be a linear sub-bundle of F , so that if W_x and F_x are the fibers over $x \in X$, then

$$\mathbb{T}(\pi^{-1}(0, x)) \oplus W_x = F_x.$$

Thus, after further restricting B , π becomes a fiberwise complex analytic injective local diffeomorphism from $W \cap B$ to $D^{\mathbb{C}} \times X$ (or $D \times X$) whose fiberwise derivatives vary continuously.

Applying the Implicit Function Theorem (with parameter), we obtain a neighborhood U of 0 and a map $\sigma : U \times X \rightarrow B$ which is fiberwise complex analytic (or C^k) and whose fiberwise derivatives varies continuously, so that $\pi \circ \sigma = \text{Id}$. Thus σ is the desired section of E . \square

Theorem 8.6 now follows from Theorem 8.7 and Lemma 8.9.

Proof of Theorem 8.6: Let V be the complex (or real) vector bundle provided by Lemma 8.9. We know that $\|\mathbf{D}_{\sigma_0(x)}^f F\| < 1$ for all x in X . After further restraining U and choosing r small enough, we may assume by continuity that for all y in $B(r)$, $\|\mathbf{D}_y^f F\| < K < 1$.

After further restricting U , we may assume that for all $u \in U$ and $x \in X$, we have

$$\|F(\sigma(u, x)) - \sigma(u, f(x))\| \leq (1 - K)r,$$

In particular, if $y \in B(r)$ is in the fiber over (u, x) ,

$$\begin{aligned} \|F(y) - \sigma(u, f(x))\| &\leq \|F(y) - F(\sigma(u, x))\| \\ &\quad + \|F(\sigma(u, x)) - \sigma(u, f(x))\| \\ &\leq Kr + (1 - K)r = r. \end{aligned}$$

Thus F maps $B(r)$ to itself and is contracting. We can therefore apply Theorem 8.7 to complete the proof.

8.1.3. *Regularity in $C^\alpha(X, M)$.* The following lemma shows that transverse regularity of a continuous function $f : D \times X \rightarrow M$ implies regularity of the associated map of D into $C^\alpha(X, M)$.

Let X be a compact metric space and let M be a complex analytic (or C^k) manifold. If U is an open subset of M and V is a relatively compact open subset of X , then let

$$\mathcal{W}(U, V) = \{g \in C^\alpha(X, M) \mid \overline{g(V)} \subset U\}.$$

We will say that a map f from D to $C^\alpha(X, M)$ is *complex analytic* (or C^k) if for any U and V as above and any complex analytic function $\phi : U \rightarrow \mathbb{C}$ (or C^k function $\phi : U \rightarrow \mathbb{R}$), the function f^ϕ defined on $f^{-1}(\mathcal{W}(U, V))$, by

$$f^\phi(x) = \phi \circ f(x),$$

with values in $C^\alpha(V, \mathbb{C})$ (or $C^\alpha(V, \mathbb{R})$ is complex analytic (or C^k).

Lemma 8.10. *Suppose that $f : D \times X \rightarrow M$ is α -Hölder transversely C^k , then the map \hat{f} from D to $C^\alpha(X, M)$ given by $u \rightarrow f_u$ where $f_u(\cdot) = f(u, \cdot)$ is C^{k-1} .*

Similarly, if $f : D^\mathbb{C} \times X \rightarrow M$ is α -Hölder transversely complex analytic, then the map \hat{f} from $D^\mathbb{C}$ to $C^\alpha(X, M)$ is complex analytic.

Proof. We first give the proof in the case that $M = \mathbb{C}$ (or $M = \mathbb{R}$). Let $\|\cdot\|_k$ be the C^k norm on $C^k(D, M)$ and let $\|\cdot\|_\alpha$ be the Hölder norm on $C^\alpha(X, M)$. If D is dimension n , then for any multi-index $j = (j_1, j_2, \dots, j_n)$, we define $\partial^j f = \partial_{u_1}^{j_1} \dots \partial_{u_n}^{j_n} f$. We further let $|j| = j_1 + \dots + j_n$. Then for $f \in C^k(D, M)$, $0 \leq i \leq k$, the i^{th} derivative of f is the collection of functions $D^i f = (\partial^j f)_{|j|=i}$. Then

$$\|f\|_k = \sum_{|j| \leq k} \sup_{u \in D} |\partial^j f(u)| = \sum_{i=0}^k \sup_{u \in D} \|D^i f(u)\|$$

where the final norm is the operator norm. We first suppose that $f : D \times X \rightarrow M$ is α -Hölder transversely C^k . Let $\bar{f} : X \rightarrow C^k(D, M)$ be given by $x \rightarrow f_x$ where $f_x(\cdot) = f(\cdot, x)$. Our hypotheses imply that \bar{f} is α -Hölder. Therefore by definition of the C^k norm, we have

$$\|\bar{f}(x) - \bar{f}(y)\|_k = \|f_x - f_y\|_k = \sum_{|j| \leq k} \sup_{u \in D} \|\partial^j f_x(u) - \partial^j f_y(u)\| \leq K|x - y|^\alpha.$$

Thus for $0 \leq |j| \leq k$ and $u \in D$ fixed, the functions $x \rightarrow \partial^j f_x(u)$ are α -Hölder and therefore in $C^\alpha(X, M)$. For $0 \leq i \leq k$, we define $\hat{f}^i(u)$ to be the map $x \rightarrow D^i f_x(u)$, or equivalently $\hat{f}^i(u) = (x \rightarrow \partial^j f_x(u))_{|j|=i}$. We will show that \hat{f}^i is the i^{th} derivative of \hat{f} for $i \leq k-1$.

We proceed iteratively, starting with the $k=2$ case. We will show that \hat{f} is C^1 and that its derivative at $u \in D$ is given by $\hat{f}^1(u)$. Thus we need to show that

$$\lim_{v \rightarrow u} \frac{\|\hat{f}(u) - \hat{f}(v) - \hat{f}^1(u)(u - v)\|_\alpha}{\|u - v\|} = 0$$

Fixing u, v in D , the numerator above is given by the Taylor remainder

$$R : x \mapsto R(x) = f_x(u) - f_x(v) - D^1 f_x(u)(u - v)$$

where the product on the righthand side is a vector product. Applying Taylor's formula with integral remainder to $f_x - f_y$, we get that

$$\begin{aligned} |R(x) - R(y)| &\leq \frac{\|u - v\|^2}{2} \sup_{w \in [u, v]} \|D^2 f_x(w) - D^2 f_y(w)\| \\ &\leq \frac{\|u - v\|^2}{2} \|f_x - f_y\|_2 \\ &\leq \frac{\|u - v\|^2}{2} K |x - y|^\alpha, \end{aligned} \tag{38}$$

for some K , where the last inequality comes from the hypothesis that \bar{f} is α -Hölder. Thus

$$\|R_{u,v}\|_\alpha \leq K \frac{\|u - v\|^2}{2}.$$

Therefore

$$\lim_{v \rightarrow u} \frac{\|\hat{f}(u) - \hat{f}(v) - \hat{f}'(u)(u - v)\|_\alpha}{\|u - v\|} = \lim_{v \rightarrow u} \frac{\|R_{u,v}\|_\alpha}{\|u - v\|} = 0.$$

The first step follows. The result holds for k finite or infinite by induction.

If we assume that $f : D^\mathbb{C} \times X \rightarrow M$ is α -Hölder transversely complex analytic, then the first part of the argument implies that \hat{f} is C^k for all k . Then, since $\bar{f}(x)$ satisfies the Cauchy-Riemann equations for all x our formula for $D\hat{f}$ implies that \hat{f} satisfies the Cauchy-Riemann equations, so is complex analytic.

Now suppose that M is a complex analytic (or C^k) manifold. Let U , V and ϕ be as in the definition preceding this lemma. Observe that if $f : D \times X \mapsto M$ is α -Hölder transversely complex analytic (or C^k), then so is its restriction $f_{U,V}$ to $f^{-1}(\mathcal{W}(U, V)) \times V$, and thus $f^\phi = \phi \circ f_{U,V}$ is also α -Hölder transversely complex analytic (or C^k). Therefore, by the previous argument, f^ϕ is complex analytic (or C^k) as a map into $C^\alpha(V, \mathbb{C})$ (or $C^\alpha(V, \mathbb{R})$). The result follows. \square

8.2. Analytic variation of the limit maps. We are now ready to begin the proof of Theorem 8.3. Given a complex analytic family of representations which contains an Anosov representation, we construct an associated bundle where we can apply the results of the previous section to produce a family of limit maps.

Let $G^\mathbb{C}$ be a complex Lie group and let $P^\mathbb{C}$ be a parabolic subgroup. Let $\{\rho_u\}_{u \in D^\mathbb{C}}$ be a complex analytic family of homomorphisms of Γ into $G^\mathbb{C}$ so that ρ_0 is $(G^\mathbb{C}, P^\mathbb{C})$ -Anosov.

We construct a $\mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$ -bundle over $D^{\mathbb{C}} \times \mathbf{U}_0\Gamma$. Let

$$\tilde{A} = D^{\mathbb{C}} \times \widetilde{\mathbf{U}_0\Gamma} \times \mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$$

which is a $\mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$ -bundle over $D^{\mathbb{C}} \times \widetilde{\mathbf{U}_0\Gamma}$. Then $\gamma \in \Gamma$ acts on \tilde{A} , by

$$\gamma(u, x, [g]) = (u, \gamma(x), [\rho_u(\gamma)g])$$

and we let

$$A = \tilde{A}/\Gamma.$$

The geodesic flows on $\widetilde{\mathbf{U}_0\Gamma}$ and $\mathbf{U}_0\Gamma$ lift to geodesic flows on A and \tilde{A} . (These flows act trivially on the $D^{\mathbb{C}}$ and $\mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$ factors.)

Since ρ_0 is $(\mathbf{G}^{\mathbb{C}}, \mathbf{P}^{\mathbb{C}})$ -Anosov there exists a section σ_0 of A over $\{0\} \times \mathbf{U}_0\Gamma$. Concretely, if $\xi_0 : \partial_{\infty}\Gamma \rightarrow \mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$ is the limit map, we construct an equivariant section $\tilde{\sigma}_0$ of \tilde{A} over $\{0\} \times \widetilde{\mathbf{U}_0\Gamma}$ of the form

$$(0, (x, y, t)) \rightarrow (0, (x, y, t), \xi_0(x)).$$

The section $\tilde{\sigma}_0$ descends to the desired section σ_0 of A over $\{0\} \times \mathbf{U}_0\Gamma$. One may identify the bundle over $\{0\} \times X$ with fiber $\mathbf{T}_{\sigma_0(x)}\pi^{-1}(0, x)$ with \mathcal{N}_{ρ}^{-} . Since the geodesic flow lifts to a contracting flow on \mathcal{N}_{ρ}^{-} , the flow $\{\Phi_t\}_{t \in \mathbb{R}}$ is contracting along $\sigma_0(\mathbf{U}_0\Gamma)$.

Theorem 8.6 then implies that there exists a sub-disk $D_1^{\mathbb{C}} \subset D^{\mathbb{C}}$ containing 0, $\alpha > 0$, and an α -Hölder transversely complex analytic section $\eta : D_1^{\mathbb{C}} \times \mathbf{U}_0\Gamma \rightarrow A$ that extends σ_0 , is fixed by $\{\Phi_t\}_{t \in \mathbb{R}}$ and so that $\{\Phi_t\}_{t \in \mathbb{R}}$ contracts along η . (More concretely, Theorem 8.6 produces, for large enough t , a section fixed by Φ_t so that Φ_t contracts along η . One may then use the uniqueness portion of the statement to show that η is fixed by Φ_t for all t .) We may lift η to a section $\tilde{\eta} : D_1^{\mathbb{C}} \times \widetilde{\mathbf{U}_0\Gamma} \rightarrow \tilde{A}$ which we may view as a map $\tilde{\eta} : D_1^{\mathbb{C}} \times \widetilde{\mathbf{U}_0\Gamma} \rightarrow \mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$. Since $\tilde{\eta}$ is flow-invariant and the flow is contracting, $\tilde{\eta}(u, (x, y, t))$ depends only on x . Therefore, we obtain a transversely complex analytic map

$$\xi : D_1^{\mathbb{C}} \times \partial_{\infty}\Gamma \rightarrow \mathbf{G}^{\mathbb{C}}/\mathbf{P}^{\mathbb{C}}$$

which extends ξ_0 . The map ξ satisfies properties (2) and (3), since ξ is α -Hölder transversely complex analytic, while property (4) follows from Lemma 8.10.

It remains to prove that we may restrict to a sub disk $D_0^{\mathbb{C}}$ of $D_1^{\mathbb{C}}$ so that if $u \in D_0^{\mathbb{C}}$, then ρ_u is $(\mathbf{G}^{\mathbb{C}}, \mathbf{P}^{\mathbb{C}})$ -Anosov with limit map ξ_u . Let $\mathbf{Q}^{\mathbb{C}}$ be a parabolic subgroup of $\mathbf{G}^{\mathbb{C}}$ which is opposite to $\mathbf{P}^{\mathbb{C}}$. Then there exists a Lipschitz transversely complex analytic $\mathbf{G}^{\mathbb{C}}/\mathbf{Q}^{\mathbb{C}}$ -bundle A' over $D^{\mathbb{C}} \times \mathbf{U}_0\Gamma$ and we may lift the geodesic flow to a flow $\{\Phi'_t\}$ on A' . Since ρ_0 is $(\mathbf{G}^{\mathbb{C}}, \mathbf{P}^{\mathbb{C}})$ -Anosov, there exists a map $\theta_0 : \partial_{\infty}\Gamma \rightarrow \mathbf{G}^{\mathbb{C}}/\mathbf{Q}^{\mathbb{C}}$ which gives rise to a section σ'_0 of A' over $\{0\} \times \mathbf{U}_0\Gamma$ such that the inverse flow is contracting on a neighborhood of $\sigma'_0(\{0\} \times \mathbf{U}_0\Gamma)$. We again

apply Corollary 8.6 to find an α' -Hölder (for some $\alpha' > 0$) transversely complex analytic section $\eta' : D_2^{\mathbb{C}} \times \mathbf{U}_0\Gamma \rightarrow A'$ that extends σ'_0 , for some sub-disk $D_2^{\mathbb{C}}$ of $D^{\mathbb{C}}$ which contains 0, and is fixed by $\{\Phi'_t\}_{t \in \mathbb{R}}$. The section η' lifts to a section of $\tilde{\eta}'$ of \tilde{A}' which we may reinterpret as a map $\tilde{\eta}' : D_2^{\mathbb{C}} \times \widetilde{\mathbf{U}_0\Gamma} \rightarrow \mathbf{G}^{\mathbb{C}}/\mathbf{Q}^{\mathbb{C}}$ so that $\tilde{\eta}'(x, y, t)$ depends only on y . So we obtain an α' -Hölder transversely complex analytic map

$$\theta : D_2^{\mathbb{C}} \times \partial_{\infty}\Gamma \rightarrow \mathbf{G}^{\mathbb{C}}/\mathbf{Q}^{\mathbb{C}}$$

which restricts to θ_0 . Since ξ_0 and θ_0 are transverse, we may find a sub disk $D_0^{\mathbb{C}}$ of $D_1^{\mathbb{C}} \cap D_2^{\mathbb{C}}$ so that ξ_u and θ_u are transverse if $u \in D_0^{\mathbb{C}}$. It follows that if $u \in D_0^{\mathbb{C}}$, then ρ_u is $(\mathbf{G}^{\mathbb{C}}, \mathbf{P}^{\mathbb{C}})$ -Anosov with limit maps ξ_u and θ_u . This completes the proof of Theorem 8.3 in the complex analytic case. Notice that the entire argument also goes through in the C^k setting.

8.3. Analytic variation of the reparameterization. We now turn to the proof of Proposition 8.2. We begin by considering the C^k case

8.3.1. Transversely C^k . Let $\{\rho_u : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})\}_{u \in D}$ be a C^k -family of convex Anosov representations. We first construct a Lipschitz transversely C^k \mathbb{R}^m -bundle W over $D \times \mathbf{U}_0\Gamma$. Let $\tilde{W} = D \times \widetilde{\mathbf{U}_0\Gamma} \times \mathbb{R}^m$ be the trivial \mathbb{R}^m -bundle over $D \times \widetilde{\mathbf{U}_0\Gamma}$. The group Γ naturally acts on \tilde{W} , where the action on the D factor is trivial, to produce the quotient bundle W . The Gromov geodesic flow on $\mathbf{U}_0\Gamma$ may be extended to a flow on $D \times \mathbf{U}_0\Gamma$ which acts trivially on the D factor and then lifted to a Lipschitz transversely C^k flow $\{\Psi_t\}$ on W (which acts trivially on the \mathbb{R}^m factor upstairs).

One can use a partition of unity associated to a family of trivialization of the bundle W to construct a metric.

Lemma 8.11. *The bundle W admits a Lipschitz transversely C^k metric G .*

Theorem 8.3 gives, possibly after restricting D , an α -Hölder transversely C^k map

$$\xi : D \times \partial_{\infty}\Gamma \rightarrow \mathbf{G}/\mathbf{P} = \mathbb{RP}(m),$$

such that if $u \in D$, then ρ_u is convex Anosov with limit map $\xi_u = \xi(u, \cdot)$. Let L be the line sub-bundle of W over $D \times \mathbf{U}_0\Gamma$ associated with the limit curve. Concretely, let \tilde{L} be the line sub-bundle of \tilde{W} so that the fiber over $(u, (x, y, t)) \in D \times \mathbf{U}_0\Gamma$ is the line $\xi(u, x)$ and let L be the quotient line sub-bundle of W . The bundle L is α -Hölder transversely C^k , so G restricts to an α -Hölder transversely C^k metric

on L , which we simply call G . Since each ρ_u is convex Anosov with limit map ξ_u , the flow $\{\Psi_t\}_{t \in \mathbb{R}}$ preserves L and is contracting on L .

For each t , we let $k_t : D \times \mathbf{U}_0\Gamma \rightarrow \mathbb{R}$, be defined by

$$\Psi_t^* G = k_t G.$$

Since G is α -Hölder transversely C^k , so is k_t .

We may generalize the construction in the proof of Lemma 5.3 to establish:

Lemma 8.12. *The line bundle L admits an α -Hölder transversely C^k metric G^0 such that there exists $\beta > 0$ so that*

$$\Psi_t^*(G^0) < e^{-\beta t} G^0$$

for all $t > 0$.

Concretely,

$$G^0 = \int_0^{t_0} e^{\beta s} \Psi_s^*(G) ds = \left(\int_0^{t_0} e^{\beta s} k_s ds \right) G$$

for some $t_0 > 0$. Moreover,

$$\Psi_t^*(G^0) = \int_0^{t_0} e^{\beta s} \Psi_{s+t}^* G ds = \left(\int_0^{t_0} e^{\beta t} k_{s+t} dt \right) G.$$

So, $\Psi_t^*(G^0) = K_t G^0$ where

$$K_t = \frac{\int_0^{t_0} e^{\beta s} k_{s+t} ds}{\int_0^{t_0} e^{\beta s} k_s ds} = e^{-\beta t} \frac{\int_t^{t_0+t} e^{\beta s} k_s ds}{\int_0^{t_0} e^{\beta s} k_s ds}.$$

Let $g : D \times \mathbf{U}_0\Gamma \times \mathbb{R}$ be given by $g(\cdot, t) = \log K_t(\cdot)$. By construction, g is differentiable in the t coordinate. Then, let

$$f : D^{\mathbb{C}} \times \mathbf{U}_0\Gamma \times \mathbb{R} \rightarrow \mathbb{R}$$

be given by

$$f(\cdot, s) = \frac{\partial g}{\partial t}(\cdot, s).$$

We can differentiate the equality

$$g(\cdot, t + s) = g(\Phi_s(\cdot), t) + g(\cdot, s)$$

with respect to t and evaluate at $t = 0$ to conclude that

$$f(\cdot, s) = f(\Phi_s(\cdot), 0).$$

In particular, for any t ,

$$\int_0^t (f(\Phi_s(\cdot), 0) ds = g(\cdot, t).$$

Let $\gamma \in \Gamma$ and let $x \in \mathbf{U}_0\Gamma$ be a point on the periodic orbit associated to γ (which is simply the quotient of $(\gamma^+, \gamma^-) \times \mathbb{R} \subset \widetilde{\mathbf{U}_0\Gamma}$). For all $u \in D$, we define $f_u : \mathbf{U}_0\Gamma \rightarrow \mathbb{R}$ by

$$f_u(x) = f(u, x, 0).$$

If t_γ is the period of the orbit of $\mathbf{U}_0\Gamma$ containing x , then

$$e^{\int_0^{t_\gamma} f_u(\Phi_s(u, x)) ds} G^0(x, u) = \Phi_{t_\gamma}^* G^0(u, x) = e^{\Lambda(\rho_u, \gamma)} G^0(u, x),$$

so

$$\int_0^{t_\gamma} f_u(\Phi_s(u, x)) ds = \Lambda(\rho_u, \gamma)$$

is the period of the reparameterization of the flow $\mathbf{U}_0\Gamma$ by f_u . Since the periods of the reparameterization of $\mathbf{U}_0\Gamma$ by f_u and the periods of $U_{\rho_u}\Gamma$ agree (see Proposition 5.1), Livšic's Theorem 7.2 implies that the reparameterization of $\mathbf{U}_0\Gamma$ by f_u is Hölder conjugate to $U_{\rho_u}\Gamma$ as desired.

To complete the proof, we must establish the regularity of the family $\{f_u\}_{u \in D}$. Notice that

$$f_u(\cdot) = \frac{\partial}{\partial t} \log K_t(\cdot)|_{t=0} = \frac{\partial K_t}{\partial t}(\cdot, 0) = -\beta + \frac{e^{\beta t_0} k_{t_0}(\cdot) - 1}{\int_0^{t_0} e^{\beta s} k_s(\cdot) ds}.$$

So, if we define $\hat{f} : D \times \mathbf{U}_0\Gamma \rightarrow \mathbb{R}$, by $\hat{f}(u, x) = f(u, x, 0) = f_u(x)$ we see that \hat{f} is α -Hölder transversely C^k , since each k_t is α -Hölder transversely C^k . Lemma 8.10 then implies that the map from D to $C^\alpha(\mathbf{U}_0\Gamma, \mathbb{R})$ given by $u \rightarrow f_u$ is C^{k-1} . This completes the proof of Proposition 8.2 in the C^k setting.

8.3.2. The real analytic case. Let $\{\rho_u : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})\}_{u \in D}$ be a real analytic family of convex Anosov representations. In order to show that the map $u \rightarrow f_u$ is real analytic, we must again complexify the situation. Let $D^\mathbb{C}$ be the complexification of D . We may extend $\{\rho_u\}_{u \in D}$ to a complex analytic family $\{\rho_u : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{C})\}_{u \in D^\mathbb{C}}$ of homomorphisms. Theorem 8.3 implies that, after possibly restricting $D^\mathbb{C}$, there exists a α -Hölder transversely complex analytic map

$$\xi : D^\mathbb{C} \times \partial_\infty \Gamma \rightarrow \mathbf{G}^\mathbb{C}/\mathbf{P}^\mathbb{C} = \mathbb{CP}(m)$$

such that if $u \in D^\mathbb{C}$, then ρ_u is Anosov with respect to the parabolic subgroup $\mathbf{P}^\mathbb{C}$ which is the stabilizer of a complex line with limit map ξ_u . (We call such representations *complex convex Anosov*.)

We construct a Lipschitz transversely complex analytic \mathbb{C}^m -bundle $W^\mathbb{C}$ over $D^\mathbb{C} \times \mathbf{U}_0\Gamma$ which is the quotient of $\widetilde{W}^\mathbb{C} = D^\mathbb{C} \times \widetilde{\mathbf{U}_0\Gamma} \times \mathbb{C}^m$ associated to the family $\{\rho_u\}_{u \in D^\mathbb{C}}$. We can then lift the Gromov geodesic flow on $\mathbf{U}_0\Gamma$ to a Lipschitz transversely complex analytic flow

$\{\Psi_t\}_{t \in \mathbb{R}}$ on $W^\mathbb{C}$. Since the functions in the partition of unity for our trivializations of $W^\mathbb{C}$ are constant in the $D^\mathbb{C}$ direction, we have:

Proposition 8.13. *After possibly further restricting $D^\mathbb{C}$, the bundle $W^\mathbb{C}$ is equipped with a Lipschitz transversely complex analytic 2-form ω of type $(1, 1)$ such that*

$$G(u, v) = \omega(u, v) + \overline{\omega(v, u)},$$

is Hermitian.

Let $L^\mathbb{C}$ be the (complex) line sub-bundle of $W^\mathbb{C}$ determined by ξ , i.e. $L^\mathbb{C}$ is the quotient of the line sub-bundle of $\tilde{W}^\mathbb{C}$ whose fiber over $(u, (x, y, t)) \in D^\mathbb{C} \times \mathbf{U}_0\Gamma$ is the complex line $\xi_u(x)$. Then, $L^\mathbb{C}$ is a α -Hölder transversely complex analytic line bundle over $D^\mathbb{C} \times \mathbf{U}_0\Gamma$. Since each ρ_u is complex convex Anosov with limit map ξ_u , $L^\mathbb{C}$ is preserved by the flow $\{\Psi_t\}_{t \in \mathbb{R}}$. We restrict ω and G to $L^\mathbb{C}$ (and still denote them by ω and G).

In analogy with the C^k case, we will define, for all t , a map $k_t : D^\mathbb{C} \times \mathbf{U}_0\Gamma \rightarrow \mathbb{R}$ so that

$$\Psi_t^* G = k_t G.$$

We will then show that k_t is α -Hölder transversely real analytic and that the function $u \rightarrow k_t(u, \cdot)$ from $D^\mathbb{C}$ to $C^\alpha(\mathbf{U}_0\Gamma, \mathbb{R})$ is real analytic. Once we have done so we can complete the proof much as in the C^k setting.

Since $L^\mathbb{C}$ is a line bundle, we can consider the function

$$a : D^\mathbb{C} \times \mathbf{U}_0\Gamma \rightarrow \mathbb{C}$$

such that

$$\omega(u, x)(v, v) = a(u, x)G(u, x)(v, v).$$

whenever v is in the fiber of $L^\mathbb{C}$ over (u, x) . Concretely,

$$a(u, x) = \frac{\omega(v, v)}{2\Re(\omega(v, v))}$$

for any non-trivial v in the fiber over (u, x) .

If U is an open subset of $\mathbf{U}_0\Gamma$ in one of our trivializing sets, we can construct a non-zero section

$$V : D^\mathbb{C} \times U \rightarrow L^\mathbb{C}$$

which is α -Hölder transversely complex analytic. Then

$$\omega(V, V) : D^\mathbb{C} \times U \rightarrow \mathbb{C}$$

is α -Hölder transversely complex analytic. Lemma 8.10 implies that the map from $D^\mathbb{C}$ to $C^\alpha(U, \mathbb{C})$ given by $u \rightarrow \omega(V(u, \cdot), V(u, \cdot))$ is complex

analytic. Therefore, the map from $D^{\mathbb{C}}$ to $C^{\alpha}(U, \mathbb{R})$ given by $u \rightarrow \Re(\omega(V(u, \cdot), V(u, \cdot)))$ is real analytic. It follows that the map from $D^{\mathbb{C}}$ to $C^{\alpha}(U, \mathbb{C})$ given by $u \rightarrow a(u, \cdot)$ is real analytic since

$$a|_{D^{\mathbb{C}} \times U} = \frac{\omega(V, V)}{2\Re(\omega(V, V))}.$$

Since x was arbitrary the map from $D^{\mathbb{C}}$ to $C^{\alpha}(\mathbf{U}_0\Gamma, \mathbb{C})$ given by $u \rightarrow a(u, \cdot)$ is real analytic. Similarly, a itself is α -Hölder transversely real analytic.

If we define, for all t , the map

$$h_t : D^{\mathbb{C}} \times \mathbf{U}_0\Gamma \rightarrow \mathbb{C}$$

so that

$$\Psi_t^* \omega = h_t \omega,$$

then, we may argue, just as above, that h_t is α -Hölder transversely complex analytic. Lemma 8.10 guarantees that the map from $D^{\mathbb{C}}$ to $C^{\beta}(\mathbf{U}_0\Gamma, \mathbb{C})$ given by $u \rightarrow h_t(u, \cdot)$ is complex analytic.

If $t \in \mathbb{R}$,

$$\Psi_t^* G(\cdot) = 2\Re(\Psi_t^* \omega(\cdot)) = 2\Re(a(\cdot)h_t(\cdot)\omega(\cdot)) = 2\Re(a(\cdot)h_t(\cdot) G(\cdot)).$$

We define $k_t(\cdot) = \Re(ah_t)(\cdot)$ and note that $\Psi_t^* G = k_t G$. Then, k_t is α -Hölder transversely real analytic and the map from $D^{\mathbb{C}}$ to $C^{\alpha}(\mathbf{U}_0\Gamma, \mathbb{R})$ given by $u \rightarrow k_t(u, \cdot)$ is real analytic (since it is the real part of a product of a real analytic and a complex analytic function).

We again apply the construction of Lemma 5.3 to produce an α -Hölder transversely real analytic metric G^0 on \hat{L} such that

$$\Psi_t^*(G^0) < e^{-\beta t} G^0.$$

for some $\beta > 0$ and all $t > 0$, and define, for all t , $K_t : D^{\mathbb{C}} \times \mathbf{U}_0\Gamma \rightarrow \mathbb{R}$ so that

$$\Psi_t^*(G^0) = K_t G^0.$$

We check, just as in the C^k case, that

$$K_t = e^{-\beta t} \frac{\int_t^{t_0+t} e^{\beta s} k_s \, ds}{\int_0^{t_0} e^{\beta s} k_s \, ds}.$$

Then, for each $u \in D^{\mathbb{C}}$ we define $f_u : \mathbf{U}_0\Gamma \rightarrow \mathbb{R}$, by setting

$$f_u(\cdot) = \frac{\partial K_t}{\partial t}(u, \cdot, 0) = -\beta + \frac{e^{\beta t_0} k_{t_0}(\cdot) - 1}{\int_0^{t_0} e^{\beta s} k_s(\cdot) \, ds}.$$

Then, since $u \rightarrow k_t(u, \cdot)$ is real analytic for all t , our formula for f_u guarantees that the map from $D^{\mathbb{C}}$ to $C^{\beta}(\mathbf{U}_0\Gamma, \mathbb{R})$ given by $u \rightarrow f_u$ is real analytic. Therefore, the restriction of this map to the real submanifold

D is also real analytic. To complete the proof of Proposition 8.2 in the analytic setting, we argue, exactly as in the C^k setting, that if $u \in D$, then the reparameterization of $U_0\Gamma$ by f_u is Hölder conjugate to $U_{\rho_u}\Gamma$.

9. THERMODYNAMIC FORMALISM ON THE DEFORMATION SPACE OF CONVEX ANOSOV REPRESENTATIONS

In this section, we show that entropy, intersection and normalized intersection vary analytically over $\mathcal{C}(\Gamma, m)$ and construct the thermodynamic mapping of $\mathcal{C}(\Gamma, m)$ into the space of pressure zero functions on $U_0\Gamma$.

9.1. Analyticity of entropy and intersection. Let Γ be a word hyperbolic group admitting a convex Anosov representation. By Proposition 6.8, the Gromov geodesic flow on $U_0\Gamma$ admits a Hölder reparametrisation which turns it into a topologically transitive metric Anosov flow. Since the Gromov geodesic flow is only well defined up to reparametrisation, we choose a fixed Hölder reparametrisation which is a topologically transitive metric Anosov, and use the corresponding flow, denoted by $\psi = \{\psi_t\}_{t \in \mathbb{R}}$ as a background flow on $U_0\Gamma$.

Periodic orbits of the Gromov geodesic flow ψ are in bijection with conjugacy classes of infinite order primitive (*i.e.* not a positive power of another element of Γ) elements of Γ . This bijection associates to the conjugacy class $[\gamma]$ the projection to $U_0\Gamma$ of $(\gamma^+, \gamma^-) \times \mathbb{R}$.

Let $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ be a convex Anosov representation. By Proposition 5.1, the geodesic flow $(U_\rho\Gamma, \{\phi_t\}_{t \in \mathbb{R}})$ of ρ is Hölder conjugate to a Hölder reparametrization of the flow $\{\psi_t\}_{t \in \mathbb{R}}$. Periodic orbits of $\{\phi_t\}_{t \in \mathbb{R}}$ are in one-to-one correspondence with conjugacy classes of infinite order primitive elements of Γ . The periodic orbit associated to the conjugacy class $[\gamma]$ has period $\Lambda(\rho)(\gamma)$.

If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is convex Anosov, let $f_\rho : U_0\Gamma \rightarrow \mathbb{R}$ be a Hölder function such that the reparameterization of $U_0\Gamma$ by f_ρ is Hölder conjugate to $U_\rho\Gamma$. Livšic's theorem 7.2 implies that the correspondence $\rho \mapsto f_\rho$ is well defined modulo Livšic cohomology and invariant under conjugation of the homomorphism ρ . Therefore, we may define

$$h(\rho_0) = h(f_{\rho_0}), \quad (39)$$

$$\mathbf{I}(\rho_0, \rho_1) = \mathbf{I}(f_{\rho_0}, f_{\rho_1}), \text{ and} \quad (40)$$

$$\mathbf{J}(\rho_0, \rho_1) = \mathbf{J}(f_{\rho_0}, f_{\rho_1}) = \frac{h(\rho_1)}{h(\rho_0)} \mathbf{I}(\rho_0, \rho_1), \quad (41)$$

for convex Anosov homomorphisms $\rho_0 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ and $\rho_1 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$. These quantities are well defined and agree with the definition

given in the Introduction. Proposition 7.3.1 implies that

$$h(f_{\rho_0}) = \lim_{T \rightarrow \infty} \frac{1}{T} \log \#(R_T(\rho_0))$$

while equation (32) implies that

$$\mathbf{I}(f_{\rho_0}, f_{\rho_1}) = \lim_{T \rightarrow \infty} \left(\frac{1}{\#(R_T(\rho_0))} \sum_{[\gamma] \in R_T(\rho_0)} \frac{\log(\Lambda(\gamma)(\rho_1))}{\log(\Lambda(\gamma)(\rho_0))} \right).$$

Proposition 8.2 implies that if $\{\rho_u\}_{u \in D}$ is an analytic family of of convex, Anosov homomorphisms defined on a disc D , then we can choose, at least locally, the map $u \mapsto f_{\rho_u}$ to be analytic. Proposition 7.11 then implies that entropy, intersection and renormalized intersection all vary analytically.

Proposition 9.1. *Given two analytic families $\{\rho_u\}_{u \in D}$ and $\{\eta_v\}_{v \in D'}$ of convex Anosov homomorphisms, the functions $u \mapsto h(\rho_u)$, $(u, v) \mapsto \mathbf{I}(\rho_u, \eta_v)$ and $(u, v) \mapsto \mathbf{J}(\rho_u, \eta_v)$ are analytic on their domains of definition.*

Combining Propositions 7.7, 7.8 and 7.10 one obtains the following.

Corollary 9.2. *For every pair of convex Anosov representations $\rho, \eta : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ one has*

$$\mathbf{J}(\rho, \eta) \geq 1.$$

If $\mathbf{J}(\rho, \eta) = 1$, then there exists a constant $c \geq 1$ such that

$$\Lambda_\rho(\gamma)^c = \Lambda_\eta(\gamma)$$

for every $\gamma \in \Gamma$.

Moreover, if $\{\rho_u\}_{u \in D}$ is a smooth one parameter family of convex Anosov representations and $\{f_u\}_{u \in D}$ is an associated smooth family $\{f_u\}$ of reparametrisations, then

$$\left. \frac{\partial^2}{\partial t^2} \right|_{t=0} \mathbf{J}(\rho_0, \rho_t) = 0$$

if and only if

$$\left. \frac{\partial}{\partial u} \right|_{u=0} (h_{\rho_u} f_u)$$

is Livšic cohomologous to 0.

9.2. The thermodynamic mapping and the pressure form. If $\rho \in \mathcal{C}(\Gamma, m)$ and f_ρ is a reparametrisation of the Gromov geodesic flow giving rise to the geodesic flow of ρ , we define $\Phi_\rho : \mathcal{U}_0\Gamma \rightarrow \mathbb{R}$ by

$$\Phi_\rho(x) = -h(\rho)f_\rho(x).$$

Lemma 7.1 implies that $\Phi_\rho \in \mathcal{P}(\mathcal{U}_0\Gamma)$. Let $\mathcal{H}(\mathcal{U}_0\Gamma)$ be the set of Livšic cohomology classes of pressure zero function, we saw that the class of Φ_ρ in $\mathcal{H}(\mathcal{U}_0\Gamma)$ only depends on ρ . We define the *Thermodynamic mapping* to be

$$\mathfrak{T} : \begin{cases} \mathcal{C}(\Gamma, m) & \rightarrow \mathcal{H}(\mathcal{U}_0\Gamma) \\ \rho & \mapsto [\Phi_\rho] \end{cases}$$

By Proposition 8.2, the thermodynamic mapping is “analytic” in the following sense: for every representation ρ in the analytic manifold $\mathcal{C}(\Gamma, m)$, there exists a neighborhood U of ρ in $\mathcal{C}(\Gamma, m)$ and an analytic mapping from U to $\mathcal{P}(\mathcal{U}_0\Gamma)$ which lifts the Thermodynamic mapping.

We use the Thermodynamic mapping to define a 2-tensor on our deformation spaces.

Definition 9.3. [PRESSURE FORM] *Let $\{\rho_u\}_{u \in M}$ be an analytic family of convex Anosov homomorphisms parametrised by an analytic manifold M . If $z \in M$, we define $\mathbf{J}_z : M \rightarrow \mathbb{R}$ by letting*

$$\mathbf{J}_z(u) = \mathbf{J}(\rho_z, \rho_u).$$

The associated pressure form \mathbf{p} on M is the 2-tensor such that if $v, w \in T_z M$, then

$$\mathbf{p}(v, w) = D_z^2 \mathbf{J}_z(v, w).$$

Notice that, by Corollary 9.2, the pressure form is non-negative.

In particular, we get pressure forms on $\tilde{\mathcal{C}}(\Gamma, m)$ and on $\tilde{\mathcal{C}}(\Gamma, \mathbf{G})$ when \mathbf{G} is a reductive subgroup of $\mathbf{SL}_m(\mathbb{R})$. Since \mathbf{J} is invariant under the action of conjugation on each variable, these pressure forms descend to 2-tensors, again called pressure forms, on the analytic manifolds $\mathcal{C}(\Gamma, m)$ and $\mathcal{C}(\Gamma, \mathbf{G})$.

We next observe that tangent vectors with pressure norm zero have a very special property.

If Γ is a word hyperbolic group, α is an infinite order element of Γ and $\{\rho_u\}_{u \in M}$ is an analytic family of convex Anosov homomorphisms parameterised by an analytic manifold M , one may view $\Lambda(\alpha)$ as an analytic function on M where we abuse notation by letting $\Lambda(\alpha)(u) = \Lambda(\alpha)(\rho_u)$ denote the spectral radius of $\rho_u(\alpha)$.

Lemma 9.4. *Let $\{\rho_u\}_{u \in M}$ be an analytic family of convex Anosov homomorphisms parametrised by an analytic manifold M and let \mathbf{p} be the associated pressure form. If $v \in \mathbb{T}_z M$ and*

$$\mathbf{p}(v, v) = 0,$$

then there exists $K \in \mathbb{R}$ such that if α is any element of infinite order in Γ , then

$$D_z \log(\Lambda(\alpha))(v) = K \log(\Lambda(\alpha))(z).$$

Proof. Consider a smooth one parameter family $\{u_s\}_{s \in (-1,1)}$ in M such that $u_0 = z$ and $\dot{u}_0 = v$. Let $\rho_s = \rho_{u_s}$ and let $f_s = f_{u_s}$ where f_u is a smooth family of reparametrisations obtained from Proposition 8.2. We define, for all $s \in (-1, 1)$,

$$\Phi_s = \Phi_{\rho_s} = -h(\rho_s)f_s,$$

By Corollary 9.2, $\dot{\Phi}_0$ is Livšic cohomologous to zero. In particular, the integral of $\dot{\Phi}_0$ is zero on any ϕ_s -invariant measure. Thus for any infinite order element $\alpha \in \Gamma$ one has

$$\langle \delta_\alpha | \dot{\Phi}_0 \rangle = 0.$$

By definition, $\Phi_s = -h(\rho_s)f_{\rho_s}$ and thus

$$\langle \delta_\alpha | \Phi_s \rangle = -h(\rho_s) \log \Lambda(\alpha)(u_s).$$

It then follows that

$$0 = \langle \delta_\alpha | \left. \frac{d\Phi_s(x)}{ds} \right|_{s=0} \rangle = \left. \frac{d(\langle \delta_\alpha | \Phi_s \rangle)(x)}{ds} \right|_{s=0} = \left. \frac{d(h(\rho_s) \log(\Lambda(\alpha)(u_s)))}{ds} \right|_{s=0}.$$

Applying the chain rule we get

$$0 = \left(\left. \frac{dh(\rho_s)}{ds} \right|_{s=0} \right) \log(\Lambda(\alpha)(u_s)) + h(\rho_s) \left(\left. \frac{d \log(\Lambda(\alpha)(u_s))}{ds} \right|_{s=0} \right).$$

It follows that setting

$$K = -\frac{1}{h(\rho_0)} \left. \frac{d(h(\rho_s))}{ds} \right|_{s=0},$$

we get that for all $\alpha \in \Gamma$,

$$D_z \log(\Lambda(\alpha))(v) = \left. \frac{d}{ds} \right|_{s=0} (\log(\Lambda(\alpha)(\rho_s))) = K \log(\Lambda(\alpha)(z)).$$

This concludes the proof. \square

10. DEGENERATE VECTORS FOR THE PRESSURE METRIC

In this section, we further analyze the norm zero vectors for the pressure metric.

Proposition 10.1. *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$. Suppose that $\{\rho_u : \Gamma \rightarrow \mathbf{G}\}_{u \in D}$ is an analytic family of convex Anosov \mathbf{G} -generic homomorphisms defined on a disc D with associated pressure form \mathbf{p} . Suppose that $v \in \mathbb{T}_0 D$ and*

$$\mathbf{p}(v, v) = 0.$$

Then, for every element α of infinite order in Γ ,

$$D_0 \log(\Lambda(\alpha))(v) = 0.$$

10.1. Trace functions.

Definition 10.2. *We say that a family $\{f_n\}_{n \in \mathbb{N}}$ of analytic functions defined on a disk D decays at $v \in \mathbb{T}_z D$ if*

$$\lim_{n \rightarrow \infty} f_n(z) = 0 \quad \text{and} \quad \lim_{n \rightarrow \infty} D_z f_n(v) = 0.$$

We say that an analytic function f has log-type K at $v \in \mathbb{T}_u M$, if

$$D_u \log(f)(v) = K \log(f(u)),$$

and is of log-type if it is of log-type K for some K .

The following lemma is immediate.

Lemma 10.3. *Let G be an analytic function that may be written, for all positive integers n , as*

$$G = G_n(1 + h_n),$$

where G_n has log-type K and $\{h_n\}_{n \in \mathbb{N}}$ decays at $v \in \mathbb{T}_u M$, then G has log-type K .

Proof. Notice that

$$\begin{aligned} D_u \log(G)(v) &= D_u \log(G_n)(v) + D_u \log(1 + h_n)(v) \\ &= K \log G_n(u) + \frac{D_u h_n(v)}{1 + h_n(u)}. \end{aligned}$$

We now simply notice that the right hand side of the equation converges to $K \log G(u)$ \square

Recall, from Proposition 2.6, that if α is an infinite order element of Γ and ρ is a convex Anosov representation in $\mathcal{C}(\Gamma, m)$, then we may write

$$\rho(\alpha) = \mathbf{L}(\alpha)(\rho)\mathbf{p}(\rho(\alpha)) + \mathbf{m}(\rho(\alpha)) + \frac{1}{\mathbf{L}(\alpha^{-1})(\rho)}\mathbf{q}(\rho(\alpha)),$$

where

- (1) $\mathbf{L}(\alpha)(\rho)$ is the eigenvalue of $\rho(\alpha)$ of maximum modulus and $\mathbf{p}(\rho(\alpha))$ is the projection on $\xi(\alpha^+)$ parallel to $\theta(\alpha^-)$
- (2) $\mathbf{L}(\alpha^{-1})(\rho)$ is the eigenvalue of $\rho(\alpha^{-1})$ of maximal modulus and $\mathbf{q}(\rho(\alpha))$ is the projection onto the line $\xi(\alpha^-)$ parallel to $\theta(\alpha^+)$, and
- (3) the spectral radius of $\mathbf{m}(\rho(\alpha))$ is less than $\delta^{l(\alpha)}\Lambda(\alpha)(\rho)$ for some $\delta = \delta(\rho) \in (0, 1)$ which depends only on ρ .

It will be useful to define

$$\mathbf{r}(\rho(\alpha)) = \mathbf{m}(\rho(\alpha)) + \frac{1}{\mathbf{L}(\alpha^{-1})(\rho)}\mathbf{q}(\rho(\alpha))$$

which also has spectral radius less than $\delta^{l(\alpha)}\Lambda(\alpha)(\rho)$.

If $\{\rho_u\}_{u \in D}$ is an analytic family of convex Anosov \mathbf{G} -generic homomorphisms defined on a disc D and α and β are infinite order elements of Γ , we consider the following analytic functions on D :

$$\begin{aligned} \mathbf{T}(\alpha, \beta) &: u \mapsto \text{Tr}(\rho_u(\alpha)\rho_u(\beta)) \\ \mathbf{T}(\mathbf{p}(\alpha), \beta) &: u \mapsto \text{Tr}(\mathbf{p}(\rho_u(\alpha))\rho_u(\beta)), \\ \mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta)) &: u \mapsto \text{Tr}(\mathbf{p}(\rho_u(\alpha))\mathbf{p}(\rho_u(\beta))). \\ \mathbf{T}(\mathbf{p}(\alpha), \mathbf{r}(\beta)) &: u \mapsto \text{Tr}(\mathbf{p}(\rho_u(\alpha))\mathbf{r}(\rho_u(\beta))). \\ \mathbf{T}(\mathbf{r}(\alpha), \mathbf{p}(\beta)) &: u \mapsto \text{Tr}(\mathbf{r}(\rho_u(\alpha))\mathbf{p}(\rho_u(\beta))). \\ \mathbf{T}(\mathbf{r}(\alpha), \mathbf{r}(\beta)) &: u \mapsto \text{Tr}(\mathbf{r}(\rho_u(\alpha))\mathbf{r}(\rho_u(\beta))). \end{aligned}$$

We say that two infinite order elements of Γ are *coprime* if they have distinct fixed points in $\partial_\infty \Gamma$ (i.e. they do not share a common power).

We then have

Proposition 10.4. *Let $\{\rho_u\}_{u \in D}$ be an analytic family of convex Anosov homomorphisms defined on a disc D . If α and β are infinite order, coprime elements of Γ , then*

$$\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta)) = \lim_{n \rightarrow \infty} \frac{\mathbf{L}(\alpha^n \beta^n)}{\mathbf{L}(\alpha)^n \mathbf{L}(\beta)^n}$$

and

$$\mathbf{T}(\mathbf{p}(\alpha), \beta) = \lim_{n \rightarrow \infty} \frac{\mathbf{L}(\alpha^n \beta)}{\mathbf{L}(\alpha)^n}.$$

Moreover, if $\mathbf{L}(\gamma)$ has log-type K at $v \in \mathbf{T}_u D$ for all infinite order $\gamma \in \Gamma$, then both $\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))$ and $\mathbf{T}(\mathbf{p}(\alpha), \beta)$ have log-type K at v .

Proof. First notice that

$$\mathbf{T}(\alpha^n, \beta^n) = \mathbf{L}(\alpha^n \beta^n)(1 + g_n)$$

where

$$g_n = \frac{\text{Tr}(\mathbf{r}(\alpha^n \beta^n))}{\mathbf{L}(\alpha^n \beta^n)}.$$

Since $\mathbf{r}(\alpha^n \beta^n)(\rho_u)$ has spectral radius at most $\delta(\rho_u)^{2n} \mathbf{L}(\alpha_n \beta_n)$, and $\delta(\rho_u) \in (0, 1)$, $\lim_{n \rightarrow \infty} g_n(\rho_u) = 0$ for all $\rho_u \in \mathcal{C}(\Gamma, m)$. Since $\{g_n\}$ is a sequence of analytic functions, g_n decays at v .

On the other hand,

$$\begin{aligned} \rho_u(\alpha^n \beta^n) = \\ \mathbf{L}(\alpha)^n \mathbf{L}(\beta)^n \mathbf{p}(\alpha) \mathbf{p}(\beta) + \mathbf{L}(\alpha^n) \mathbf{p}(\alpha) \mathbf{r}(\beta^n) + \mathbf{L}(\beta^n) \mathbf{r}(\alpha^n) \mathbf{p}(\beta) + \mathbf{r}(\alpha^n) \mathbf{r}(\beta^n), \end{aligned}$$

so

$$\mathbf{T}(\alpha^n, \beta^n) = \mathbf{L}(\alpha^n) \mathbf{L}(\beta)^n \mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))(1 + \hat{g}_n)$$

where

$$\hat{g}_n = \frac{\mathbf{L}(\alpha^n) \mathbf{T}(\mathbf{p}(\alpha), \mathbf{r}(\beta^n)) + \mathbf{L}(\beta^n) \mathbf{T}(\mathbf{r}(\alpha^n), \mathbf{p}(\beta)) + \mathbf{T}(\mathbf{r}(\alpha^n), \mathbf{r}(\beta^n))}{\mathbf{L}(\alpha^n) \mathbf{L}(\beta)^n}.$$

and again \hat{g}_n decays at v .

Combining, we see that

$$\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta)) = \frac{\mathbf{L}(\alpha^n \beta^n)(1 + g_n)}{\mathbf{L}(\alpha)^n \mathbf{L}(\beta)^n (1 + \hat{g}_n)},$$

which implies, since $\lim g_n = 0$ and $\lim \hat{g}_n = 0$, that

$$\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta)) = \lim_{n \rightarrow \infty} \frac{\mathbf{L}(\alpha^n \beta^n)}{\mathbf{L}(\alpha)^n \mathbf{L}(\beta)^n}.$$

Moreover, if $\mathbf{L}(\gamma)$ has log-type K at v for all infinite order $\gamma \in \Gamma$, then $G_n = \frac{\mathbf{L}(\alpha^n \beta^n)}{\mathbf{L}(\alpha)^n \mathbf{L}(\beta)^n}$ has log-type K , being the ratio of log-type K functions and we may apply Lemma 10.3 to see that $\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))$ has log-type K .

We similarly derive the claimed facts about $\mathbf{T}(\mathbf{p}(\alpha), \beta)$ by noting that

$$\mathbf{T}(\alpha^n, \beta) = \mathbf{L}(\alpha^n \beta)(1 + h_n)$$

where

$$h_n = \frac{\text{Tr}(\mathbf{r}(\alpha^n \beta))}{\mathbf{L}(\alpha^n \beta)},$$

and that

$$\mathbf{T}(\alpha^n, \beta) = \mathbf{L}(\alpha)^n \mathbf{T}(\mathbf{p}(\alpha), \beta)(1 + \hat{h}_n)$$

where

$$\hat{h}_n = \frac{\mathbf{T}(\mathbf{r}(\alpha^n), \beta)}{\mathbf{L}(\alpha^n)}$$

and applying an argument similar to the one above. \square

Remark: Dreyer [20] previously established that

$$\left\{ \frac{\Lambda(\alpha^n \beta)(\rho)}{\Lambda(\alpha)(\rho)^n} \right\}$$

has a finite limit when ρ is a Hitchin representation.

10.2. Technical lemmas. We will need a rather technical lemma, Lemma 10.6 in the proof of Lemma 10.7, which is itself the main ingredient in the proof of Proposition 10.1.

We first prove a preliminary lemma, which may be viewed as a complicated version of the fact that exponential functions grow faster than polynomials. If a_s is a polynomial in q variables and their conjugates, we will use the notation

$$\|a_s\| = \sup\{|a_s(z_1, \dots, z_q)| \mid |z_i| = 1\}.$$

Lemma 10.5. *Let (f_1, \dots, f_q) and $(\theta_1, \dots, \theta_q)$ be two q -tuples of real numbers and let (g_1, \dots, g_q) be a q -tuple of complex numbers, such that*

$$1 > f_1 > \dots > f_q > 0.$$

Suppose that there exists a strictly decreasing sequence $\{\mu_s\}_{s \in \mathbb{N}}$ of positive numbers all less than 1 and complex-valued polynomials $\{a_s\}_{s \in \mathbb{N}}$ in q variables and their conjugates, such that, for all $n \in \mathbb{N}$,

$$\sum_{p=1}^q n f_p^n \Re(e^{in\theta_p} g_p) = \sum_{s=1}^{\infty} \mu_s^n \Re(a_s(e^{in\theta_1}, \dots, e^{in\theta_q})), \quad (42)$$

and there exists N such that

$$\sum_{s=1}^{\infty} |\mu_s|^n \|a_s\|$$

is convergent for all $n \geq N$. Then, for all $p = 1, \dots, q$,

$$\begin{aligned} \Re(g_p) &= 0 & \text{if } \theta_p &\in 2\pi\mathbb{Q}, \\ g_p &= 0 & \text{if } \theta_p &\notin 2\pi\mathbb{Q}. \end{aligned}$$

Proof. There exists $r \in \mathbb{N}$, so that, for all i , either $r\theta_i \in 2\pi\mathbb{Z}$ or $r\theta_i \notin 2\pi\mathbb{Q}$. Equation (42) remains true if we replace $(\theta_1, \dots, \theta_q)$ with $(r\theta_1, \dots, r\theta_q)$, so we may assume that either $\theta_i \notin 2\pi\mathbb{Q}$ or $\theta_i \in \mathbb{Z}$.

Let V be the set of accumulation points of $\{(e^{in\theta_1}, \dots, e^{in\theta_q}) \mid n \in \mathbb{N}\}$. We first show that if $(z_1, \dots, z_q) \in V$, then $\Re(g_1 z_1) = 0$. This will

suffice to prove our claim if $p = 1$, since if $\theta_i \in 2\pi\mathbb{Z}$, then $z_1 = 1$ and $\Re(g_1) = 0$. If not, any $z_1 \in S^1$ can arise in such a limit, so $\Re(z_1 g_1) = 0$ for all $z_1 \in S^1$, which implies that $g_1 = 0$.

So, suppose that $\{n_m\}$ is an increasing sequence in \mathbb{N} and $\{(e^{in_m\theta_1}, \dots, e^{in_m\theta_q})\}$ converges to (z_1, \dots, z_q) . Then either

(1)

$$\Re(a_s(z_1, z_2, \dots, z_q)) = 0$$

for all s , or

(2) there exists $s_0 \in \mathbb{N}$ so that

$$\mathfrak{A}_0 = \Re(a_{s_0}(z_1, z_2, \dots, z_q)) \neq 0,$$

and for all $s < s_0$

$$\Re(a_s(z_1, z_2, \dots, z_q)) = 0.$$

If (1) holds, then Equation (42) implies

$$\lim_{m \rightarrow \infty} n_m \Re(e^{in_m\theta_1} g_1) + \epsilon_0(n_m) = 0. \quad (43)$$

where

$$\epsilon_0(n_m) = \sum_{p=2}^q n_m \left(\frac{f_p}{f_1} \right)^{n_m} \Re(e^{in_m\theta_p} g_p).$$

Since, $\lim_{m \rightarrow \infty} \Re(e^{in_m\theta_1} g_1) = \Re(z_1 g_1)$ and $\lim_{m \rightarrow \infty} \epsilon_0(n_m) = 0$, we conclude that $\Re(z_1 g_1) = 0$.

If (2) holds, then Equation (42) implies that

$$\lim_{m \rightarrow \infty} n_m \Re(z_1 g_1) + \epsilon_0(n_m) - \left(\frac{\mu_{s_0}}{f_1} \right)^{n_m} \mathfrak{A}_m (1 + \epsilon_1(n_m)) = 0$$

where

$$\begin{aligned} \mathfrak{A}_m &= \Re(a_{s_0}(e^{in_m\theta_1}, e^{in_m\theta_2}, \dots, e^{in_m\theta_q})), \\ A_{m,s} &= \frac{1}{\mathfrak{A}_m} \left(\frac{\mu_s}{\mu_{s_0}} \right)^{n_m} \Re(a_s(e^{in_m\theta_1}, \dots, e^{in_m\theta_q})), \text{ and} \\ \epsilon_1(n_m) &= \sum_{s=s_0}^{\infty} A_{m,s}. \end{aligned} \quad (44)$$

Observe that

$$\lim_{m \rightarrow \infty} \mathfrak{A}_m = \mathfrak{A}_0 \neq 0$$

If m is large enough that $|\mathfrak{A}_m| \geq \frac{1}{2}|\mathfrak{A}_0|$ and $n_m > N$, then

$$|A_{m,s}| \leq \frac{\mu_{s_0+1}^{n_m-N}}{\mu_{s_0}^{n_m}} B_s \text{ where } B_s = \frac{2}{\mathfrak{A}_0} |\mu_s|^N \|a_s\|.$$

Since $\lim_{m \rightarrow \infty} \frac{\mu_{s_0+1}^{n_m-N}}{\mu_{s_0}^{n_m}} = 0$ and $\sum_{s=1}^{\infty} B_s$ is convergent, $\lim_{n \rightarrow \infty} \epsilon_1(n_m) = 0$. It then follows that the sequence

$$\left\{ \frac{1}{n_m} \left(\frac{\mu_{s_0}}{f_1} \right)^{n_m} \right\}_{m \in \mathbb{N}}$$

is bounded. Thus $\mu_{s_0} \leq f_1$ and it follows that $\Re(z_1 g_1) = 0$.

Once we have proved that $\Re(z_1 g_1) = 0$ for all $(z_1, \dots, z_q) \in V$, we may use the same argument to prove that $\Re(z_2 g_2) = 0$ for all (z_1, z_2, \dots, z_q) and proceed iteratively to complete the proof for all p . \square

We are now ready to prove the technical lemma used in the proof of Lemma 10.7

Lemma 10.6. *Let $\{f_p\}_{p=1}^q$ and $\{\theta_p\}_{p=1}^q$ be 2 families of real analytic functions defined on $(-1, 1)$ such that*

$$1 > f_1(t) > \dots > f_q(t) > 0 \quad \text{and} \quad \dot{\theta}_q(0) = 0$$

Let $\{g_p\}_{p=1}^q$ be a family of complex valued analytic functions defined on $(-1, 1)$ so that $g_q(0) \in \mathbb{R} \setminus \{0\}$. For all $n \in \mathbb{N}$, let

$$F_n = 1 + \sum_{p=1}^q f_p^n \Re(e^{in\theta_p} g_p).$$

If there exists a constant K such that for all large enough n ,

$$\dot{F}_n(0) = K F_n(0) \log(F_n(0)).$$

Then, $\dot{f}_q(0) = 0$.

Proof. Let $g(x) = K(1+x)\log(1+x)$. Then g is analytic at 0. Consider the expansion

$$g(x) = \sum_{n \geq 0} a_n x^n$$

with radius of convergence $\delta > 0$. Notice that there exists N such that if $n \geq N$, then

$$\sum_{p=1}^q f_p(0)^n |g_p(0)| < \frac{\delta}{2}.$$

If $n \geq N$, then

$$K F_n(0) \log(F_n(0)) = g \left(\sum_{p=1}^q f_p(0)^n \Re(e^{in\theta_p(0)} g_p(0)) \right)$$

$$= \sum_{m>0} a_m \left(\sum_{p=1}^q f_p(0)^n \Re(e^{in\theta_p(0)} g_p(0)) \right)^m.$$

If we expand this out, for each q -tuple of non-negative integers $\vec{m} = (m_1, \dots, m_q)$, we get a term of the form

$$(\Pi_{p=1}^q f_p(0)^{m_p})^n \binom{m_1 + \dots + m_q}{m_1 \ m_2 \ \dots \ m_q} (\Pi_{p=1}^q (\Re(g_p(0) e^{in\theta_p(0)})^{m_p}).$$

Let

$$h_{\vec{m}} = (\Pi_{p=1}^q f_p(0)^{m_p}) < 1.$$

Using the equality $\Re(z(w + \bar{w})) = 2\Re(z)\Re(w)$ repeatedly, we may rewrite

$$\binom{m_1 + \dots + m_q}{m_1 \ m_2 \ \dots \ m_q} (\Pi_{p=1}^q (\Re(g_p(0) e^{in\theta_p})^{m_p}) = \Re(H_{\vec{m}}(e^{in\theta_1(0)}, \dots, e^{in\theta_q(0)}))$$

where $H_{\vec{m}}$ is a complex polynomial in q variables and their conjugates. With these conventions the term associated to \vec{m} has the form

$$h_{\vec{m}}^n \Re(H_{\vec{m}}(e^{in\theta_1}, \dots, e^{in\theta_q})).$$

Since the series $\sum_{\vec{m}} h_{\vec{m}}^n \|H_{\vec{m}}\|$ is convergent for all $n \geq N$, we are free to re-arrange the terms. We group all terms where the coefficient $h_{\vec{m}}$ agrees (of which there are only finitely many for each value of $h_{\vec{m}}$) and order the resulting terms in decreasing order of co-efficient to express

$$KF_n(0) \log(F_n(0)) = \sum_{s=0}^{\infty} h_s^n \Re(H_s(e^{in\theta_1}, \dots, e^{in\theta_q})),$$

where each H_s is a complex polynomial in q variables and their conjugates and $\{h_s\}_{s \in \mathbb{N}}$ is a strictly decreasing sequence of positive numbers less than 1. Moreover, for all $n \geq N$ the series

$$\sum_{s=0}^{\infty} |h_s|^n \|H_s\|$$

is convergent.

On the other hand,

$$\dot{F}_n(0) = \sum_{p=1}^q n f_p^n \Re \left(e^{in\theta_p} g_p \left(\frac{\dot{f}_p}{f_p} + i\dot{\theta}_p \right) \right) + \sum_{p=1}^q f_p^n \Re(e^{in\theta_p} \dot{g}_p)$$

where all functions on the right hand side are evaluated at 0. Since $\dot{F}_n(0) = KF_n(0) \log(F_n(0))$ we see that after reordering (and grouping

terms whose leading coefficients agree)

$$\sum_{p=1}^q n f_p^n \Re \left(e^{in\theta_p} g_p \left(\frac{\dot{f}_p}{f_p} + i\dot{\theta}_p \right) \right) = \sum_{p=1}^{\infty} \mu_p^n \Re(a_p(e^{in\theta_1}, \dots, e^{in\theta_q})),$$

where each a_s is a polynomial functions in q variables and their conjugates and $\{\mu_s\}_{s \in \mathbb{N}}$ is a strictly decreasing sequence of positive numbers less than 1. Moreover, the series $\sum_{s=1}^{\infty} |\mu_s|^n \|a_s\|$ is convergent for all $n \geq N$.

The previous lemma then implies that for all p

$$\Re \left(g_p \left(\frac{\dot{f}_p}{f_p} + i\dot{\theta}_p \right) \right) = 0$$

Since $g_q(0)$ is a non zero real number, $f_q(0) \neq 0$ and $\dot{\theta}_q(0) = 0$, we get that $\dot{f}_q(0) = 0$. \square

10.3. Degenerate vectors have log-type zero. Proposition 10.1 then follows from the following lemma and Lemma 9.4.

Lemma 10.7. *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\mathbf{SL}_m(\mathbb{R})$. If $\{\rho_u\}_{u \in D}$ is an analytic family of convex Anosov \mathbf{G} -generic homomorphisms defined on a disc D and $\mathbf{L}(\alpha)$ has log-type K at $v \in \mathbf{T}_z D$ for all infinite order $\alpha \in \Gamma$, then $K = 0$.*

Proof. Notice that if we replace the family $\{\rho_u\}_{u \in D}$ by a conjugate family $\{\rho'_u = g_u \rho_u g_u^{-1}\}_{u \in D}$ where $\{g_u\}_{u \in D}$ is an analytic family of elements of $\mathbf{SL}_m(\mathbb{R})$, then $\mathbf{L}(\alpha)(\rho_u) = \mathbf{L}(\alpha)(\rho'_u)$ for all $u \in D$. Therefore, we are free to conjugate our original family when proving the result.

By Proposition 2.16, we may choose $\beta \in \Gamma$, so that $\rho_u(\beta)$ is generic. After possibly restricting to a smaller disk about z , we may assume that $\rho_u(\beta)$ is generic for all $u \in D$. We may then conjugate the family so that $\rho_u(\beta)$ lies in the same maximal torus for all u , we can write

$$\rho_u(\beta^n) = \mathbf{L}(\beta)^n \mathbf{p} + \sum_{p=1}^{q-1} \lambda_p^n (\cos(n\theta_p) \mathbf{p}_p + \sin(n\theta_p) \widehat{\mathbf{p}}_p) + \frac{1}{\mathbf{L}(\beta^{-1})} \mathbf{q},$$

where $\mathbf{L}(\beta)$, $\mathbf{L}(\beta^{-1})$, λ_p , and θ_p are analytic functions of u .

Choose an infinite order element $\alpha \in \Gamma$ which is coprime to β . Proposition 10.4, implies that, for all n ,

$$\begin{aligned} \frac{\mathbf{T}(\mathbf{p}(\alpha), \beta^n)}{\mathbf{L}(\beta^n) \overline{\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))}} &= 1 + \left(\frac{1}{\mathbf{L}(\beta) \mathbf{L}(\beta^{-1})} \right)^n \left(\frac{\mathbf{Tr}(\mathbf{p}(\rho(\alpha)) \mathbf{q})}{\overline{\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))}} \right) \\ &+ \sum_{p=1}^{q-1} \left(\frac{\lambda_p}{\mathbf{L}(\beta)} \right)^n \Re \left(e^{in\theta_p} \left(\frac{\mathbf{Tr}(\mathbf{p}(\rho(\alpha)) \mathbf{p}_p)}{\overline{\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))}} + i \frac{\mathbf{Tr}(\mathbf{p}(\rho(\alpha)) \widehat{\mathbf{p}}_p)}{\overline{\mathbf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))}} \right) \right). \end{aligned}$$

has log-type K at v , since the numerator has log-type K at v and the denominator is a product of two functions which have log-type K at v .

Since α and β are coprime and ρ is convex Anosov, $\xi(\beta^-) \oplus \theta(\alpha^-) = \mathbb{R}^m$, so $\text{Tr}(\mathbf{p}(\rho(\alpha)), \mathbf{q}) \neq 0$ (since $\mathbf{p}(\rho(\alpha))$ is a projection onto the line $\xi(\alpha^+)$ parallel to $\theta(\alpha^-)$ and $\mathbf{q} = \mathbf{q}(\rho(\beta))$ is a projection onto the line $\xi(\beta^-)$). Similarly, $\text{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta)) \neq 0$, since $\xi(\beta^+) \oplus \theta(\alpha^-) = \mathbb{R}^m$.

Let $\{u_s\}_{s \in (-1,1)}$ be a smooth family in D so that $u_0 = z$ and $\dot{u}_0 = v$. We now apply Lemma 10.6, taking

$$\begin{aligned} f_p(s) &= \frac{\lambda_p(u_s)}{\mathbf{L}(\beta)(u_s)}, \\ g_p(s) &= \left(\frac{\text{Tr}(\mathbf{p}(\rho_{u_s}(\alpha))\mathbf{p}_p)}{\text{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))(u_s)} + i \frac{\text{Tr}(\mathbf{p}(\rho_{u_s}(\alpha))\widehat{\mathbf{p}}_p)}{\text{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))(u_s)} \right), \end{aligned}$$

if $p = 1, \dots, q-1$, and taking

$$\begin{aligned} f_q(s) &= \frac{1}{\mathbf{L}(\beta)(u_s)\mathbf{L}(\beta^{-1})(u_s)}, \\ g_q(s) &= \frac{\text{Tr}(\mathbf{p}(\rho_{u_s}(\alpha))\mathbf{q})}{\text{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta))(u_s)}, \text{ and} \\ \theta_q(s) &= 0. \end{aligned}$$

We conclude from Lemma 10.6 that $\dot{f}_q = 0$. Thus

$$D_z \mathbf{L}(\beta)(v) \cdot \mathbf{L}(\beta^{-1})(z) = -\mathbf{L}(\beta)(z) \cdot D_z \mathbf{L}(\beta^{-1})(v). \quad (45)$$

Since $\mathbf{L}(\beta)$ and $\mathbf{L}(\beta^{-1})$ both have log-type K at v , we get that

$$\frac{D_z \mathbf{L}(\beta)(v)}{\mathbf{L}(\beta)(z)} = K \log(\mathbf{L}(\beta)(z)) \quad \text{and} \quad \frac{D_z \mathbf{L}(\beta^{-1})(v)}{\mathbf{L}(\beta^{-1})(z)} = K \log(\mathbf{L}(\beta^{-1})(z)). \quad (46)$$

Combining (45) and (46) we see that

$$K \log(\mathbf{L}(\beta)(z)) = \frac{D_z \mathbf{L}(\beta)(v)}{\mathbf{L}(\beta)(z)} = -\frac{D_z \mathbf{L}(\beta^{-1})(v)}{\mathbf{L}(\beta^{-1})(z)} = -K \log(\mathbf{L}(\beta^{-1})(z)).$$

Since $\log \mathbf{L}(\beta) > 0$ and $\log \mathbf{L}(\beta^{-1}) > 0$, this implies that $K = 0$. \square

11. VARIATION OF LENGTH AND COHOMOLOGY CLASSES

The aim of this section is to prove the following proposition.

Proposition 11.1. *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\text{SL}_m(\mathbb{R})$. Suppose that $\eta : D \rightarrow \text{Hom}(\Gamma, \mathbf{G})$ is an analytic map such that for each $u \in D$, $\eta(u) = \rho_u$ is convex, irreducible and \mathbf{G} -generic. If $v \in \text{T}_z D$ and*

$$D\mathbf{L}(\alpha)(v) = 0$$

for all infinite order elements $\alpha \in \Gamma$, then $D\eta(v)$ defines a zero cohomology class in $H_{\eta(z)}^1(\Gamma, \mathfrak{g})$.

We recall that $D\eta(v)$ defines a zero cohomology class in $H_{\eta(z)}^1(\Gamma, \mathfrak{g})$ if and only if it is tangent to the orbit $\mathbf{G}\eta(z)$ in $\text{Hom}(\Gamma, \mathbf{G}) \subset \mathbf{G}^r$.

As a Corollary of Propositions 10.1 and 11.1 we obtain:

Corollary 11.2. *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\text{SL}_m(\mathbb{R})$. Suppose that $\eta : D \rightarrow \tilde{\mathcal{C}}_g(\Gamma, \mathbf{G})$ is an analytic map and \mathbf{p} is the associated pressure form on D . If $v \in \mathbf{T}_z D$ and*

$$\mathbf{p}(v, v) = 0,$$

then $D\eta(v)$ defines a zero cohomology class in $H_{\eta(z)}^1(\Gamma, \mathfrak{g})$.

In the course of the proof of Proposition 11.1 we also obtain the following fact which is of independent interest.

Proposition 11.3. *Suppose that \mathbf{G} is a reductive subgroup of $\text{SL}_m(\mathbb{R})$ and $\rho \in \mathcal{C}_g(\Gamma, \mathbf{G})$. Then the set*

$$\{DL(\alpha) \mid \alpha \text{ infinite order in } \Gamma\},$$

generates the cotangent space $\mathbf{T}_\rho \mathcal{C}_g(\Gamma, \mathbf{G})$.

Both propositions will be established in section 11.3.

11.1. Invariance of the cross-ratio. We recall the definition of the *cross ratio* of a pair of hyperplanes and a pair of lines. First define

$$\mathbb{RP}(m)^{(4)} = \{(\varphi, \psi, u, v) \in \mathbb{RP}(m)^{*2} \times \mathbb{RP}(m)^2 : (\varphi, v) \text{ and } (\psi, u) \text{ span } \mathbb{R}^m\}.$$

We then define $\mathbf{b} : \mathbb{RP}(m)^{(4)} \rightarrow \mathbb{R}$ by

$$\mathbf{b}(\varphi, \psi, u, v) = \frac{\langle \varphi | u \rangle \langle \psi | v \rangle}{\langle \varphi | v \rangle \langle \psi | u \rangle}.$$

Notice that for this formula to make sense we must make choices of elements in φ , ψ , u , and v , but that the result is independent of our choices.

If ρ is a convex Anosov representation with limit curves $\xi : \partial_\infty \Gamma \rightarrow \mathbb{RP}(m)$ and $\theta : \partial_\infty \Gamma \rightarrow \mathbb{RP}(m)^*$, we define the associated *cross ratio* on $\partial_\infty \Gamma^{(4)}$, as in [33], to be

$$\mathbf{b}_\rho(x, y, z, w) = \mathbf{b}(\theta(x), \theta(y), \xi(z), \xi(w)). \quad (47)$$

We first derive a formula for the cross-ratio at points associated to co-prime elements. This formula generalizes the formula in Corollary 1.6 from Benoist [4].

Proposition 11.4. *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex Anosov representation and α and β are infinite order co-prime elements of Γ , then*

$$\mathbf{b}_\rho(\alpha^-, \beta^-, \beta^+, \alpha^+) = \mathsf{T}(\mathbf{p}(\alpha), \mathbf{p}(\beta)) = \lim_{n \rightarrow \infty} \frac{\mathsf{L}(\alpha^n \beta)}{\mathsf{L}(\alpha)^n}.$$

Proof. Choose $a^+ \in \xi(\alpha^+)$, $a^- \in \theta(\alpha^-)$, $b^+ \in \xi(\beta^+)$ and $b^- \in \theta(\beta^-)$. Observe that

$$\mathbf{p}(\alpha)(u) = \frac{\langle a^- | u \rangle}{\langle a^- | a^+ \rangle} a^+.$$

for all $u \in \mathbb{R}^m$. In particular,

$$\mathbf{p}(\beta)\mathbf{p}(\alpha)(u) = \frac{\langle b^- | a^+ \rangle}{\langle a^- | a^+ \rangle \langle b^- | b^+ \rangle} \langle a^- | u \rangle b^+.$$

Therefore,

$$\mathsf{T}(\mathbf{p}(\alpha)\mathbf{p}(\beta)) = \frac{\langle a^- | b^+ \rangle \langle b^- | a^+ \rangle}{\langle a^- | a^+ \rangle \langle b^- | b^+ \rangle} = \mathbf{b}_\rho(\alpha^-, \beta^-, \beta^+, \alpha^+).$$

The last equality in the formula follows immediately from Proposition 10.4. \square

As a corollary, we see that if $\mathsf{L}(\alpha)$ has log-type zero for all infinite order $\alpha \in \Gamma$, then the cross-ratio also has log-type zero.

Corollary 11.5. *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$. Suppose that $\{\rho_u : \Gamma \rightarrow \mathbf{G}\}_{u \in D}$ is an analytic family of convex Anosov \mathbf{G} -generic homomorphisms parametrized by a disc D . If $\mathsf{L}(\alpha)$ has log-type 0 at $v \in \mathsf{T}_z D$ for all infinite order $\alpha \in \Gamma$, then for all distinct collections of points $x, y, z, w \in \partial_\infty \Gamma$, the function*

$$u \mapsto \mathbf{b}_{\rho_u}(x, y, z, w),$$

is of log-type 0 at v .

Proof. Suppose that $\alpha, \beta \in \Gamma$ have infinite order. Propositions 10.4 and 11.4 imply that $\mathbf{b}_\rho(\alpha^-, \beta^-, \beta^+, \alpha^+)$ has log-type 0.

Since pairs of fixed points of infinite order elements are dense in $\partial_\infty \Gamma^{(2)}$ and ξ_u and θ_u vary analytically by Proposition 8.1, we see that

$$\rho \mapsto \mathbf{b}_\rho(x, y, z, w),$$

has log-type 0 for all pairwise distinct $x, y, z, w \in \partial_\infty \Gamma$. \square

11.2. An useful immersion. We define a mapping from $\mathrm{PSL}_m(\mathbb{R})$ into a quotient $W(m)$ of the vector space \mathbf{M}^{m+1} of all $(m+1) \times (m+1)$ -matrices and use it to encode a collection of cross ratios.

Consider the action of the multiplicative group $(\mathbb{R} \setminus \{0\})^{2(m+1)}$ on \mathbf{M}^{m+1} given by

$$(a_0, \dots, a_m, b_0, \dots, b_m)(M_{i,j}) = (a_i b_j M_{i,j}).$$

We denote the quotient by

$$W(m) = \mathbf{M}^{m+1} / (\mathbb{R} \setminus \{0\})^{2(m+1)}.$$

Given a projective frame $F = (x_0, \dots, x_m)$ for $\mathbb{RP}(m)$ and a projective frame $F^* = (X_0, \dots, X_m)$ for the dual $\mathbb{RP}(m)^*$, let

- \hat{x}_i be non zero vectors in x_i , such that

$$0 = \sum_{i=0}^m \hat{x}_i, \tag{48}$$

- \hat{X}_i be non zero covectors in X_i such that

$$0 = \sum_{i=0}^m \hat{X}_i. \tag{49}$$

Observe that \hat{x}_i , respectively \hat{X}_i , are uniquely defined up to a common multiple. Then, the mapping

$$\mu_{F,F^*} : \mathrm{PSL}_m(\mathbb{R}) \rightarrow W(m)$$

given by

$$\mu_{F,F^*} : A \mapsto \hat{X}_i(A(\hat{x}_j))$$

is well defined, independent of the choice of \hat{x}_i and \hat{X}_i .

Lemma 11.6. *The mapping μ_{F,F^*} is a smooth injective immersion.*

Proof. Since $\mu_{F,F^*}(A)$ determines the projective coordinates of the image of the projective frame (x_0, \dots, x_n) by A , μ_{F,F^*} is injective.

Let $\mu = \mu_{F,F^*}$. Let $\{A_t\}_{t \in (-1,1)}$ be a smooth one-parameter family in $\mathrm{PSL}_m(\mathbb{R})$ such that

$$\dot{A} \in T_{A_0}(\mathrm{PSL}_m(\mathbb{R})) \quad \text{and} \quad D\mu(\dot{A}) = 0.$$

Let $\{\hat{X}_i^t\}_{t \in (-1,1)}$ and $\{\hat{x}_j^t\}_{t \in (-1,1)}$ be time dependent families of covectors in X_i and vectors x_j respectively, and let

$$a_{i,j}^t = \hat{X}_i^t(A_t(\hat{x}_j^t)).$$

If $D\mu(\dot{A}) = 0$, then there exists λ_i and μ_j such that

$$\dot{a}_{i,j} = \lambda_i a_{i,j} + \mu_j a_{i,j}.$$

Multiplying each \hat{X}_i^t by $e^{-\lambda_0 t}$ and each \hat{x}_i^t by $e^{-\mu_0 t}$ has the effect of replacing λ_i and μ_j by $\lambda_i - \lambda_0$ and $\mu_j - \mu_0$ respectively. Thus, we may assume that $\lambda_0 = \mu_0 = 0$.

We now use the normalization (48) and (49), to see that

$$\sum_{i=1}^m \lambda_i a_{i,j} = 0 = \sum_{j=1}^m \mu_j a_{i,j}.$$

On the other hand, since the collections of vectors $\{a_i = (a_{i,j})_{1 \leq j \leq m}\}$ and $\{b_j = (a_{i,j})_{1 \leq i \leq m}\}$ are linearly independent, this implies that $\lambda_i = \mu_j = 0$ for all i and j . \square

The following lemma relates the immersion μ and the cross ratio.

Lemma 11.7. *Let $\{x_0, \dots, x_m\}$ and $\{y_0, \dots, y_m\}$ be collections of $m+1$ pairwise distinct points in $\partial_\infty \Gamma$. Suppose that $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is convex Anosov with limit maps ξ and θ and that*

$$\begin{aligned} F &= (\xi(x_0), \dots, \xi(x_m)), \\ F^* &= (\theta(y_0), \dots, \theta(y_m)). \end{aligned}$$

are projective frames for $\mathbb{RP}(m)$ and $\mathbb{RP}(m)^*$. If $\alpha \in \Gamma$, then

$$\mu_{F, F^*}(\pi_m(\rho(\alpha))) = [b_\rho(y_i, z, \alpha(x_j), w)]$$

where z and w are arbitrary points in $\partial_\infty \Gamma$.

Proof. Choose, for each $i = 0, \dots, m$, $\phi_i \in \theta(y_i)$ and $v_i \in \xi(x_i)$, and choose $\phi \in \theta(z)$ and $v \in \xi(w)$. Then

$$\mu_{F, F^*}(\pi_m(\rho(\alpha))) = [\langle \phi_i | \alpha(v_j) \rangle]$$

while

$$[b_\rho(y_i, z, \alpha(x_j), w)] = \left[\frac{\langle \phi_i | \alpha(v_j) \rangle \langle \phi | v \rangle}{\langle \phi_i | v \rangle \langle \phi | v_j \rangle} \right].$$

The equivalence is given by taking $a_i = \frac{\langle \phi | v \rangle}{\langle \phi_i | v \rangle}$ and $b_j = \frac{1}{\langle \phi | v_j \rangle}$. \square

11.3. Vectors with log type zero. Propositions 11.1 and 11.3 follow from Proposition 10.1 and the following lemma.

Lemma 11.8. *Let Γ be a word hyperbolic group and let \mathbf{G} be a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$. Suppose that $\eta : D \rightarrow \mathrm{Hom}(\Gamma, \mathbf{G})$ is an analytic map such that for each $u \in D$, $\eta(u) = \rho_u$ is convex, irreducible and \mathbf{G} -generic. Suppose that $v \in \mathbb{T}_z D$ and that $D_z \mathbf{L}(\alpha)(v) = 0$ for all infinite order $\alpha \in \Gamma$. Then the cohomology class of $D\eta(v)$ vanishes in $H_{\eta(z)}^1(\Gamma, \mathfrak{g})$.*

Proof. Let $\{u_t\}_{t \in (-1,1)}$ be a path in D so that $u_0 = z$ and $\dot{u}_0 = v$. Let $\rho_t = \rho_{u_t}$. By Corollary 11.5,

$$\left. \frac{d}{dt} \right|_{t=0} (b_{\rho_t}(x, y, z, w)) = 0$$

for any pairwise distinct (x, y, z, w) in $\partial_\infty \Gamma$.

Lemma 2.12 allows us to choose collections $\{x_0, \dots, x_m\}$ and $\{y_0, \dots, y_m\}$ of pairwise distinct points in $\partial_\infty \Gamma$ such that if

$$\begin{aligned} F_t &= (\xi_t(x_0), \dots, \xi_t(x_m)), \\ F_t^* &= (\theta_t(y_0), \dots, \theta_t(y_m)). \end{aligned}$$

then F_0 and F_0^* are both projective frames. For some $\epsilon > 0$, F_t and F_t^* are projective frames for all $t \in (-\epsilon, \epsilon)$. (We will restrict to this domain for the remainder of the argument.) We may then normalize, by conjugating ρ_t by an appropriate element of $\mathbf{SL}_m(\mathbb{R})$, so that $F_t = F_0$ for all $t \in (-\epsilon, \epsilon)$.

Let

$$\mu_t = \mu_{F_t, F_t^*} \circ \pi_m.$$

Then, by Lemma 11.7,

$$\mu_t(\rho_t(\alpha)) = [b_{\rho_t}(x_i, z, \alpha(y_j), w)]$$

for all $\alpha \in \Gamma$. Therefore,

$$\left. \frac{d}{dt} \right|_{t=0} \mu_t(\rho_t(\alpha)) = 0.$$

for all $\alpha \in \Gamma$. Notice that if χ and χ^* are projective frames, then

$$\mu_{\chi, B^* \chi^*}(A) = \mu_{\chi, \chi^*}(B^{-1} \circ A),$$

for all $A, B \in \mathbf{SL}_m(\mathbb{R})$. If we choose $C_t \in \mathbf{SL}_m(\mathbb{R})$ so that $(C_t^{-1})^*(F_t^*) = F_0^*$, then

$$\begin{aligned} 0 &= \left. \frac{d}{dt} \right|_{t=0} (\mu_t(\rho_t(\alpha))) = \left. \frac{d}{dt} \right|_{t=0} (\mu_0(C_t \rho_t(\alpha))) \\ &= D\mu_0 \left(\left. \frac{d}{dt} \right|_{t=0} (C_t \circ \rho_t(\alpha)) \right). \end{aligned}$$

Lemma 11.6 implies that μ_0 is an immersion, so

$$\left. \frac{d}{dt} \right|_{t=0} (C_t \circ \rho_t(\alpha)) = 0$$

Thus,

$$C_0 \circ \left. \frac{d}{dt} \right|_{t=0} \rho_t(\alpha) + \dot{C}_0 \circ \rho(\alpha) = 0. \quad (50)$$

Taking $\alpha = \text{id}$ in Equation (50), we see that $\dot{C}_0 = 0$. Since $C_0 = I$,

$$\left. \frac{d}{dt} \right|_{t=0} \rho_t(\alpha) = 0$$

for all $\alpha \in \Gamma$. Therefore the cohomology class of $D\eta(v)$ vanishes in $H_{\eta(z)}^1(\Gamma, \mathfrak{sl}_m(\mathbb{R}))$. Since \mathbf{G} is a reductive subgroup of $\mathbf{SL}_m(\mathbb{R})$, $\mathfrak{sl}_m\mathbb{R} = \mathfrak{g} \oplus \mathfrak{g}^\perp$, so $H_{\eta(z)}^1(\Gamma, \mathfrak{g})$ injects into $H_{\eta(z)}^1(\Gamma, \mathfrak{sl}_m(\mathbb{R}))$. Therefore, $D\eta(v)$ vanishes in $H_{\eta(z)}^1(\Gamma, \mathfrak{g})$ as claimed. \square

12. RIGIDITY RESULTS

In this section, we establish two rigidity results for convex Anosov representations. We first establish Theorem 1.2 which states that the signed spectral radii determine the limit map of a convex Anosov representation, up to the action of $\mathbf{SL}_m(\mathbb{R})$, and that they determine the conjugacy class, in $\mathbf{GL}_m(\mathbb{R})$, of a convex irreducible representation.

Theorem 12.1. [SPECTRAL RIGIDITY] *Let Γ be a word hyperbolic group and let $\rho_1 : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathbf{SL}_m(\mathbb{R})$ be convex Anosov representations such that*

$$\mathbf{L}(\gamma)(\rho_1) = \mathbf{L}(\gamma)(\rho_2)$$

for all infinite order $\gamma \in \Gamma$. Then there exists $g \in \mathbf{GL}_m(\mathbb{R})$ such that $g \circ \xi_1 = \xi_2$.

Moreover, if ρ_1 is irreducible, then $\rho_2 = g\rho_1g^{-1}$.

We next establish our rigidity result for renormalised intersection. We denote by π_m the projection from $\mathbf{SL}_m(\mathbb{R})$ to $\mathbf{PSL}_m(\mathbb{R})$. If \mathbf{H} is a Zariski closed subgroup of \mathbf{G} , let \mathbf{H}^0 denote the connected component of the identity of the group \mathbf{H} and $Z(\mathbf{H})$ its center.

Theorem 12.2. [INTERSECTION RIGIDITY] *Suppose that Γ is a word hyperbolic group and $\rho_1 : \Gamma \rightarrow \mathbf{SL}_{m_1}(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathbf{SL}_{m_2}(\mathbb{R})$ are convex Anosov representations such that*

$$\mathbf{J}(\rho_1, \rho_2) = 1.$$

If the Zariski closures \mathbf{G}_1 and \mathbf{G}_2 of $\rho_1(\Gamma)$ and $\rho_2(\Gamma)$ are simple, and Γ_0 is the finite index subgroup of Γ defined by

$$\Gamma_0 = \Gamma \cap \rho_1^{-1}(\mathbf{G}_1^0) \cap \rho_2^{-1}(\mathbf{G}_2^0),$$

then there exists a group isomorphism

$$g : \mathbf{G}_1^0/Z(\mathbf{G}_1^0) \rightarrow \mathbf{G}_2^0/Z(\mathbf{G}_2^0)$$

such that

$$g \circ \bar{\rho}_1|_{\Gamma_0} = \bar{\rho}_2|_{\Gamma_0}$$

where $Z(\mathbf{G}_i)$ is the center of \mathbf{G}_i and $\bar{\rho}_i : \Gamma \rightarrow \mathbf{G}_i/Z(\mathbf{G}_i)$ is the composition of ρ_i and the projection from \mathbf{G}_i to $\mathbf{G}_i/Z(\mathbf{G}_i)$.

If ρ_1 and ρ_2 are both irreducible, then

$$\mathbf{G}_i^0/Z(\mathbf{G}_i^0) = \pi_{m_i}(\mathbf{G}_i^0) \quad \text{and} \quad \bar{\rho}_i = \pi_{m_i} \circ \rho_i.$$

Remarks: (1) If \mathbf{G}_1^0 and \mathbf{G}_2^0 are simple, but not isomorphic, then Theorem 12.2 implies that $\mathbf{J}(\rho_1, \rho_2) > 1$.

(2) The representations need not actually be conjugate if $\mathbf{J}(\rho_1, \rho_2) = 1$. Let $\rho : \pi_1(\Sigma) \rightarrow \mathrm{PSL}_2(\mathbb{R})$ be a Fuchsian representation. If $\tau_m : \mathrm{PSL}_2(\mathbb{R}) \rightarrow \mathrm{PSL}_m(\mathbb{R})$ and $\tau_n : \mathrm{PSL}_2(\mathbb{R}) \rightarrow \mathrm{PSL}_n(\mathbb{R})$ are irreducible representations, with $m \neq n$, then $\mathbf{J}(\tau_n \circ \rho, \tau_m \circ \rho) = 1$.

12.1. Spectral rigidity. Our spectral rigidity theorem will follow from Proposition 11.4 and work of Labourie [33].

Recall, from Section 11.1, that we defined the cross ratio \mathbb{B} of a pair of hyperplanes and a pair of lines. Then, given a convex Anosov representation ρ with limit maps ξ and θ , we defined a cross-ratio b_ρ on $\partial_\infty \Gamma^{(4)}$ by letting

$$b_\rho(x, y, z, w) = \mathbf{b}(\theta(x), \theta(y), \xi(z), \xi(w)). \quad (51)$$

Labourie [33, Theorem 5.1] showed that if ρ is a convex Anosov representation with limit map ξ , then the dimension $\dim \langle \xi(\partial_\infty \Gamma) \rangle$ can be read directly from the cross ratio b_ρ . (In [33], Labourie explicitly handles the case where $\Gamma = \pi_1(S)$, but his proof generalizes immediately.) Consider S_*^p the set of pairs $(e, u) = (e_0, \dots, e_p, u_0, \dots, u_p)$ of $(p+1)$ -tuples in $\partial_\infty \Gamma$ such that $e_j \neq e_i \neq u_0$ and $u_j \neq u_i \neq e_0$ when $j > i > 0$. If $(e, u) \in S_*^p$, he defines

$$\chi_{b_\rho}^p(e, u) = \det_{i,j>0} (b_\rho(e_i, e_0, u_j, u_0)).$$

Lemma 12.3. *If $\rho : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ is a convex Anosov representation, then $\dim \langle \xi(\partial_\infty \Gamma) \rangle = \inf \{p \in \mathbb{N} : \chi_{b_\rho}^p \equiv 0\} - 1$.*

Lemma 4.3 of Labourie [33] extends in our setting to give:

Lemma 12.4. *If $\rho_1 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ are convex Anosov representations such that $b_{\rho_1} = b_{\rho_2}$, then there exists $g \in \mathrm{GL}_m(\mathbb{R})$ such that $g \circ \xi_1 = \xi_2$.*

Moreover, if ρ_1 is irreducible, then $g(\pi_m \circ \rho_1)g^{-1} = \pi_m \circ \rho_2$.

Proof. Lemma 12.3 implies that

$$\dim \langle \xi_1(\partial_\infty \Gamma) \rangle = \dim \langle \xi_2(\partial_\infty \Gamma) \rangle = p.$$

Choose $\{x_0, \dots, x_p\} \subset \partial_\infty \Gamma$ so that

$$\{\xi_1(x_0), \dots, \xi_1(x_p)\} \quad \text{and} \quad \{\xi_2(x_0), \dots, \xi_2(x_p)\}$$

are projective frames for $\langle \xi_1(\partial_\infty \Gamma) \rangle$ and $\langle \xi_2(\partial_\infty \Gamma) \rangle$ (see Lemma 2.11).

Choose $u_0 \in \xi_1(x_0)$ and $\{\varphi_1, \dots, \varphi_p\} \subset (\mathbb{R}^m)^*$ such that $\varphi_i \in \theta_1(x_i)$ and $\varphi_i(u_0) = 1$. One may check that $\{\varphi_1, \dots, \varphi_p\}$ is a basis for $\langle \theta_1(\partial_\infty \Gamma) \rangle$. Complete $\{\varphi_1, \dots, \varphi_p\}$ to a basis

$$\mathcal{B}_1 = \{\varphi_1, \dots, \varphi_p, \varphi_{p+1}, \dots, \varphi_m\}$$

for $(\mathbb{R}^m)^*$ such that $\varphi_i(\langle \xi_1(\partial_\infty \Gamma) \rangle) = 0$ for all $i > p$. For $y \in \partial_\infty \Gamma$, the projective coordinates of $\xi_1(y)$ with respect to the dual basis of \mathcal{B}_1 are given by

$$[\dots : \langle \varphi_i | \xi_1(y) \rangle : \dots] = [\dots : \frac{\langle \varphi_i | \xi_1(y) \rangle}{\langle \varphi_1 | \xi_1(y) \rangle} \frac{\langle \varphi_1 | u_0 \rangle}{\langle \varphi_i | u_0 \rangle} : \dots]$$

which reduces to

$$[b_{\rho_1}(x_1, x_1, y, x_0), \dots, b_{\rho_1}(x_p, x_1, y, x_0), 0, \dots, 0].$$

Now choose $v_0 \in \xi_2(x_0)$ and $\{\psi_1, \dots, \psi_p\}$ such that $\psi_i \in \theta_2(x_i)$ and $\psi_i(v_0) = 1$. One sees that $\{\psi_1, \dots, \psi_p\}$ is a basis of $\langle \theta_2(\partial_\infty \Gamma) \rangle$. One can then complete $\{\psi_1, \dots, \psi_p\}$ to a basis

$$\mathcal{B}_2 = \{\psi_1, \dots, \psi_p, \psi_{p+1}, \dots, \psi_m\}$$

for $(\mathbb{R}^m)^*$ such that $\psi_i(\langle \xi_2(\partial_\infty \Gamma) \rangle) = 0$ for all $i > p$. One checks, as above, that if $y \in \partial_\infty \Gamma$, then the projective coordinates $\xi_2(y)$ with respect to the dual basis of \mathcal{B}_2 are given by

$$[b_{\rho_2}(x_1, x_1, y, x_0), \dots, b_{\rho_2}(x_p, x_1, y, x_0), 0, \dots, 0].$$

We now choose $g \in \mathrm{GL}_m(\mathbb{R})$ so that $g\varphi_i = \psi_i$ for all i . It follows from the fact that $b_{\rho_1}(x_i, x_1, y, x_0) = b_{\rho_2}(x_i, x_1, y, x_0)$ for all $i \leq p$, that $g \circ \xi_1 = \xi_2$.

Assume now that ρ_1 is irreducible, so that $p = m$. Lemma 2.11 implies that there exists a $(m+1)$ -tuple (x_0, \dots, x_m) of points in $\partial_\infty \Gamma$ such that $F = (\xi_1(x_0), \dots, \xi_1(x_m))$ is a projective frame for $\mathbb{RP}(m)$ and $F^* = (\theta_1(x_0), \dots, \theta_1(x_m))$ is a projective frame for $\mathbb{RP}(m)^*$. Thus, using the notation of Lemma 11.7, we have that, given arbitrary distinct points $z, w \in \partial_\infty \Gamma$,

$$\mu_{F, F^*}(\pi_m(\rho_1(\gamma))) = [b_{\rho_1}(x_i, z, \gamma(x_j), w)]$$

Similarly

$$\mu_{F, F^*}(g^{-1}\pi_m(\rho_2(\gamma))g) = \mu_{gF, gF^*}(\pi_m(\rho_2(\gamma))) = [b_{\rho_2}(x_i, z, \gamma(x_j), w)]$$

Thus, since $b_{\rho_1} = b_{\rho_2}$,

$$\mu_{F, F^*}(\rho_1(\gamma)) = \mu_{F, F^*}(g^{-1}\rho_2(\gamma)g).$$

Since μ_{F, F^*} is injective, see Lemma 11.6, it follows that

$$g(\pi_m \circ \rho_1)g^{-1} = \pi_m \circ \rho_2.$$

□

We can now prove our spectral rigidity theorem:

Proof of theorem 12.1. Consider two convex Anosov representations $\rho_1, \rho_2 : \Gamma \rightarrow \mathrm{SL}_m(\mathbb{R})$ such that $\mathrm{L}(\gamma)(\rho_1) = \mathrm{L}(\gamma)(\rho_2)$ for all $\gamma \in \Gamma$. Suppose that α and β are infinite order, co-prime elements of Γ . Lemma 11.4 implies that

$$\begin{aligned} b_{\rho_1}(\beta^-, \alpha^-, \alpha^+, \beta^+) &= \lim_{n \rightarrow \infty} \frac{\mathrm{L}(\alpha^n \beta^n)(\rho_1)}{\mathrm{L}(\alpha)(\rho_1)^n \mathrm{L}(\beta)(\rho_1)^n} \\ &= \lim_{n \rightarrow \infty} \frac{\mathrm{L}(\alpha^n \beta^n)(\rho_2)}{\mathrm{L}(\alpha)(\rho_2)^n \mathrm{L}(\beta)(\rho_2)^n} \\ &= b_{\rho_2}(\beta^-, \alpha^-, \alpha^+, \beta^+). \end{aligned}$$

Since pairs of fixed points of infinite order elements of Γ are dense in $\partial_\infty \Gamma^{(2)}$ [22] and b_{ρ_1} and b_{ρ_2} are continuous, we see that $b_{\rho_1} = b_{\rho_2}$.

Lemma 12.4 implies that there exists $g \in \mathrm{GL}_m(\mathbb{R})$ such that $g \circ \xi_1 = \xi_2$. If ρ_1 is irreducible, then Lemma 12.4 guarantees that $g(\pi_m \circ \rho_1)g^{-1} = \pi_m \circ \rho_2$, so

$$\pi_m \circ (g\rho_1g^{-1}) = \pi_m \circ \rho_2.$$

Notice that if A and B are proximal matrices such that $\pi(A) = \pi(B)$ and that the eigenvalues of A and B of maximal absolute value have the same sign, then $A = B$. Therefore, if α is any infinite order element of Γ , $g\rho_2(\alpha)g^{-1} = \rho_1(\alpha)$. It follows that $g\rho_2g^{-1} = \rho_1$ as claimed. □

12.2. Renormalized intersection rigidity. In the proof of renormalized intersection rigidity we will make use of the following dichotomy for simple Lie groups (see Dal’Bo-Kim [18] or Labourie [36, Prop. 5.3.6]).

Proposition 12.5. *Suppose that Γ is a group and that \mathbf{G}_1 and \mathbf{G}_2 are connected simple Lie groups. If $\rho_1 : \Gamma \rightarrow \mathbf{G}_1$ and $\rho_2 : \Gamma \rightarrow \mathbf{G}_2$ are Zariski dense representation, then either*

- (1) $\rho_1 \times \rho_2 : \Gamma \rightarrow \mathbf{G}_1 \times \mathbf{G}_2$ is Zariski dense, or
- (2) there exists an isomorphism

$$g : \mathbf{G}_1/Z(\mathbf{G}_1) \rightarrow \mathbf{G}_2/Z(\mathbf{G}_2)$$

such that

$$g \circ \bar{\rho}_1 = \bar{\rho}_2$$

where $Z(\mathbf{G}_i)$ is the center of \mathbf{G}_i and $\bar{\rho}_i : \Gamma \rightarrow \mathbf{G}_i/Z(\mathbf{G}_i)$ is the composition of ρ_i and the projection from \mathbf{G}_i to $\mathbf{G}_i/Z(\mathbf{G}_i)$.

If \mathbf{G} is a semi-simple Lie group, let $\mathfrak{a}_{\mathbf{G}}$ be a Cartan subspace of the Lie algebra \mathfrak{g} of \mathbf{G} and let $\mathfrak{a}_{\mathbf{G}}^+$ be a Weyl Chamber. Let $\mu : \mathbf{G} \rightarrow \mathfrak{a}_{\mathbf{G}}^+$ be the Jordan projection.

For a subgroup \mathbf{H} of \mathbf{G} the *limit cone* $\mathcal{L}_{\mathbf{H}}$ of \mathbf{H} is the smallest closed cone in $\mathfrak{a}_{\mathbf{G}}^+$ generated by

$$\{\mu(h) : h \in \mathbf{H}\}.$$

Benoist [3] proved that Zariski dense subgroups have limit cones with non-empty interior.

Theorem 12.6. [BENOIST] *If Γ is a Zariski dense subgroup of a semi-simple Lie group \mathbf{G} , then \mathcal{L}_{Γ} has non empty interior.*

Proof of Theorem 12.2. Let $\rho_1 : \Gamma \rightarrow \mathrm{PSL}_{m_1}(\mathbb{R})$ and $\rho_2 : \Gamma \rightarrow \mathrm{PSL}_{m_2}(\mathbb{R})$ be convex Anosov representations such that $\mathbf{J}(\rho_1, \rho_2) = 1$. Let \mathbf{G}_1 and \mathbf{G}_2 be the Zariski closures of $\rho_1(\Gamma)$ and $\rho_2(\Gamma)$. Since each ρ_i has finite kernel and each \mathbf{G}_i has finitely many components,

$$\Gamma_0 = \rho_1^{-1}(\mathbf{G}_1^0) \cap \rho_2^{-1}(\mathbf{G}_2^0)$$

has finite index in Γ . Therefore, $\rho_1|_{\Gamma_0}$ and $\rho_2|_{\Gamma_0}$ are both convex Anosov (see [24, Cor. 3.4]). Since, by Corollary 9.2, there exists c so that

$$\Lambda(\gamma)(\rho_1)^c = \Lambda(\gamma)(\rho_2)$$

for all $\gamma \in \Gamma$, we see that $\mathbf{J}(\rho_1|_{\Gamma_0}, \rho_2|_{\Gamma_0}) = 1$. Therefore, it suffices to prove the result in the case where \mathbf{G}_1 and \mathbf{G}_2 are connected.

Let μ and η be the Jordan projections of \mathbf{G}_1 and \mathbf{G}_2 respectively. Notice that, for $i = 1, 2$, since $\mathbf{G}_i \subset \mathrm{SL}_m(\mathbb{R})$, where $m = \max\{m_1, m_2\}$, we may choose

$$\mathfrak{a}_{\mathbf{G}_i}^+ \subset \{(w_1, \dots, w_m) \mid w_1 \geq w_2 \geq \dots \geq w_m, w_1 + \dots + w_m = 0\}.$$

Therefore, the projections onto the first coordinate μ_1 and η_1 are well-defined and surject onto $(0, \infty)$. For $\gamma \in \Gamma$,

$$\mu_1(\rho_1(\gamma)) = \log(\Lambda(\rho_1(\gamma))) \quad \text{and} \quad \eta_1(\rho_2(\gamma)) = \log(\Lambda(\rho_2(\gamma))).$$

Corollary 9.2 then implies that, since $\mathbf{J}(\rho_1, \rho_2) = 1$, there exists $c > 0$ such that

$$c\mu_1(\rho_1(\gamma)) = \eta_1(\rho_2(\gamma))$$

for all $\gamma \in \Gamma$.

Notice that $\mathfrak{a}_{\mathbf{G}_1}^+ \times \mathfrak{a}_{\mathbf{G}_2}^+$ is a Weyl chamber for $\mathbf{G}_1 \times \mathbf{G}_2$ and consider the linear functional

$$\Phi : \mathfrak{a}_{\mathbf{G}_1} \times \mathfrak{a}_{\mathbf{G}_2} \rightarrow \mathbb{R}$$

so that

$$\Phi(v, w) = cw_1 - v_1.$$

Then the limit cone of $(\rho_1 \times \rho_2)(\Gamma)$ is contained in the kernel of Φ , so has empty interior. Theorem 12.6 then implies that $(\rho_1 \times \rho_2)(\Gamma)$ is not Zariski dense in $G_1 \times G_2$, so Proposition 12.5 implies that there exists an isomorphism

$$g : G_1/Z(G_1) \rightarrow G_2/Z(G_2)$$

such that

$$g \circ \bar{\rho}_1 = \bar{\rho}_2.$$

If ρ_1 and ρ_2 are irreducible, then Schur's Lemma implies that $Z(G_1) = \{\pm I\}$ and $Z(G_2) = \{\pm I\}$, so $\bar{\rho}_i = \pi_{m_i} \circ \rho_i$. and the proof is finished. \square

12.3. Rigidity for Hitchin representations. O. Guichard [25] has announced a classification of the Zariski closures of lifts of Hitchin representations.

Theorem 12.7. [GUICHARD] *If $\rho : \pi_1(S) \rightarrow \mathrm{SL}_m(\mathbb{R})$ is the lift of a Hitchin representation and H is the Zariski closure of $\rho(\pi_1(S))$, then*

- *If $m = 2n$ is even, H is conjugate to either $\tau_m(\mathrm{SL}_2(\mathbb{R}))$, $\mathrm{Sp}(2n, \mathbb{R})$ or $\mathrm{SL}_{2n}(\mathbb{R})$.*
- *If $m = 2n + 1$ is odd and $m \neq 7$, then H is conjugate to either $\tau_m(\mathrm{SL}_2(\mathbb{R}))$, $\mathrm{SO}(n, n + 1)$ or $\mathrm{SL}_{2n+1}(\mathbb{R})$.*
- *If $m = 7$, then H is conjugate to either $\tau_7(\mathrm{SL}_2(\mathbb{R}))$, G_2 , $\mathrm{SO}(3, 4)$ or $\mathrm{SL}_7(\mathbb{R})$.*

where $\tau_m : \mathrm{SL}_2(\mathbb{R}) \rightarrow \mathrm{SL}_m(\mathbb{R})$ is the irreducible representation.

Notice in particular, that the Zariski closure of the lift of a Hitchin representation is always simple and connected. We can then apply our rigidity theorem for renormalized intersection to get a rigidity statement which is independent of dimension in the Hitchin setting.

Corollary 12.8. [HITCHIN RIGIDITY] *Let S be a closed, orientable surface and let $\rho_1 \in \mathcal{H}_{m_1}(S)$ and $\rho_2 \in \mathcal{H}_{m_2}(S)$ be two Hitchin representations such that*

$$\mathbf{J}(\rho_1, \rho_2) = 1.$$

Then,

- *either $m_1 = m_2$ and $\rho_1 = \rho_2$ in $\mathcal{H}_{m_1}(S)$,*
- *or there exists an element ρ of the Teichmüller space $\mathcal{T}(S)$ so that $\rho_1 = \tau_{m_1}(\rho)$ and $\rho_2 = \tau_{m_2}(\rho)$.*

Observe that the second case in the corollary only happens if both ρ_1 and ρ_2 are Fuchsian.

Proof. In order to apply our renormalized intersection rigidity theorem, we will need the following analysis of the outer automorphism groups of the Lie algebras of Lie groups which arise as Zariski closures of lifts of

Hitchin representations. This analysis was carried about by Gündoğan [26] (see Corollary 2.15 and its proof).

Theorem 12.9. [GÜNDOĞAN [26]] *Let $\text{Out}(\mathfrak{g})$ be the group of exterior automorphism of the Lie algebra \mathfrak{g} . Then, if $n > 0$,*

- (1) *If $\mathfrak{g} = \mathfrak{sl}_{2n+2}(\mathbb{R})$, then $\text{Out}(\mathfrak{g})$ is isomorphic to $(\mathbb{Z}/2\mathbb{Z})^2$ and is generated by $X \mapsto -X^t$, and conjugation by an element of $\text{GL}_{2n+2}(\mathbb{R})$.*
- (2) *If $\mathfrak{g} = \mathfrak{sl}_{2n+1}(\mathbb{R})$, then $\text{Out}(\mathfrak{g})$ is isomorphic to $\mathbb{Z}/2\mathbb{Z}$ and is generated by $X \mapsto -X^t$.*
- (3) *If $\mathfrak{g} = \mathfrak{so}(n, n+1, \mathbb{R})$, then $\text{Out}(\mathfrak{g})$ is isomorphic to $\mathbb{Z}/2\mathbb{Z}$ and is generated by conjugation by an element of $\text{SL}_{2n+1}(\mathbb{R})$.*
- (4) *If $\mathfrak{g} = \mathfrak{sp}(2n+2, \mathbb{R})$, then $\text{Out}(\mathfrak{g})$ is isomorphic to $\mathbb{Z}/2\mathbb{Z}$ and is generated by conjugation by an element of $\text{GL}_{2n+2}(\mathbb{R})$.*
- (5) *If $\mathfrak{g} = \mathfrak{g}_2$ then $\text{Out}(\mathfrak{g})$ is trivial.*
- (6) *If $\mathfrak{g} = \mathfrak{sl}_2(\mathbb{R})$, then $\text{Out}(\mathfrak{g})$ is isomorphic to $\mathbb{Z}/2\mathbb{Z}$ and is generated by conjugation by an element of $\text{GL}_2(\mathbb{R})$.*
- (7) *If $\mathfrak{g} = \mathfrak{so}(n, 1, \mathbb{R})$, then $\text{Out}(\mathfrak{g})$ is isomorphic to $\mathbb{Z}/2\mathbb{Z}$ and is generated by conjugation by an element of $\text{GL}_{n+1}(\mathbb{R})$.*

Let $\rho_1 : \pi_1(S) \rightarrow \text{PSL}_{m_1}(\mathbb{R})$ and $\rho_2 : \pi_1(S) \rightarrow \text{PSL}_{m_2}(\mathbb{R})$ be two Hitchin representations such that

$$\mathbf{J}(\rho_1, \rho_2) = 1.$$

Let \mathbf{G}_1 and \mathbf{G}_2 be the Zariski closure of the images of ρ_1 and ρ_2 . Theorem 12.7 implies that \mathbf{G}_1 and \mathbf{G}_2 are simple and connected and have center contained in $\{\pm I\}$.

Theorem 12.2 implies that there exists an isomorphism $\sigma : \mathbf{G}_1 \rightarrow \mathbf{G}_2$ such that $\rho_2 = \sigma \circ \rho_1$. If \mathbf{G}_1 is not conjugate to $\tau_{m_1}(\text{SL}_2(\mathbb{R}))$, then it follows from Theorem 12.7, that $m_1 = m_2 = m$, and that, after conjugation of ρ_1 , $\mathbf{G}_1 = \mathbf{G}_2 = \mathbf{H}$ so that σ is an automorphism of \mathbf{H} .

We first observe that, since \mathbf{H} is connected, there is an injective map from $\text{Out}(\mathbf{H})$ to $\text{Out}(\mathfrak{h})$. We now analyze the situation in a case-by-case manner using Gündoğan's Theorem 12.9.

(1) If $\mathbf{H} = \text{PG}_2$, then σ is an inner automorphism, so $\rho_1 = \rho_2$ in $\mathcal{H}_7(S)$.

(2) If $\mathbf{H} = \text{PSO}(n, n+1)$ or $\mathbf{H} = \text{PSp}(2n, \mathbb{R})$, σ is either the identity or the conjugation by an element of $\text{PGL}_{2n+1}(\mathbb{R})$ or $\text{PGL}_{2n}(\mathbb{R})$, so $\rho_1 = \rho_2$ in $\mathcal{H}_{2n+1}(S)$ or $\mathcal{H}_{2n}(S)$.

(3) If $\mathbf{H} = \text{SL}_m(\mathbb{R})$, then, after conjugation of ρ_1 by an element of $\text{PGL}_m(\mathbb{R})$, σ is either trivial or $\rho_2 = \tau \circ \rho_1$ where $\tau(g) = \text{transpose}(g^{-1})$. If σ is non-trivial, then Corollary 9.2 implies that, using the notation

of the proof of Theorem 12.2, there exists $c > 0$ so that

$$c\mu_1(\rho_1(\gamma)) = \mu_1((\rho_2(\gamma))) = -\mu_m(\rho_1(\gamma))$$

for all $\gamma \in \Gamma$. Thus, the limit cone of $\rho_1(\Gamma)$ is contained in the subset of \mathfrak{a}^+ defined by

$$\{u \mid cu_1 = -u_m\},$$

whose interior is empty. However, since $\rho_1(\Gamma)$ is Zariski dense, this contradicts Benoist's Theorem 12.6. Therefore, $\rho_1 = \rho_2$ in $\mathcal{H}_m(S)$ in this case as well.

If G_1 is conjugate to $\tau_{m_1}(\mathrm{SL}_2(\mathbb{R}))$, then G_2 is conjugate to $\tau_{m_2}(\mathrm{SL}_2(\mathbb{R}))$. So, after conjugation, there exist Fuchsian representations, $\eta_1 : \pi_1(S) \rightarrow \mathrm{SL}_2(\mathbb{R})$ and $\eta_2 : \pi_1(S) \rightarrow \mathrm{SL}_2(\mathbb{R})$, such that $\rho_1 = \tau_{m_1} \circ \eta_1$, $\rho_2 = \tau_{m_1} \circ \eta_1$ and there exists an automorphism σ of $\mathrm{SL}(2, \mathbb{R})$ such that $\sigma \circ \eta_1 = \eta_2$. Case (6) of Gündoğan's Theorem then implies that η_1 is conjugate to η_2 by an element of $\mathrm{GL}_2(\mathbb{R})$. Therefore, we are in the second case. This completes the proof. \square

12.4. Convex projective structures. If Γ is a torsion-free hyperbolic group, we say that a representation $\rho : \Gamma \rightarrow \mathrm{PSL}(m, \mathbb{R})$ is a *Benoist representation* if there exists a properly convex subset Ω of $\mathbb{RP}(m)$ such that $\rho(\Gamma)$ acts properly discontinuously and cocompactly on Ω . (Recall that Ω is said to be *properly convex* if any two points in Ω may be joined by a unique projective line in Ω and Ω is disjoint from $\mathbb{P}(V)$ for some hyperplane V .) Benoist [6, Theorem 1.1] proved that, in this case, Ω is strictly convex and $\partial\Omega$ is C^1 . We recall that Ω is strictly convex if $\partial\Omega$ contains no projective line segments. Benoist [6, Theorem 1.1] conversely proved that if Ω is strictly convex and $\Gamma \subset \mathrm{PSL}(m, \mathbb{R})$ acts properly discontinuously and cocompactly on Ω , then Γ is word hyperbolic.

In particular, any Benoist representation is the monodromy of a strictly convex projective structure on a compact manifold. One may define a limit map $\xi : \partial\Gamma \rightarrow \partial\Omega$ and a transverse limit map $\theta : \partial\Gamma \rightarrow \mathbb{RP}(m)^*$, by letting $\theta(x) = T_{\xi(x)}\partial\Omega$. Benoist proved that ρ is irreducible, so we may apply Guichard and Wienhard's Proposition 2.9 to conclude that ρ is convex Anosov.

Benoist [7, Corollary 1.2] (see also Koszul [31]) proved that the set $B_m(\Gamma)$ of Benoist representations of Γ into $\mathrm{PSL}(m, \mathbb{R})$ is a collection of components of $\mathrm{Hom}(\Gamma, \mathrm{PSL}(m, \mathbb{R}))$. Let

$$\mathcal{B}_m(\Gamma) = B_m(\Gamma)/\mathrm{PGL}(m, \mathbb{R}).$$

We call the components of $\mathcal{B}_m(\Gamma)$ *Benoist components*.

Benoist [5, Theorem 1.3] proved that the Zariski closure of any Benoist representation is either $\mathrm{PSL}(m, \mathbb{R})$ or is conjugate to $\mathrm{PSO}(m-1, 1)$. We may thus apply the technique of proof of Theorem 12.8 to prove:

Corollary 12.10. [CONVEX PROJECTIVE RIGIDITY] *If Γ is a torsion-free hyperbolic group, $\rho_1, \rho_2 \in \mathcal{B}_m(\Gamma)$ are Benoist representations and*

$$\mathbf{J}(\rho_1, \rho_2) = 1,$$

then $\rho_1 = \rho_2$ in $\mathcal{B}_m(\Gamma)$.

13. PROOFS OF MAIN RESULTS

In this section, we assemble the proofs of the results claimed in the introduction. Several of the results have already been established.

Theorem 1.1 follows from Corollary 9.2 and Theorem 12.2. Theorem 1.2 is proven in Section 12 as Theorem 12.1, while Corollary 1.5 is proven as Corollary 12.8.

Theorem 1.3 follows from Proposition 9.1 and Corollary 9.2. Theorem 1.10 combines the results of Propositions 5.1 and 6.8.

The proof of Theorem 1.4 is easily assembled.

Proof of Theorem 1.4: Consider the pressure form defined on $\mathcal{C}_g(\Gamma, \mathbb{G})$ as in Definition 9.3. Recall that by Corollary 9.2 the pressure form is non-negative. Moreover, by Corollary 11.2 the pressure form is positive definite, so gives a Riemannian metric. The invariance with respect to $\mathrm{Out}(\Gamma)$ follows directly from the definition.

Proof of Corollary 1.6: Corollary 4.6 implies that every Hitchin component lifts to a component of $\mathcal{C}_g(\pi_1(S), \mathrm{SL}_m(\mathbb{R}))$ which is an analytic manifold. Theorem 1.4 then assures that the pressure form is an analytic Riemannian metric which is invariant under the action of the mapping class group. Entropy is constant on the Fuchsian locus, so if $\rho_1, \rho_2 \in \mathcal{T}(S)$, the renormalized intersection has the form

$$\begin{aligned} \mathbf{J}(\tau_m \circ \rho_1, \tau_m \circ \rho_2) &= \lim_{T \rightarrow \infty} \frac{1}{\#(R_{\tau_m \circ \rho_1}(T))} \sum_{[g] \in R_{\tau_m \circ \rho_1}} \frac{\Lambda_{\tau_m \circ \rho_2}(g)}{\Lambda_{\tau_m \circ \rho_1}(g)} \\ &= \lim_{T \rightarrow \infty} \frac{1}{\#(R_{\rho_1}(T))} \sum_{[g] \in R_{\rho_1}} \frac{\Lambda_{\rho_2}(g)}{\Lambda_{\rho_1}(g)} \end{aligned}$$

Wolpert [56] showed that the Hessian of the final expression, regarded as a function on $\mathcal{T}(S)$, is a multiple of the Weil-Petersson metric (see also Bonahon [11] and McMullen [42, Theorem 1.12]).

Proof of Corollary 1.7: We may assume that Γ is the fundamental group of a compact 3-manifold with non-empty boundary, since otherwise $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ consists of 0 or 2 points.

We recall, from Theorem 4.5, that the deformation space $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is an analytic manifold. Let $\alpha : \mathrm{PSL}_2(\mathbb{C}) \rightarrow \mathrm{SL}_m(\mathbb{R})$ be the Plücker representation given by Proposition 3.2.

If we choose co-prime infinite order elements α and β of Γ , we may define a global analytic lift

$$\omega : \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C})) \rightarrow \mathrm{Hom}(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$$

by choosing $\omega([\rho])$ to be a representative $\rho \in [\rho]$ so that $\rho(\alpha)$ has attracting fixed point 0 and repelling fixed point ∞ and $\rho(\beta)$ has attracting fixed point 1. Then

$$A = \alpha \circ \omega : \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C})) \rightarrow \mathrm{Hom}(\Gamma, \mathrm{SL}_m(\mathbb{R}))$$

is an analytic family of convex Anosov homomorphisms.

We define the entropy h and the renormalised intersection $\bar{\mathbf{J}}$ on $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ by setting

$$h([\rho]) = h(A([\rho])) \quad \text{and} \quad \mathbf{J}([\rho_1], [\rho_2]) = \mathbf{J}(A([\rho_1]), A([\rho_2])).$$

Since ω is analytic, both h and \mathbf{J} vary analytically over $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ and we may again define a non-negative 2-tensor on the tangent space $T\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ which we again call the pressure form, by considering the Hessian of \mathbf{J} .

Let $\mathbf{G} = \alpha(\mathrm{PSL}_2(\mathbb{C}))$. Then \mathbf{G} is a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$. If $\rho(\Gamma)$ is Zariski dense, then $A(\rho)(\Gamma)$ is Zariski dense in \mathbf{G} , so Lemma 2.16 implies that $\rho(\Gamma)$ contains a \mathbf{G} -generic element. Since α is an immersion,

$$\alpha_* : H^1_\rho(\Gamma, \mathfrak{sl}_2(\mathbb{C})) \rightarrow H^1_{\alpha([\rho])}(\Gamma, \mathfrak{g})$$

is injective where \mathfrak{g} is the Lie algebra of \mathbf{G} . Corollary 11.2 then implies that the pressure form on $T_\rho \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is Riemannian if ρ is Zariski dense.

If $\rho = \omega([\rho])$ is not Zariski dense, then its limit set is a subset of $\hat{\mathbb{R}} \subset \hat{\mathbb{C}}$, and the Zariski closure of $\rho(\Gamma)$ is either $H_1 = \mathrm{PSL}(2, \mathbb{R})$ or $H_2 = \mathrm{PSL}(2, \mathbb{R}) \cup (z \rightarrow -z)\mathrm{PSL}(2, \mathbb{R})$. Since each H_i is a real semi-simple Lie group, Proposition 4.2 then implies that the subset of non-Zariski dense representations in $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is an analytic submanifold. We then again apply Corollary 11.2 to see that the restriction of the pressure form to the submanifold of non-Zariski dense representations is Riemannian.

The pressure form determines a path pseudo-metric on the deformation space $\mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$, which is a Riemannian metric off the

analytic submanifold of non-Zariski dense representations and restricts to a Riemannian metric on the submanifold. Lemma 14.1 then implies that the path metric is actually a metric. This establishes the main claim.

Theorem 4.5 implies that if Γ is not either virtually free or virtually a surface group, then every $\rho \in \mathcal{C}_c(\Gamma, \mathrm{PSL}_2(\mathbb{C}))$ is Zariski dense. Auxiliary claim (1) then follows from our main claim.

In the case that Γ is the fundamental group of a closed orientable surface, then the restriction of the pressure metric to the Fuchsian locus is given by the Hessian of the intersection form **I**. It again follows from work of Wolpert [56] that the restriction to the Fuchsian locus is a multiple of the Weil–Petersson metric. This establishes auxiliary claim (2).

Proof of Corollary 1.8: Let $\alpha : \mathbf{G} \rightarrow \mathrm{SL}_m(\mathbb{R})$ be the Plücker representation given by Proposition 3.2. An analytic family $\{\rho_u : \Gamma \rightarrow \mathbf{G}\}_{u \in M}$ of convex cocompact homomorphisms parameterized by an analytic manifold M , gives rise to an analytic family $\{\alpha \circ \rho_u\}_{u \in M}$ of convex Anosov homomorphisms of Γ into $\mathrm{SL}_m(\mathbb{R})$. Theorem 1.3, and Corollary 3.5 then imply that topological entropy varies analytically for this family. Results of Patterson [45], Sullivan [54], Yue [57] and Corlette-Iozzi [17] imply that the topological entropy agrees with the Hausdorff dimension of the limit set, so Corollary 1.8 follows.

Proof of Corollary 1.9: Given a semi-simple real Lie group \mathbf{G} with finite center and a non-degenerate parabolic subgroup \mathbf{P} , let $\alpha : \mathbf{G} \rightarrow \mathrm{SL}_m(\mathbb{R})$ be the Plücker representation given by Proposition 3.2. Then $\mathbf{H} = \alpha(\mathbf{G})$ is a reductive subgroup of $\mathrm{SL}_m(\mathbb{R})$.

We will adapt the notation of Proposition 4.3. Let

$$\widehat{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P}) = \widetilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})/\mathbf{G}_0$$

where \mathbf{G}_0 is the connected component of \mathbf{G} . Then, $\widehat{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$ is a finite analytic manifold cover of the analytic orbifold $\mathcal{Z}(\Gamma; \mathbf{G}, \mathbf{P})$ with covering transformations given by \mathbf{G}/\mathbf{G}_0 , see Proposition 4.4. Since \mathbf{G}^0 acts freely on $\widetilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$, the slice theorem implies that if $[\rho] \in \widehat{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$, then there exists a neighborhood U of $[\rho]$ and a lift

$$\beta : U \rightarrow \widetilde{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P}) \subset \mathrm{Hom}(\Gamma, \mathbf{G}).$$

Then $\omega = \alpha \circ \beta$ is an analytic family of \mathbf{H} -generic convex Anosov homomorphisms parameterized by U . The Hessian of the pull-back of the renormalized intersection gives rise to an analytic 2-tensor, again called the pressure form, on TU . Suppose that $v \in T_z \widetilde{U}$ has pressure norm

zero. Then Corollary 11.2 implies that $D\omega(v)$ is trivial in $H_{\omega(z)}^1(\Gamma, \mathfrak{h})$ where \mathfrak{h} is the Lie algebra of \mathbf{H} . Since α is an immersion,

$$\alpha_* : H_{\beta(z)}^1(\Gamma, \mathfrak{g}) \rightarrow H_{\omega(z)}^1(\Gamma, \mathfrak{h})$$

is an isomorphism. Since β_* identifies $\mathbb{T}_z U$ with $H_{\beta(z)}^1(\Gamma, \mathfrak{g})$ this implies that $v = 0$, so the pressure form on $\mathbb{T}U$ is non-degenerate. Therefore, the pressure form is an analytic Riemannian metric on $\widehat{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$. Since the pressure form is invariant under the action of \mathbf{G}/\mathbf{G}_0 it descends to a Riemannian metric on $\widehat{\mathcal{Z}}(\Gamma; \mathbf{G}, \mathbf{P})$. This completes the proof.

14. APPENDIX

We used the following lemma in the proof of Corollary 1.7.

Lemma 14.1. *Let M be a smooth manifold and let W be a submanifold of M . Suppose that g is a smooth non negative symmetric 2-tensor g such that*

- *g is positive definite on $\mathbb{T}_x M$ if $x \in M \setminus W$,*
- *the restriction of g to $\mathbb{T}_x W$ is positive definite if $x \in W$.*

Then the path pseudo metric defined by g is a metric.

Proof. It clearly suffices to show that if $x \in M$, then there exists an open neighborhood U of M such that the restriction of g to U gives a path metric on U . If $x \in M \setminus W$, then we simply choose a neighborhood U of x contained in $M \setminus W$ and the restriction of g to U is Riemannian, so determines a path metric.

If $x \in W$ we can find a neighborhood U which is identified with a ball B in \mathbb{R}^n so that $W \cap U$ is identified with $B \cap (\mathbb{R}^k \times \{0^{n-k}\})$. Possibly after restricting to a smaller neighborhood, we can assume that there exists $r > 0$ so that if $v \in \mathbb{T}_z B$ and v is tangent to $\mathbb{R}^k \times \{(z_{k+1}, \dots, z_n)\}$, then $g(v, v) \geq r^2 \|v\|^2$, where $\|v\|$ is the Euclidean norm of v . If $z, w \in B$, $z \neq w$ and one of them, say z , is contained in $M \setminus W$, then g is Riemannian in a neighborhood of z , so $d_{U,g}(z, w) > 0$ where $d_{U,g}$ is the path pseudo-metric on U induced by g . If $z, w \in W$, then the estimate above implies that $d_{U,g}(z, w) \geq r d_B(z, w)$ where d_B is the Euclidean metric on B . Therefore, $d_{U,g}$ is a metric on U and we have completed the proof. \square

REFERENCES

- [1] L.M. Abramov, “On the entropy of a flow,” *Dokl. Akad. Nauk. SSSR* **128**(1959), 873–875.
- [2] J.W. Anderson and A. Rocha, “Analyticity of Hausdorff dimension of limit sets of Kleinian groups,” *Ann. Acad. Sci. Fenn.* **22**(1997), 349–364.

- [3] Y. Benoist, “Propriétés asymptotiques des groupes linéaires,” *Geom. Funct. Anal.* **7**(1997), 1–47.
- [4] Y. Benoist, “Propriétés asymptotiques des groupes linéaires II,” *Adv. Stud. Pure Math.* **26**(2000), 33–48.
- [5] Y. Benoist, “Automorphismes des cônes convexes,” *Invent. Math.* **141**(2000) 149–193.
- [6] Y. Benoist, “Convexes divisibles I,” in *Algebraic groups and arithmetic*, Tata Inst. Fund. Res. Stud. Math. **17**(2004), 339–374.
- [7] Y. Benoist, “Convexes divisibles III,” *Ann. Sci. de l’E.N.S.* **38**(2005), 793–832.
- [8] L. Bers, “Spaces of Kleinian groups,” in *Maryland conference in Several Complex Variables I*, Springer-Verlag Lecture Notes in Math, No. 155(1970), 9–34.
- [9] M. Bridgeman, “Hausdorff dimension and the Weil-Petersson extension to quasifuchsian space,” *Geom. and Top.* **14**(2010), 799–831.
- [10] M. Bridgeman and E. Taylor, “An extension of the Weil-Petersson metric to quasi-Fuchsian space,” *Math. Ann.* **341**(2008), 927–943.
- [11] F. Bonahon, “The geometry of Teichmüller space via geodesic currents,” *Invent. Math.* **92**(1988), 139–162.
- [12] R. Bowen, “Periodic orbits of hyperbolic flows,” *Amer. J. Math.* **94**(1972), 1–30.
- [13] R. Bowen, “Symbolic dynamics for hyperbolic flows,” *Amer. J. Math.* **95**(1973), 429–460.
- [14] R. Bowen and D. Ruelle, “The ergodic theory of axiom A flows,” *Invent. Math.* **29**(1975), 181–202.
- [15] C. Champetier, “Petite simplification dans les groupes hyperboliques,” *Ann. Fac. Sci. Toulouse Math.* **3**(1994), 161–221.
- [16] M. Coornaert and A. Papadopoulos, “Symbolic coding for the geodesic flow associated to a word hyperbolic group,” *Manu. Math.* **109**(2002), 465–492.
- [17] K. Corlette and A. Iozzi, “Limit sets of discrete groups of isometries of exotic hyperbolic spaces,” *Trans. A.M.S.* **351**(1999), 1507–1530.
- [18] F. Dal’Bo and I. Kim, “A criterion of conjugacy for Zariski dense subgroups,” *Comptes Rendus Math.* **330** (2000), 647–650.
- [19] T. Delzant, O. Guichard, F. Labourie and S. Mozes, “Displacing representations and orbit maps,” in *Geometry, rigidity and group actions*, Univ. Chicago Press, 2011, 494–514.
- [20] G. Dreyer, “Length functions for Hitchin representations,” preprint, arXiv:1106.6310.
- [21] M. Darvishzadeh and W. Goldman, “Deformation spaces of convex real projective structures and hyperbolic structures,” *J. Kor. Math. Soc.* **33**(1996), 625–639.
- [22] M. Gromov, “Hyperbolic groups,” in *Essays in Group Theory*, MSRI Publ. 8 (1987), 75–263.
- [23] O. Guichard, “Composantes de Hitchin et représentations hyperconvexes de groupes de surface,” *J. Diff. Geom.* **80**(2008), 391–431.
- [24] O. Guichard and A. Wienhard, “Anosov representations: Domains of discontinuity and applications,” *Invent. Math.*, to appear.
- [25] O. Guichard, *oral communication*.

- [26] H. Gündoğan, “The component group of the automorphism group of a simple Lie algebra and the splitting of the corresponding short exact sequence,” *J. Lie Theory* **20**(2010), 709–737.
- [27] M. W. Hirsch, C. C. Pugh and M. Shub, *Invariant manifolds* Lecture Notes in Mathematics, Vol. 583, 1977
- [28] N. Hitchin, “Lie groups and Teichmüller space,” *Topology* **31**(1992), 449–473.
- [29] D. Johnson and J. Millson, “Deformation spaces associated to compact hyperbolic manifolds,” in *Discrete Groups and Geometric Analysis*, Progress in Math., vol. 67(1987), 48–106.
- [30] M. Kapovich, *Hyperbolic manifolds and discrete groups*, Progr. Math. **183**, Birkhäuser, 2001.
- [31] J.L. Koszul, “Déformation des connexions localement plates,” *Ann. Inst. Four.* **18**(1968), 103–114.
- [32] F. Labourie, “Anosov flows, surface groups and curves in projective space,” *Invent. Math.* **165**(2006), 51–114.
- [33] F. Labourie, “Cross Ratios, Surface Groups, $SL_n(\mathbb{R})$ and Diffeomorphisms of the Circle,” *Publ. Math. de l’I.H.E.S.* **106**(2007), 139–213.
- [34] F. Labourie, “Flat projective structures on surfaces and cubic differentials,” *P.A.M.Q.* **3**(2007), 1057–1099.
- [35] F. Labourie, “Cross ratios, Anosov representations and the energy functional on Teichmüller space,” *Ann. Sci. E.N.S.* **41**(2008), 437–469.
- [36] F. Labourie, *Representations of surface groups*, to appear.
- [37] Q. Li, “Teichmüller space is totally geodesic in Goldman space,” preprint, available at: <http://front.math.ucdavis.edu/1301.1442>
- [38] A.N. Livšic, “Cohomology of dynamical systems,” *Math. USSR Izvestija* **6**(1972).
- [39] J. Loftin, “Affine spheres and convex \mathbb{RP}^2 structures,” *Amer. J. Math.* **123**(2001), 255–274.
- [40] A. Lubotzky and A. Magid, *Varieties of representations of finitely generated groups*, *Mem. Amer. Math. Soc.* **58**(1985), no. 336.
- [41] R. Mañé, *Teoria Ergodica*, Projeto Euclides, IMPA.
- [42] C. McMullen, “Thermodynamics, dimension and the Weil-Petersson metric,” *Invent. Math.* **173**(2008), 365–425.
- [43] I. Mineyev, “Flows and joins of metric spaces,” *Geom. Top.* **9**(2005), 403–482.
- [44] W. Parry and M. Pollicott, *Zeta functions and the periodic orbit structure of hyperbolic dynamics*, *Astérisque* **187-188**(1990).
- [45] S. Patterson, “The limit set of a Fuchsian group,” *Acta Math.* **136**(1976), 241–273.
- [46] M. Pollicott and R. Sharp, “Length asymptotics in higher Teichmüller theory,” preprint.
- [47] D. Ragozin, “A normal subgroup of a semisimple Lie group is closed.” *Proc. A.M.S.* **32**(1972), 632–633.
- [48] D. Ruelle, “Repellers for real analytic maps,” *Ergodic Theory Dynamical Systems* **2**(1982), 99–107.
- [49] D. Ruelle, *Thermodynamic Formalism*, Addison-Wesley, London.
- [50] A. Sambarino, *Quelques aspects des représentations linéaires des groupes hyperboliques*, Ph.D. Thesis, Paris Nord, 2011.

- [51] A. Sambarino, “Quantitative properties of convex representations,” *Comm. Math. Helv.*, to appear.
- [52] A. Sambarino, “Hyperconvex representations and exponential growth,” preprint.
- [53] M. Shub, *Global Stability of Dynamical Systems*, Springer-Verlag, 1987.
- [54] D. Sullivan, “The density at infinity of a discrete group of hyperbolic motions,” *Inst. Hautes Études Sci. Publ. Math.* **50**(1979), 171–202.
- [55] S. Tapie, “A variation formula for the topological entropy of convex-cocompact manifolds,” *Erg. Thy. Dynam. Sys.* **31**(2011), 1849–1864.
- [56] S. Wolpert, “Thurston’s Riemannian metric for Teichmüller space,” *J. Diff. Geom.* **23**(1986), 143–174.
- [57] C. Yue, “The ergodic theory of discrete isometry groups on manifolds of variable negative curvature,” *Trans. A.M.S.* **348**(1996), 4965–5005.

BOSTON COLLEGE, CHESTNUT HILL, MA 02467 USA

UNIVERSITY OF MICHIGAN, ANN ARBOR, MI 41809 USA

UNIV. PARIS-SUD, LABORATOIRE DE MATHÉMATIQUES, ORSAY F-91405 CEDEX;
CNRS, ORSAY CEDEX, F-91405 FRANCE

UNIV. PARIS-SUD, LABORATOIRE DE MATHÉMATIQUES, ORSAY F-91405 CEDEX;
CNRS, ORSAY CEDEX, F-91405 FRANCE